

# Load Handling System Symposium (INMARTECH Meeting – October 2006)



## EXPLICIT GOAL

Review of existing technologies and systems to develop a set of standard Functional Requirements (specs) to show “Proof of Concept” for new capabilities.

~ NOT to evaluate any particular vendor~

## Load Handling System Symposium (INMARTECH Meeting – October 2006)

- *Looked at numerous systems, vendors, and vessels both domestically (US) and world-wide.*
- *Talked with vessel operators and technical staff.*
- *Committee combined various features and capabilities into one set of “Functional Requirements”.*
- *Web Site: [www.unols.org](http://www.unols.org) > Committees > RVOC > LHS Symposium.*

## Load Handling System Symposium (INMARTECH Meeting – October 2006)

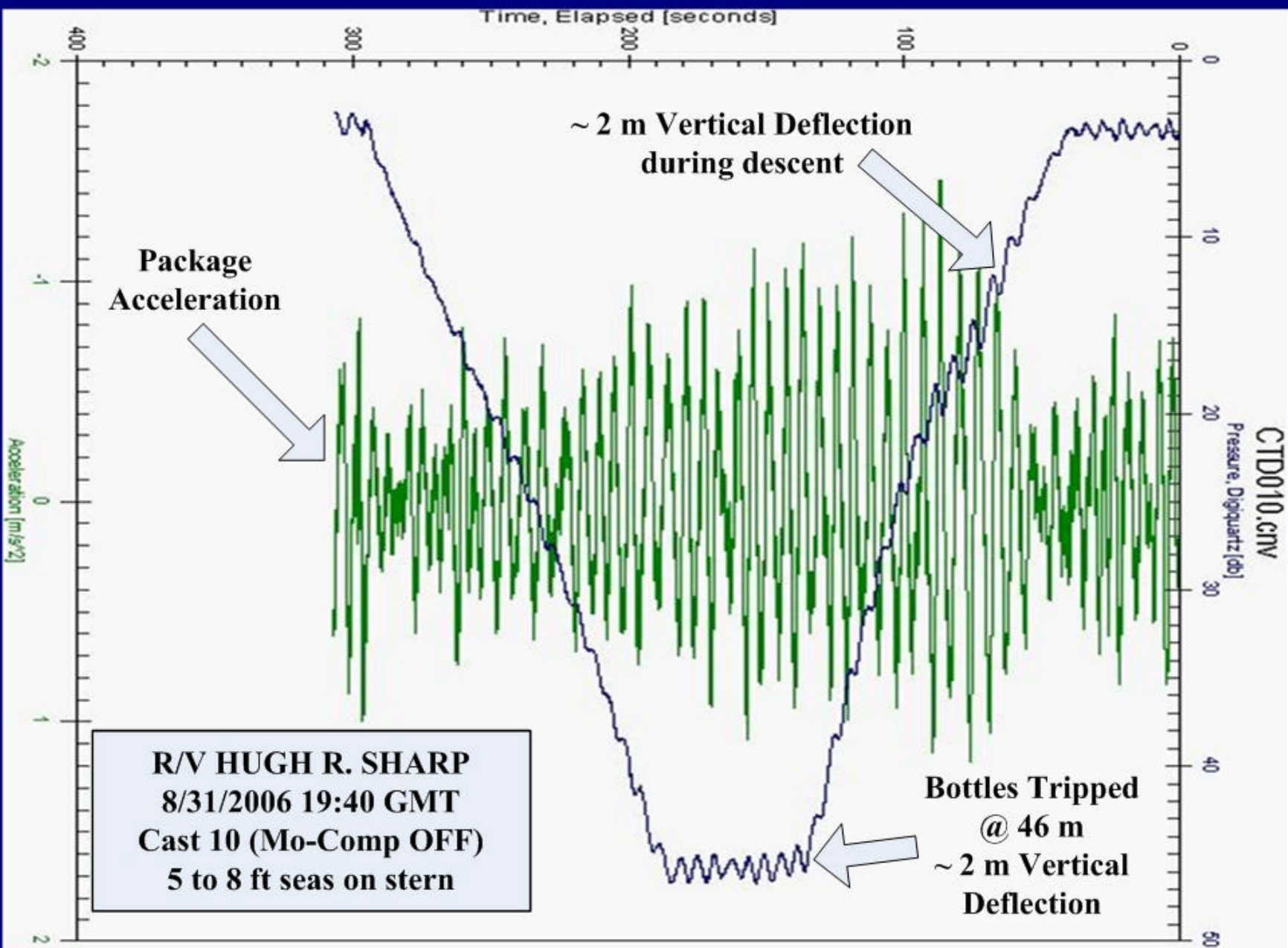
- Two systems produced following “Functional Requirements” developed during the study (*Caley Ocean Systems, Ltd*):
  - *R/V SHARP (Delivered – funded by UD)*
  - *R/V KILO MOANA (In progress)*
- Conceptually the same – different handling appliance and size of winch.
- Final Phase - Field evaluations after installation and systems in operation.

## Load Handling System Symposium (INMARTECH Meeting – October 2006)

### New Capabilities

- Motion Compensation by winch pay-in/pay-out – reduces heave of package in water column for better data resolution and lower cable strain.
- Docking Head with “Auto-Position” capability – no tag lines. Operator can set package on deck without assistance.
- “Tow Mode” (Auto Render) – used for towing and in dealing with wire SWL issues.

Play Movies Here!

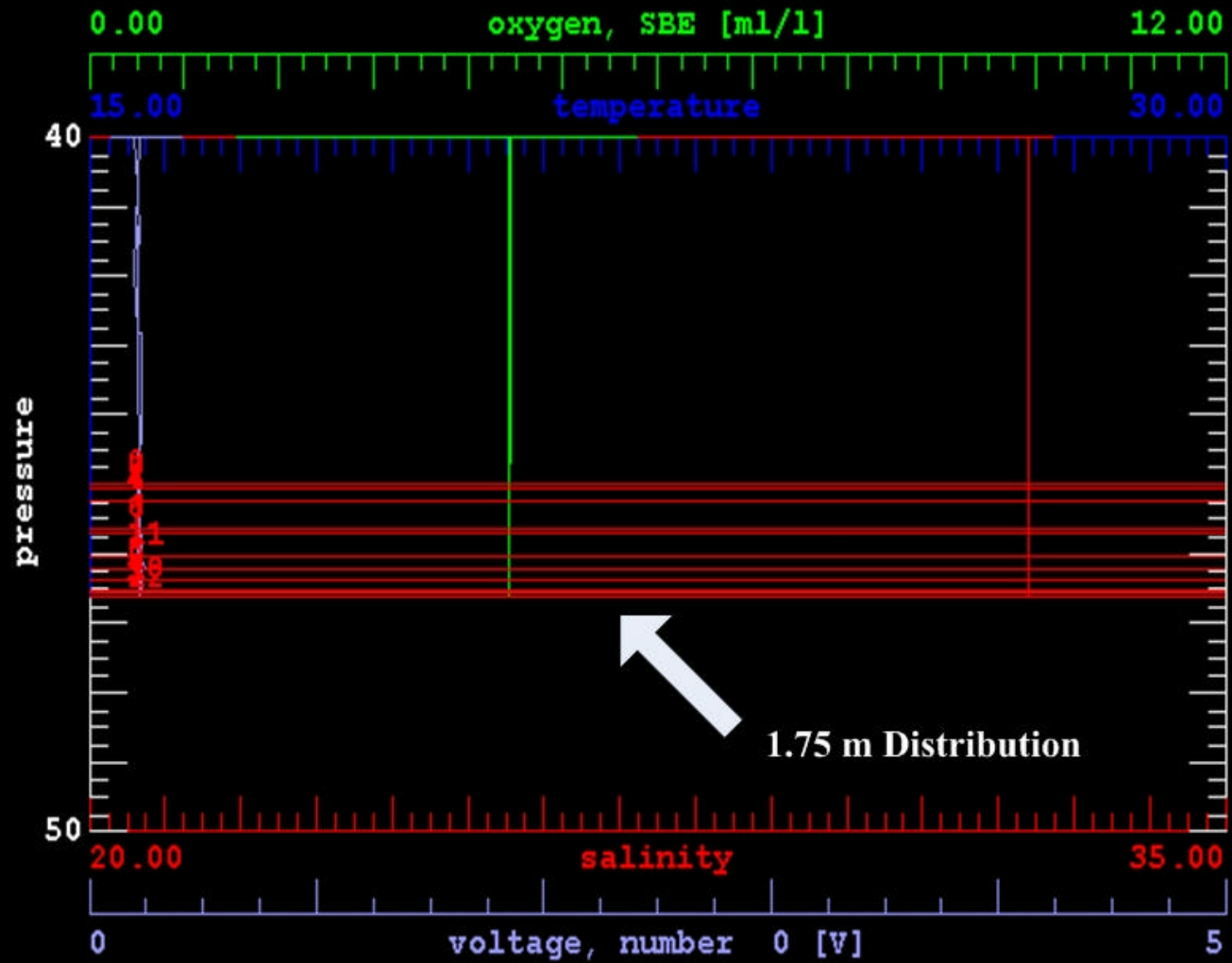


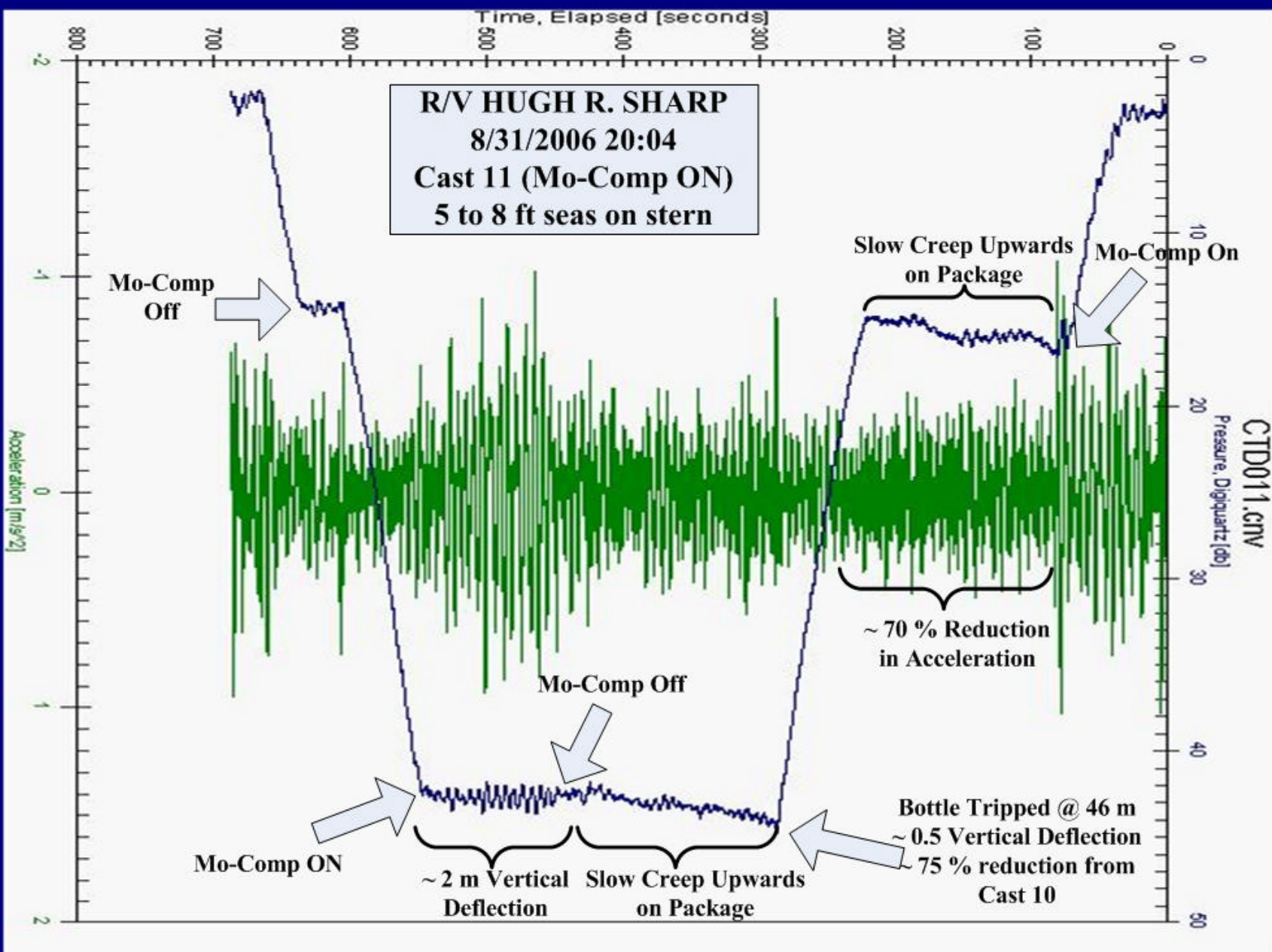
**R/V HUGH R. SHARP**  
**8/31/2006 19:40 GMT**  
**Cast 10 (Mo-Comp OFF)**  
**5 to 8 ft seas on stern**

**~ 2 m Vertical Deflection**  
**during descent**

**Bottles Tripped**  
**@ 46 m**  
**~ 2 m Vertical**  
**Deflection**

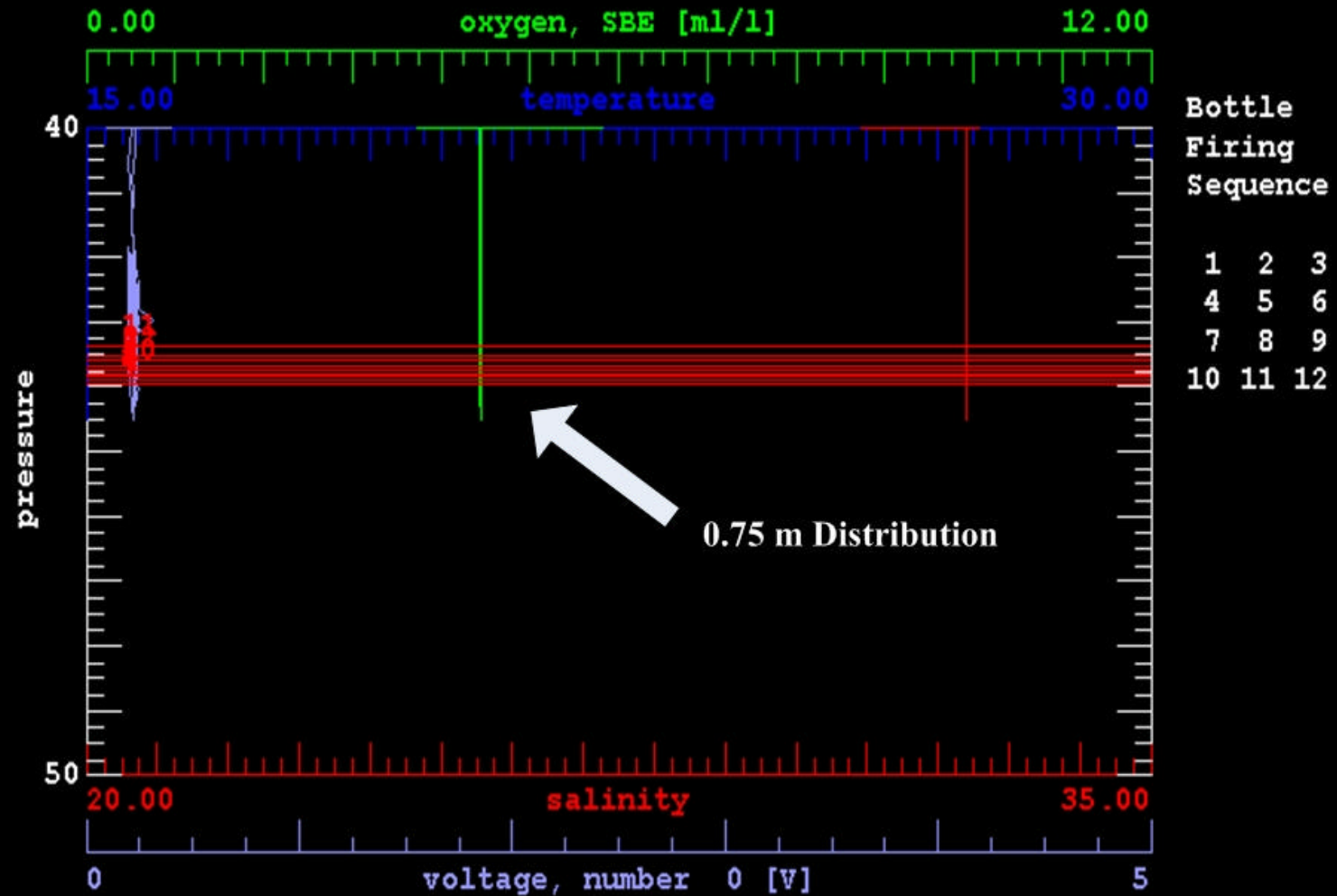
CTD010.dat:







CTD011.dat:



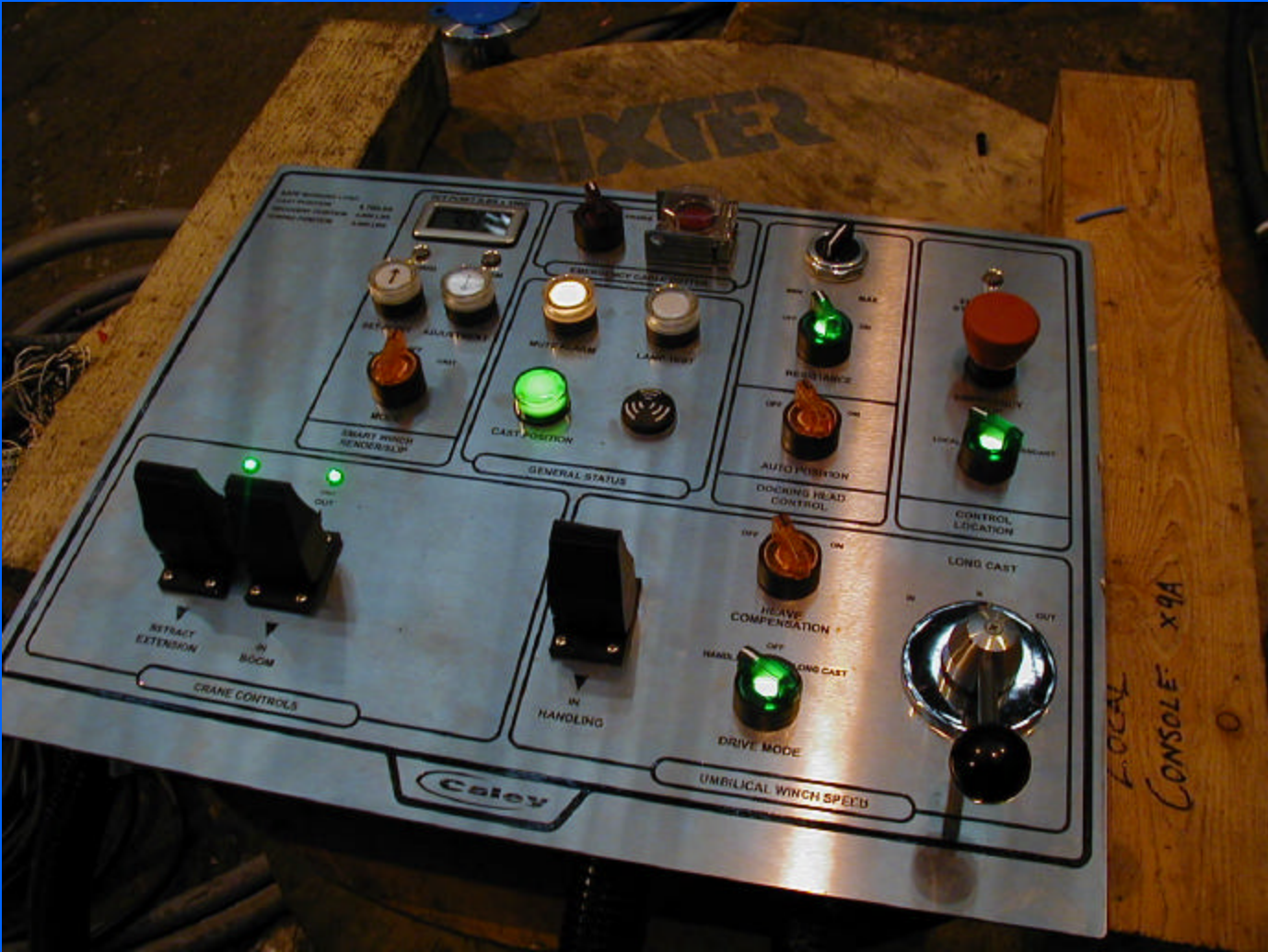
<b>CTD Accelerations</b>					
<b>% Improvement</b>	<b>Maximum</b>	<b>Minimum</b>	<b>Average</b>	<b>*Standard Deviation</b>	
<b>Overall</b>	51.7%	38.4%	76.8%	<b>62.6%</b>	
<b>Descent</b>	60.2%	68.5%	124.5%	<b>77.0%</b>	
<b>At Depth</b>	47.2%	23.1%	205.9%	<b>65.9%</b>	
<b>Ascent</b>	33.8%	39.8%	49.9%	<b>57.6%</b>	
<b>ACCELERATIONS (m/s<sup>2</sup>)</b>	<b>Motion Compensation ON</b>	<b>Maximum</b>	<b>Minimum</b>	<b>Average</b>	<b>Standard Deviation</b>
	Overall	0.5700	-0.9000	-0.0011	0.1549
	Descent	0.4700	-0.4600	0.0053	0.1352
	At Depth	0.5700	-0.9000	-0.0047	0.1690
	Ascent	0.49000	-0.59000	-0.00292	0.15019
	<b>Motion Compensation OFF</b>	<b>Maximum</b>	<b>Minimum</b>	<b>Average</b>	<b>Standard Deviation</b>
	Overall	1.1800	-1.4600	-0.0046	0.4136
	Descent	1.1800	-1.4600	-0.0216	0.5868
	At Depth	1.0800	-1.1700	0.0044	0.4959
	Ascent	0.7400	-0.9800	-0.0058	0.3539
<i>For each cast, depth ≥ 15m</i>					

\*The standard deviation is defined as the average amount by which scores in a distribution differ from the mean, ignoring the sign of the difference.

\*\*Data taken from two back-to-back CTD casts to the same depths. For comparison purposes, only data at or deeper than 15 meters were analyzed

*Thanks to: Tim McGovern, UH*

# Control Panel



## Issues To Be Evaluated

- *Cost* – was it worth it? (\$500 - \$750K)
- *Complexity* – can we handle it? (*no pun intended!*)
- *Motion Compensation* – does it work? Is it of benefit to BOTH vessel and science? Appears so – but:

### **Need tests with greater depth/higher tensions**

- *Docking Head* – Does it work? Is it safer? Appears so.
- “*Tow Mode*” (Auto Render) – Does it work? Is it safer? How do we test? Can it satisfy USCG and ABS? In Progress.
- *ABS Standards* – Comparison with same system under Sub-Chapter U. Weight savings? Greater Operational flexibility?  
In Progress.

Step Forward?

Time will tell . . .

## Final Word (Related Subject)

- DRAFT UNOLS Wire Safe Working Load (SWL) standards currently under review by RVOC Safety Committee.
- Reviewed by RVTECH on October 16th
- Eventual Inclusion in RVSS
- Submission to ABS and US Coast Guard?