

R/V Kilo Moana

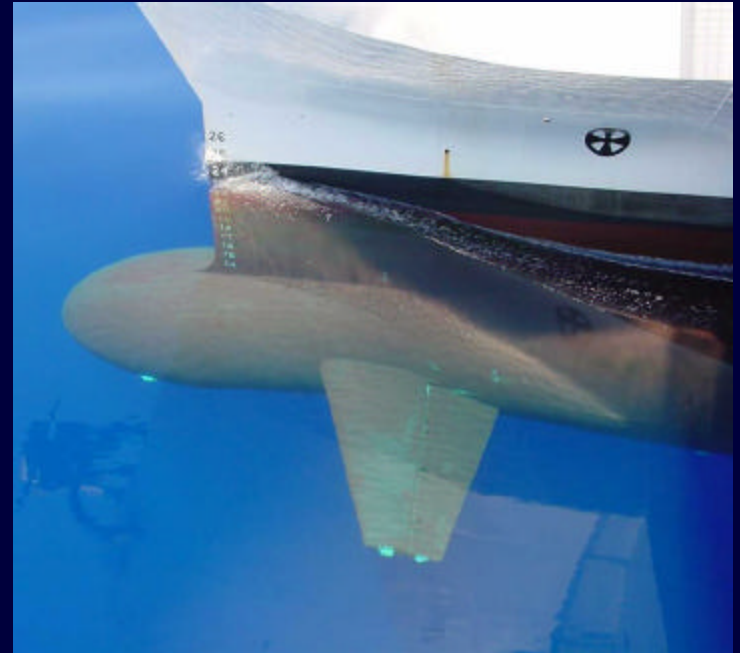
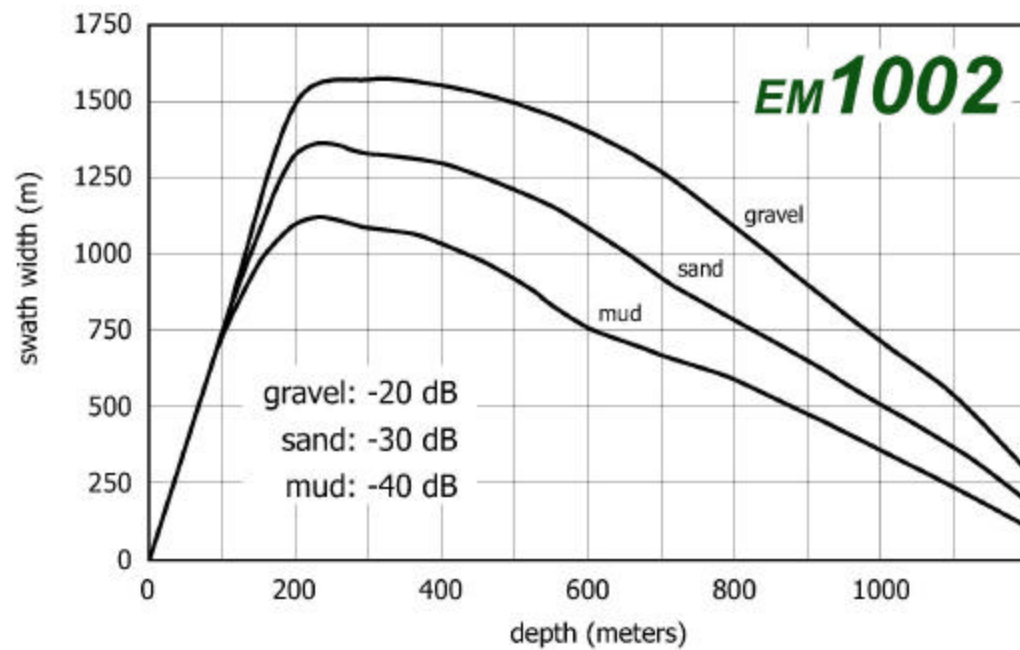
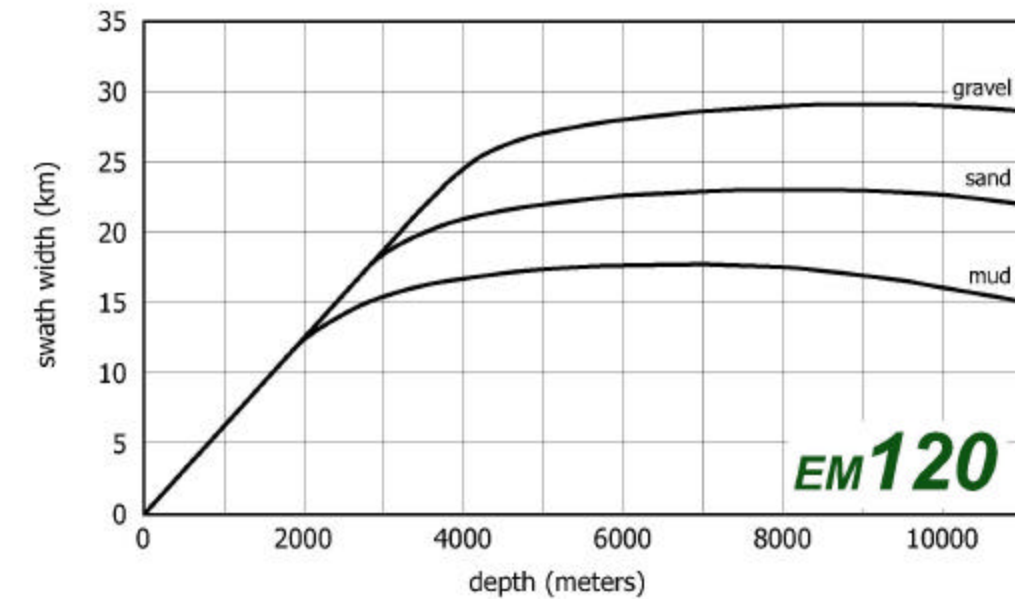
Real-Time Multibeam Mosaic Display System

Bruce Appelgate &
Roger Davis
University of Hawaii



Dual multibeam

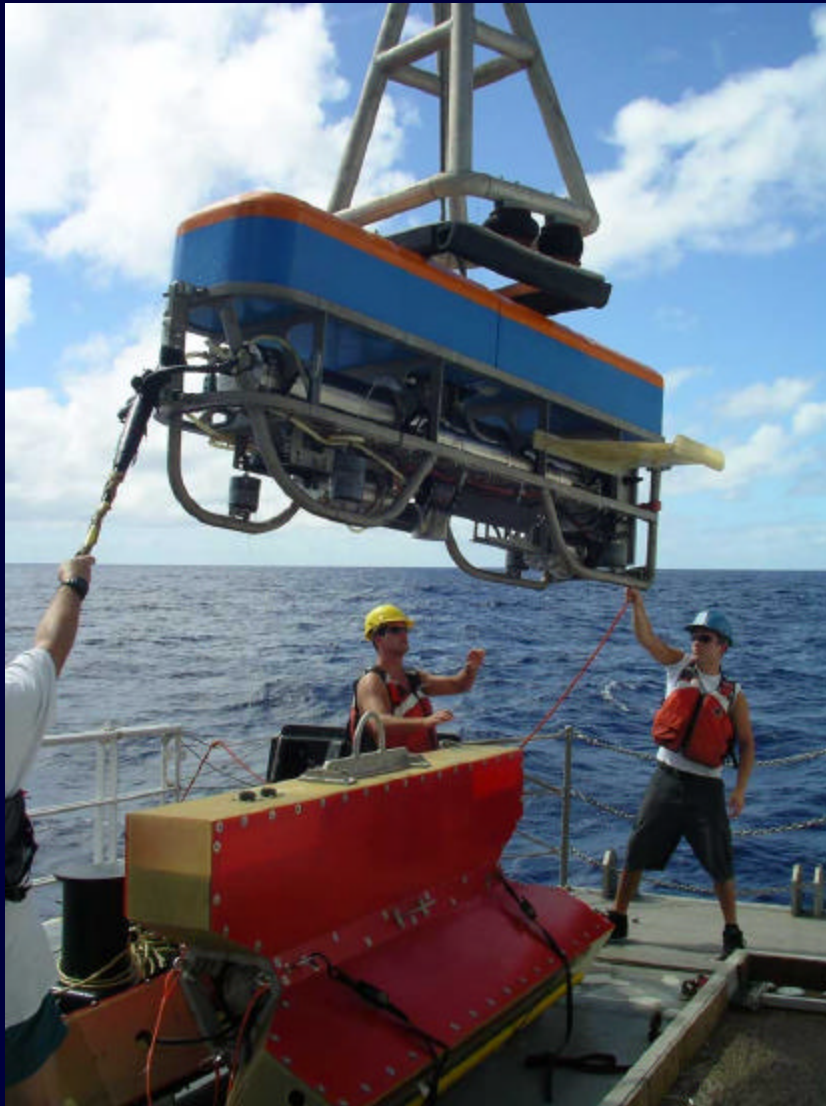
- em1002 (~95 kHz, 0-800 m)
- em120 (~12 kHz, 500+ m)
- 150° swath, weather-tolerant



Multibeam acquisition

Using acquisition workstations for survey display & planning: not good





DSL-120A & IMI-30
aboard *Kilo Moana* April, 2004

HMRG Software

Created for towed SSBS sonars

SeaMARC II, HAWAII MR1, SEAMAP, DSL-120A, IMI-30, IMI-12

Processing and charting software
for bathymetry and sidescan data



HMRG Software

Modified to process hull-mounted
multibeam imagery

Simrad em120, em1002, em300, em3000, Reson
8101, Sea Beam 2000, 2112

AHI



Melville



Healy



Knorr



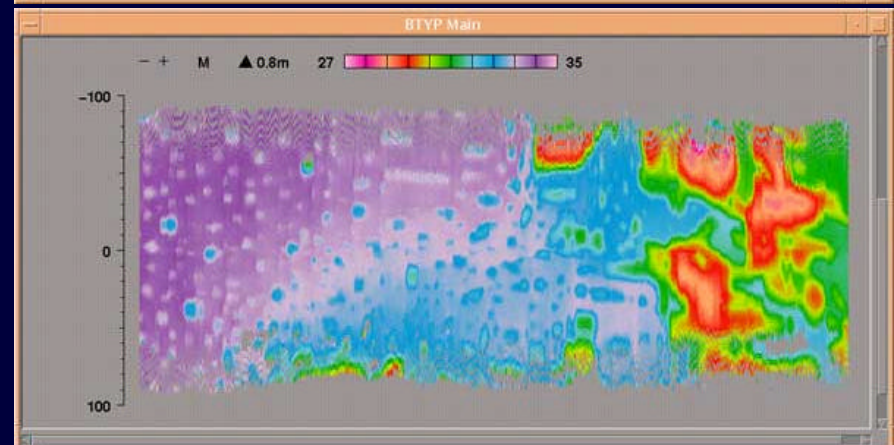
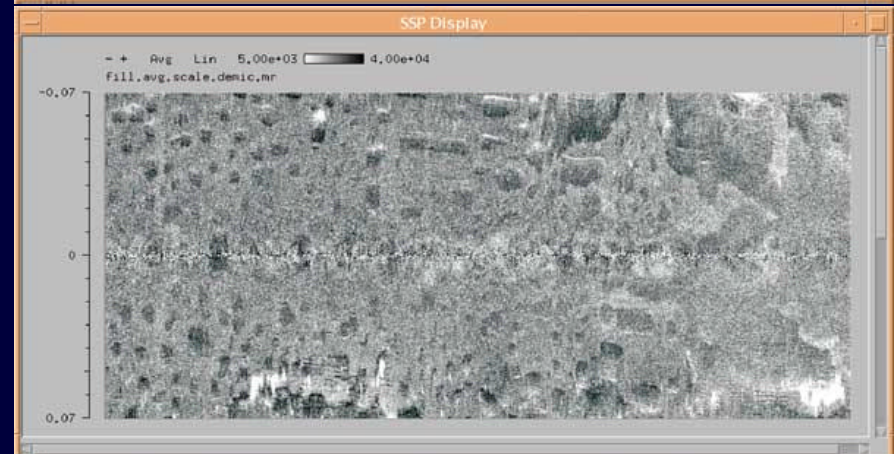
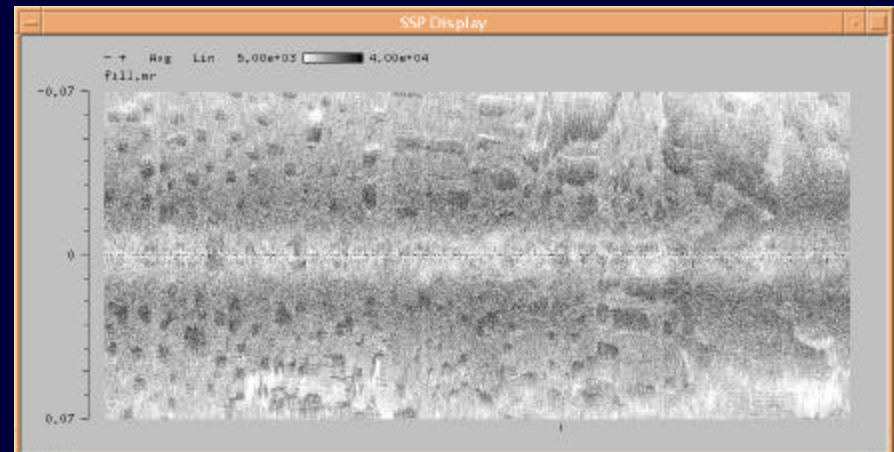
Thompson



Atlantis



Hi'ialakai



Initial Goal

- To view chart-like display of multibeam bathymetry and backscatter in real time, separate from acquisition system.

Mission Creep

- Do all kinds of stuff programmer didn't initially agree to: pan, zoom, change color lookup tables, flip grayscale polarity, autoscroll, survey planning.

Future Plans

- More robust survey planning (waypoint export/import)
- Helm display for better communication with bridge

Conclusion

It works.

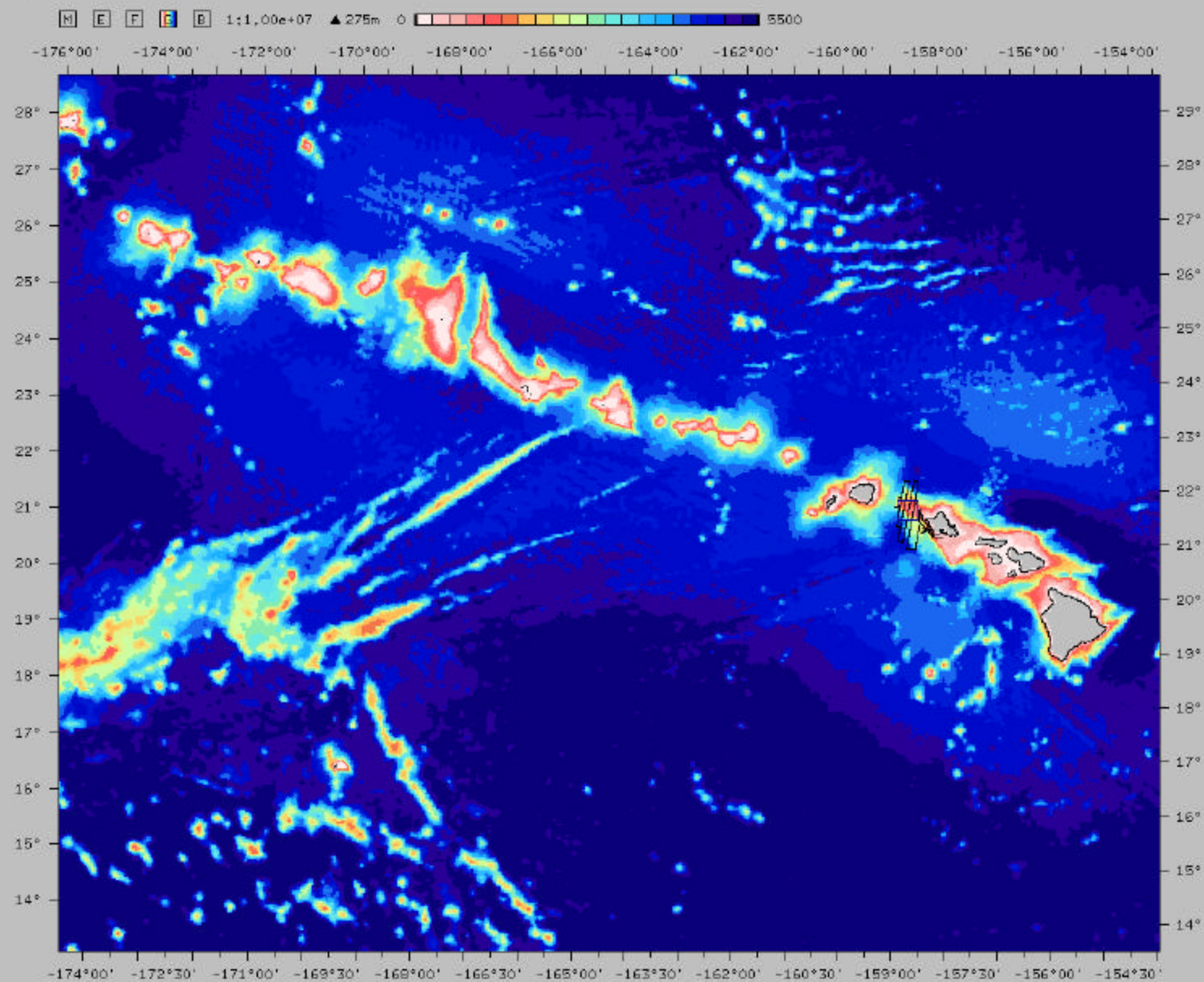


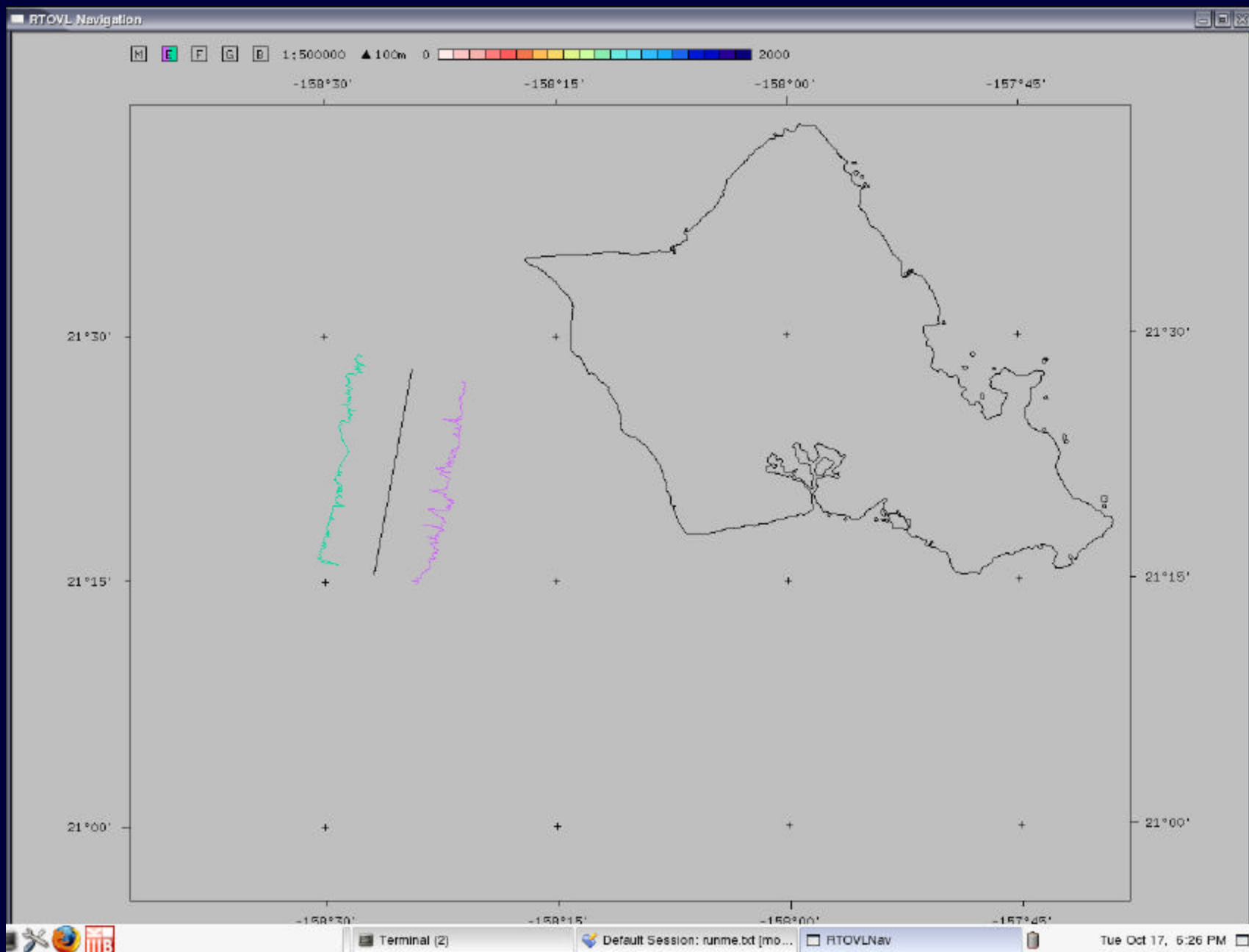
How it works

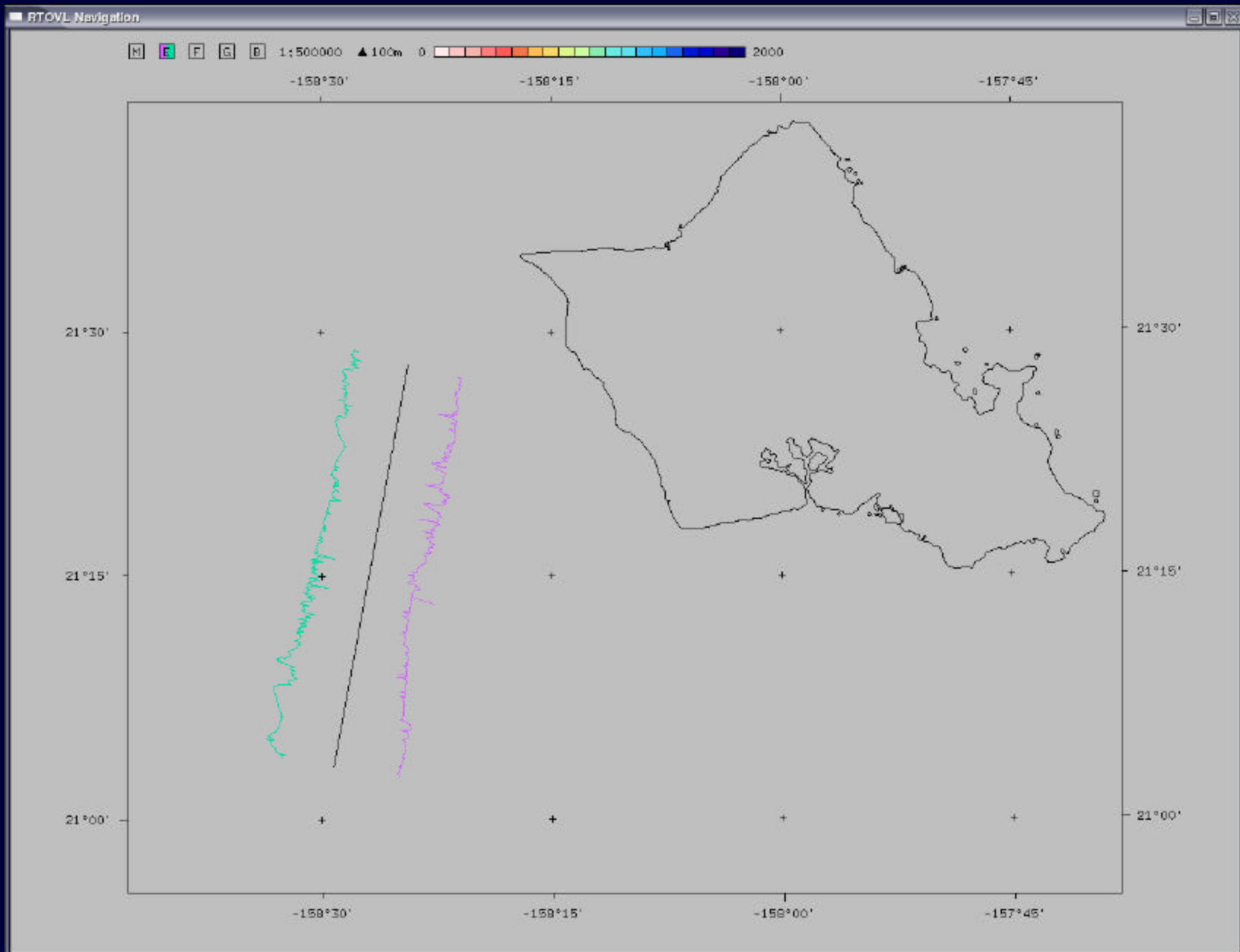
- Raw data acquired & logged normally
- Data periodically transferred to mosaic computer
- Bathymetry & backscatter are gridded at 3 resolutions
- Gridded data are incorporated into mosaic display
- Based on existing HMRG software for bathy/sidescan processing and mosaic display
- Because the mosaic display is separate from the data acquisition system, if bad things* happen to the mosaic display, data acquisition is not adversely affected.

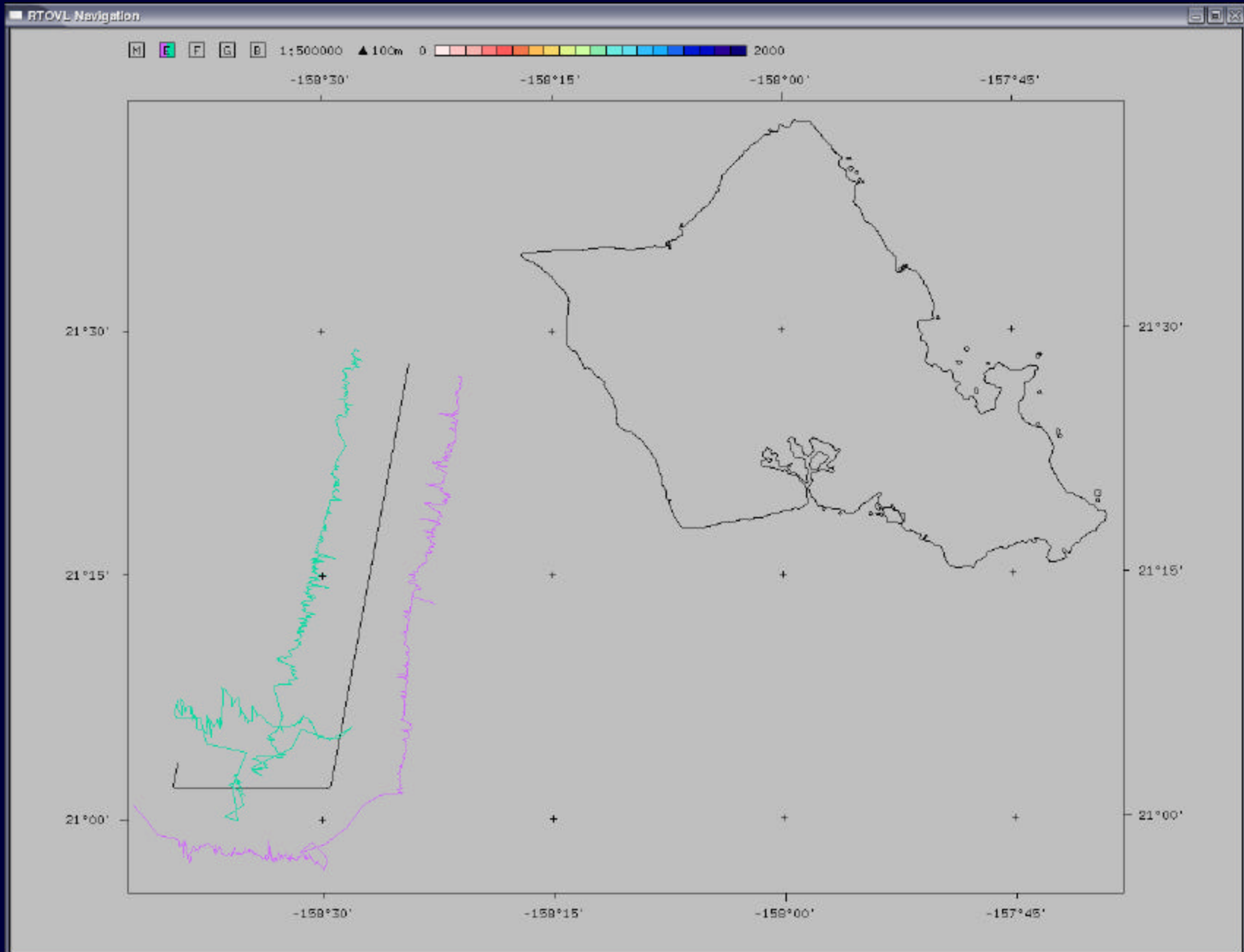
* bad things never happen

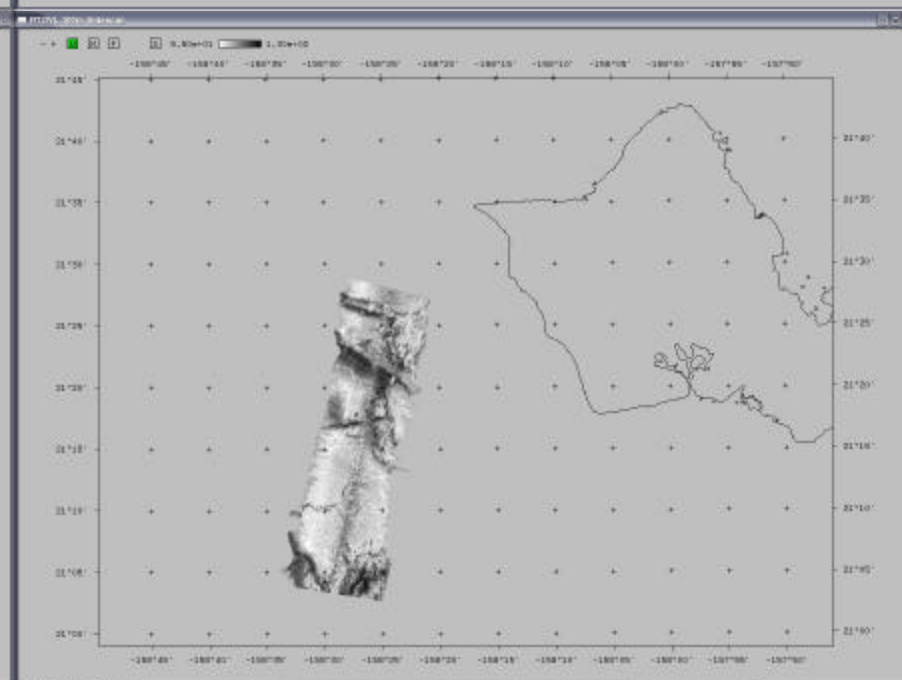
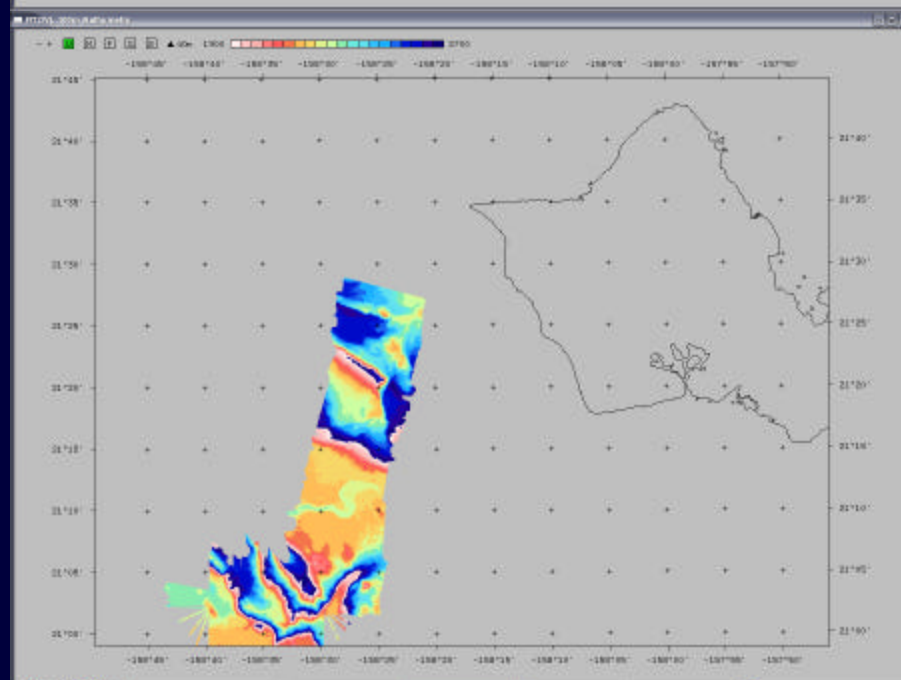
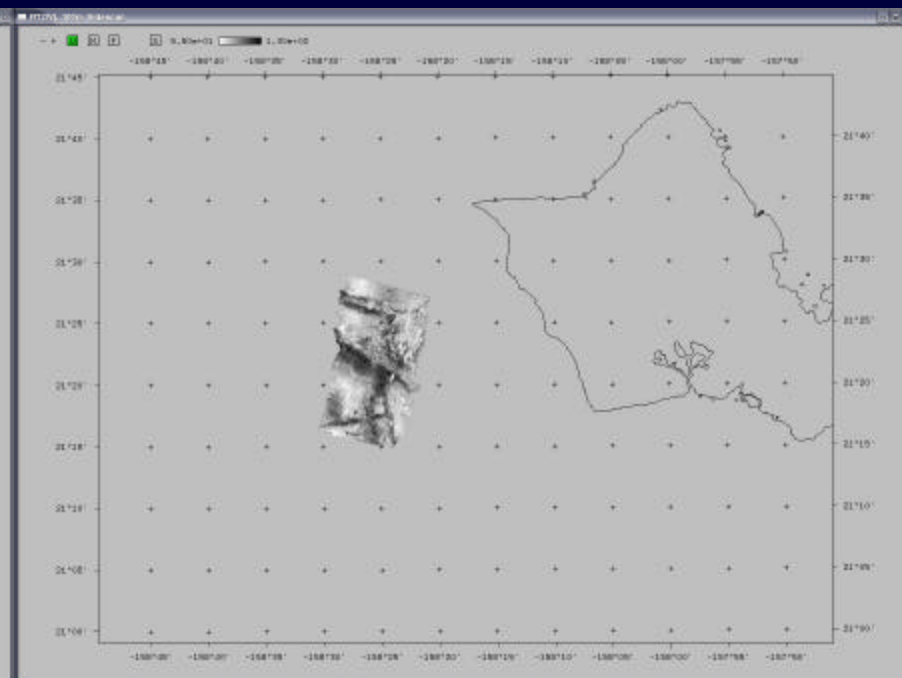
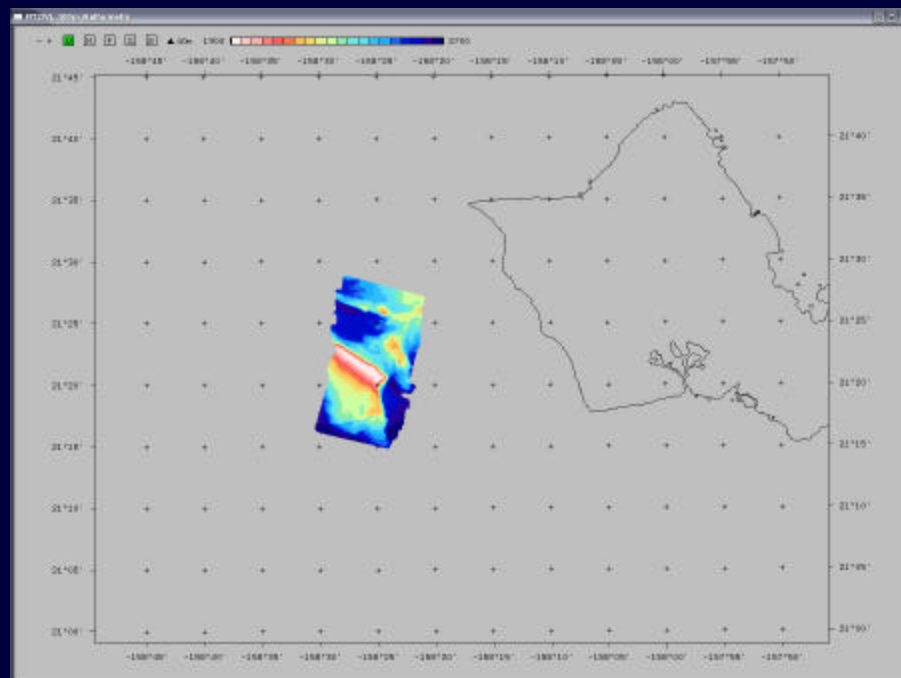
RTOVL Navigation











RTOVL View Display Attributes

Data Type ☒ Bathymetry ☐ Sidescan

Contour Start Depth

Contour Depth Increment

Depth: Increment:

Palette

Contour Wrap

Contour Transition Mode

Mosaic Pixel Width: Mosaic Pixel Height:

Resolution ☒ Low ☐ Medium ☐ High

File Boundary Display

Continuous Update

Autotracking

Center Longitude: Center Latitude:

Frame Longitude Tick Interval: Frame Latitude Tick Interval:

Frame Tick Precision:

Grid Tick Display

Grid Longitude Tick Interval: Grid Latitude Tick Interval:

Coastline Display

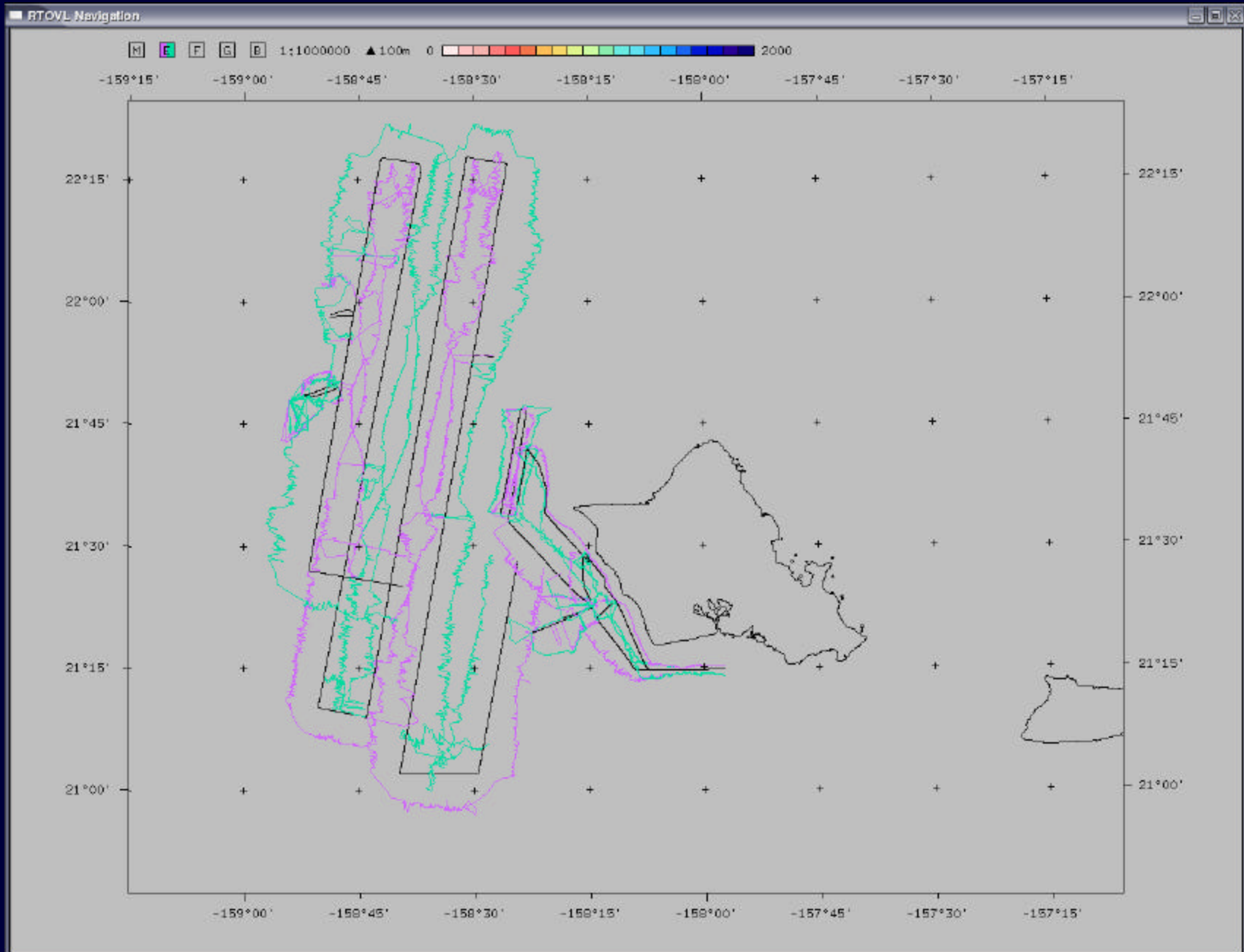
Background Grid Display

BG Bathymetry X Offset: BG Bathymetry Y Offset:

Plan Display

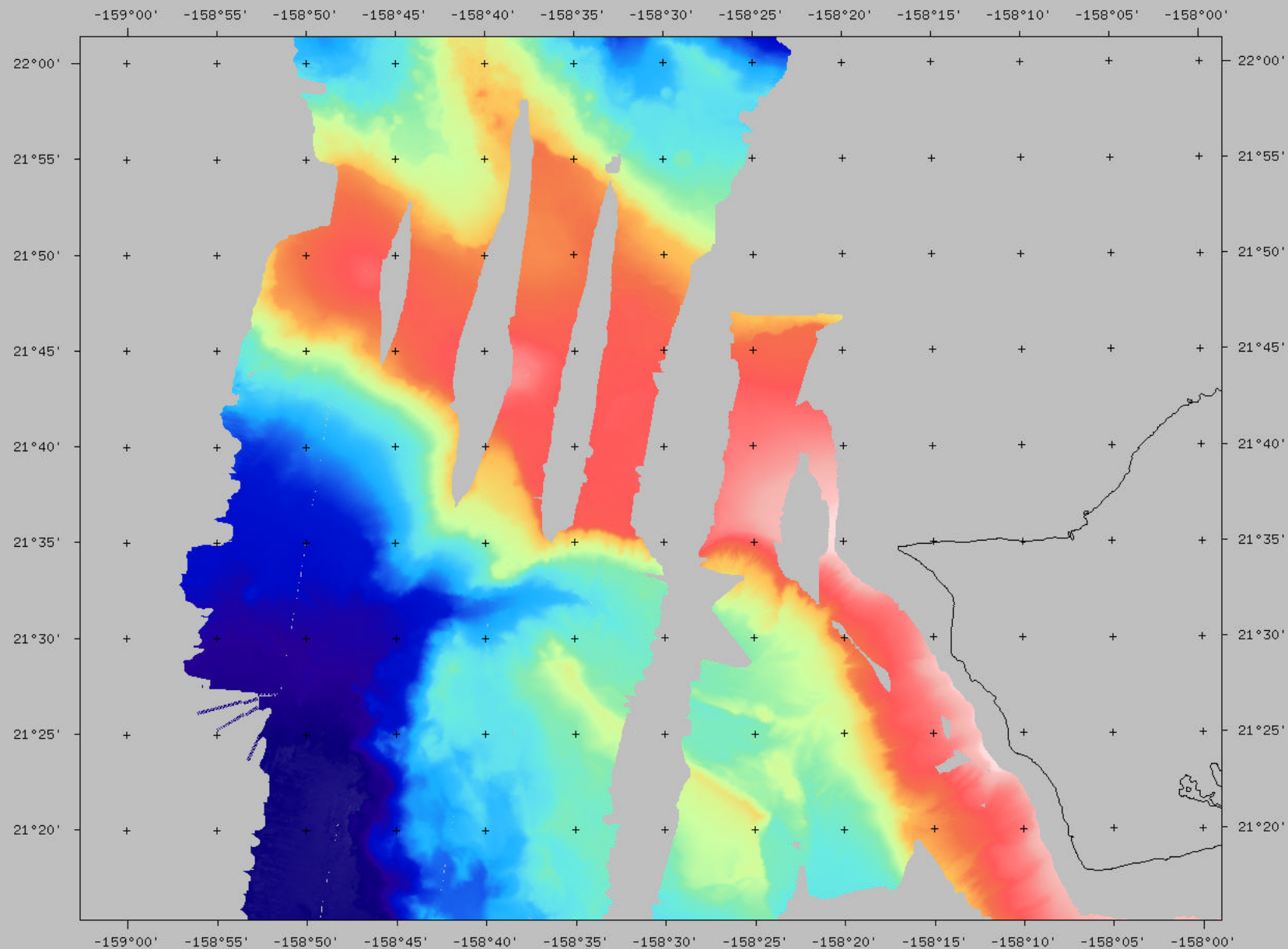
Suppressed Section Selectability ☒ Edit/Display ☐ All Operations

Apply **Cancel**



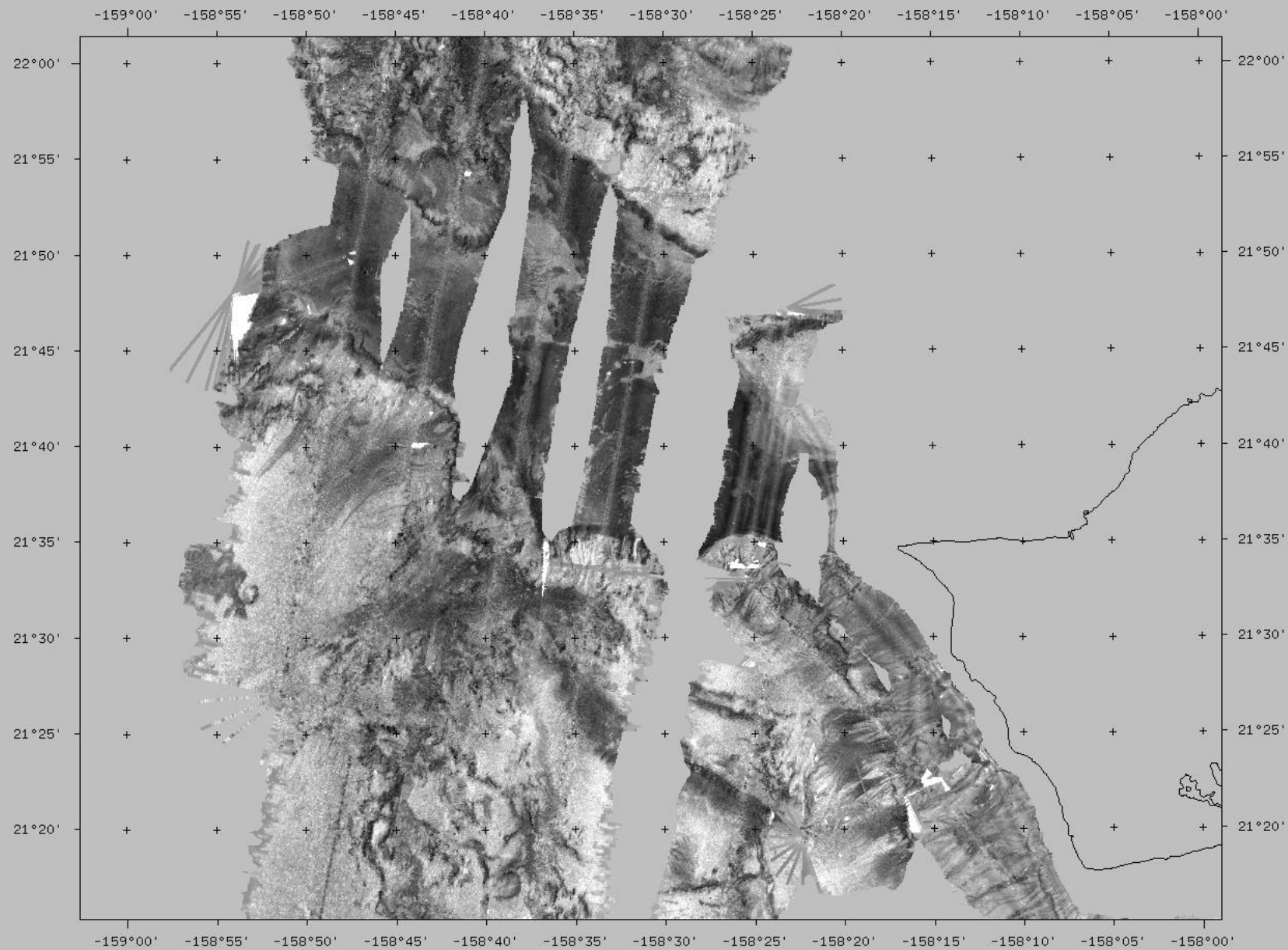
RTOVL 100m Bathymetry

- +      ▲ 250m 0  5000



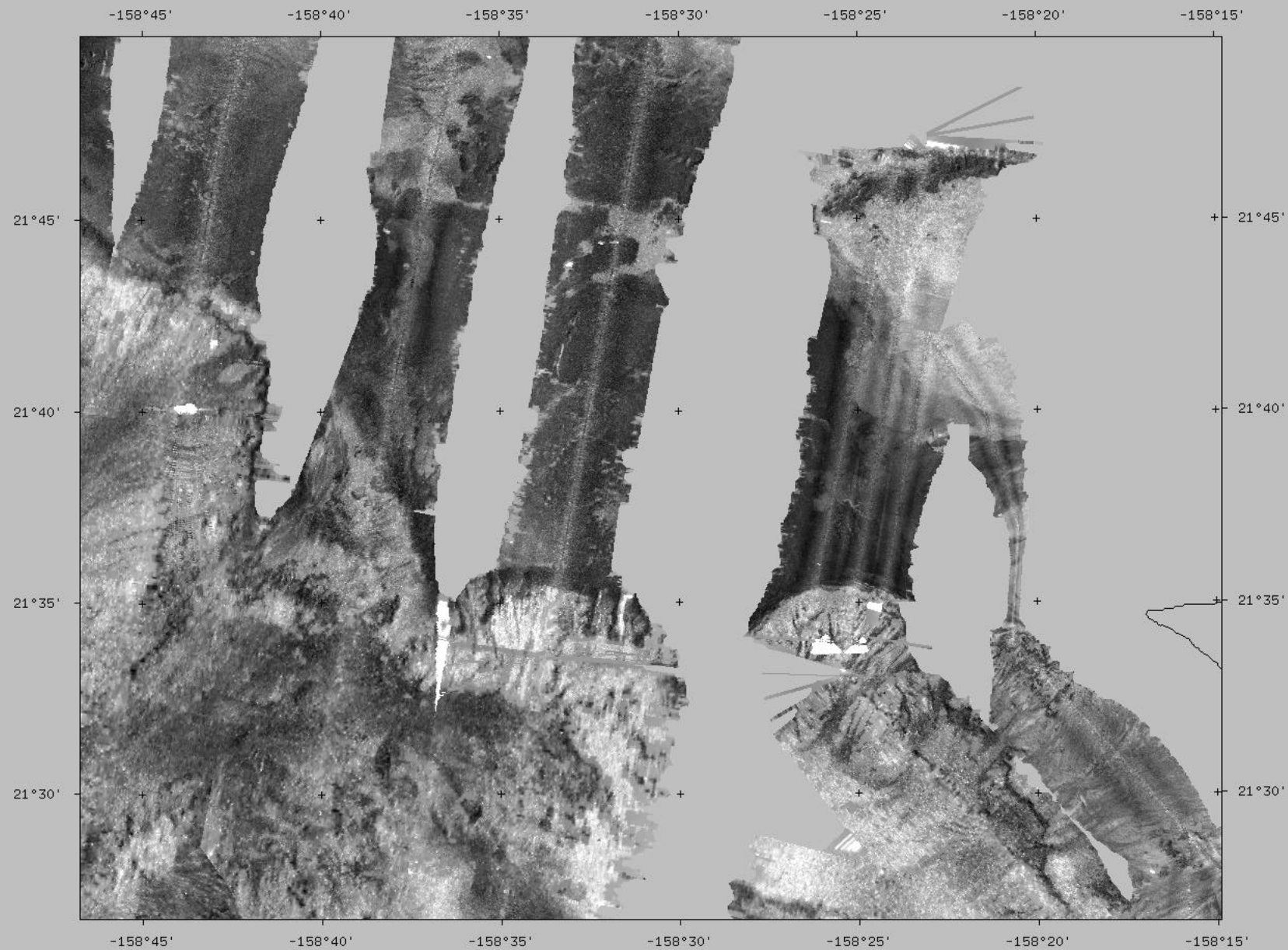
RTOVL 100m Sidescan

- +     5.50e+01  1.40e+02



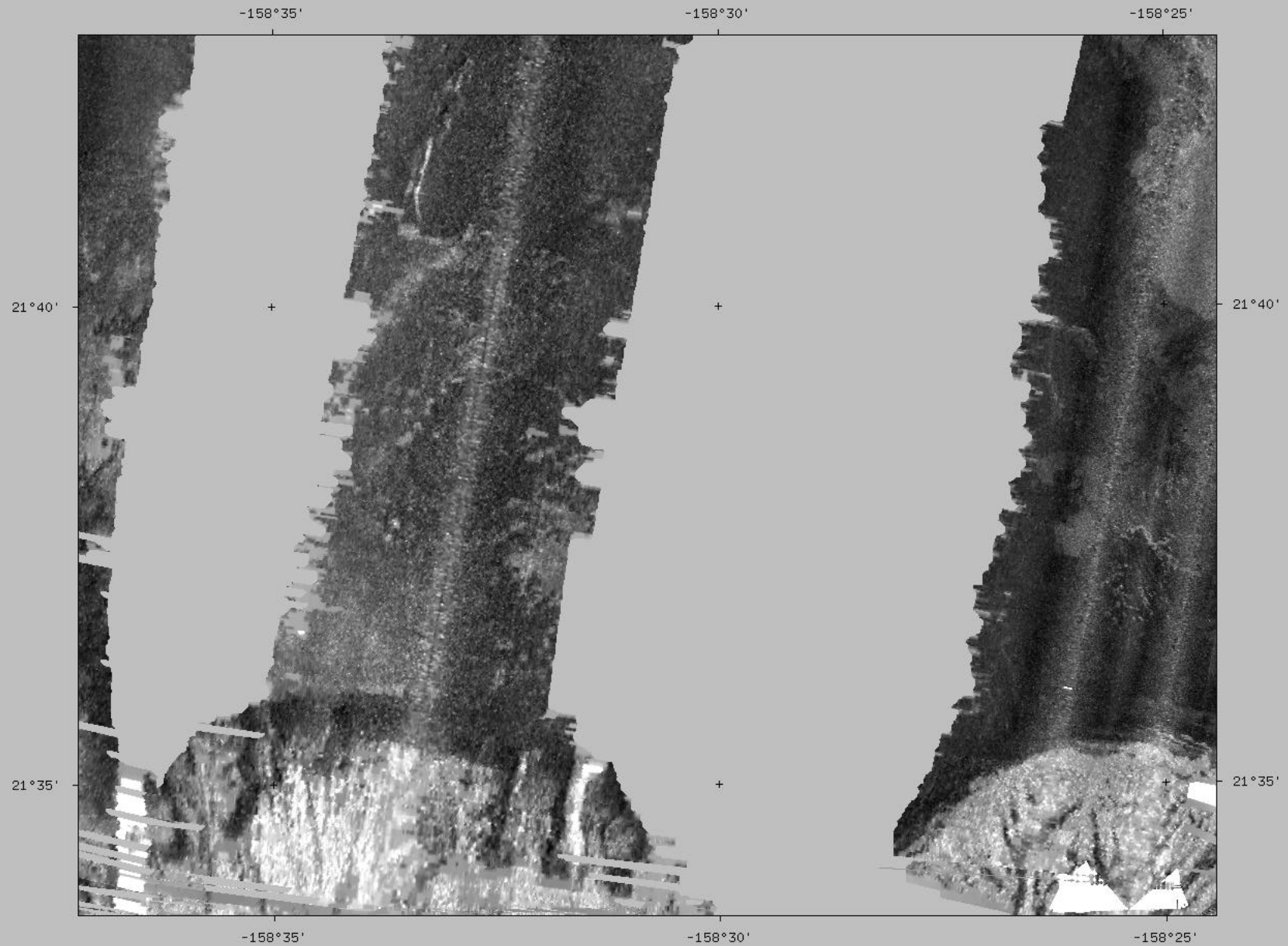
RTOVL 50m Sidescan

- +     5,50e+01  1,40e+02



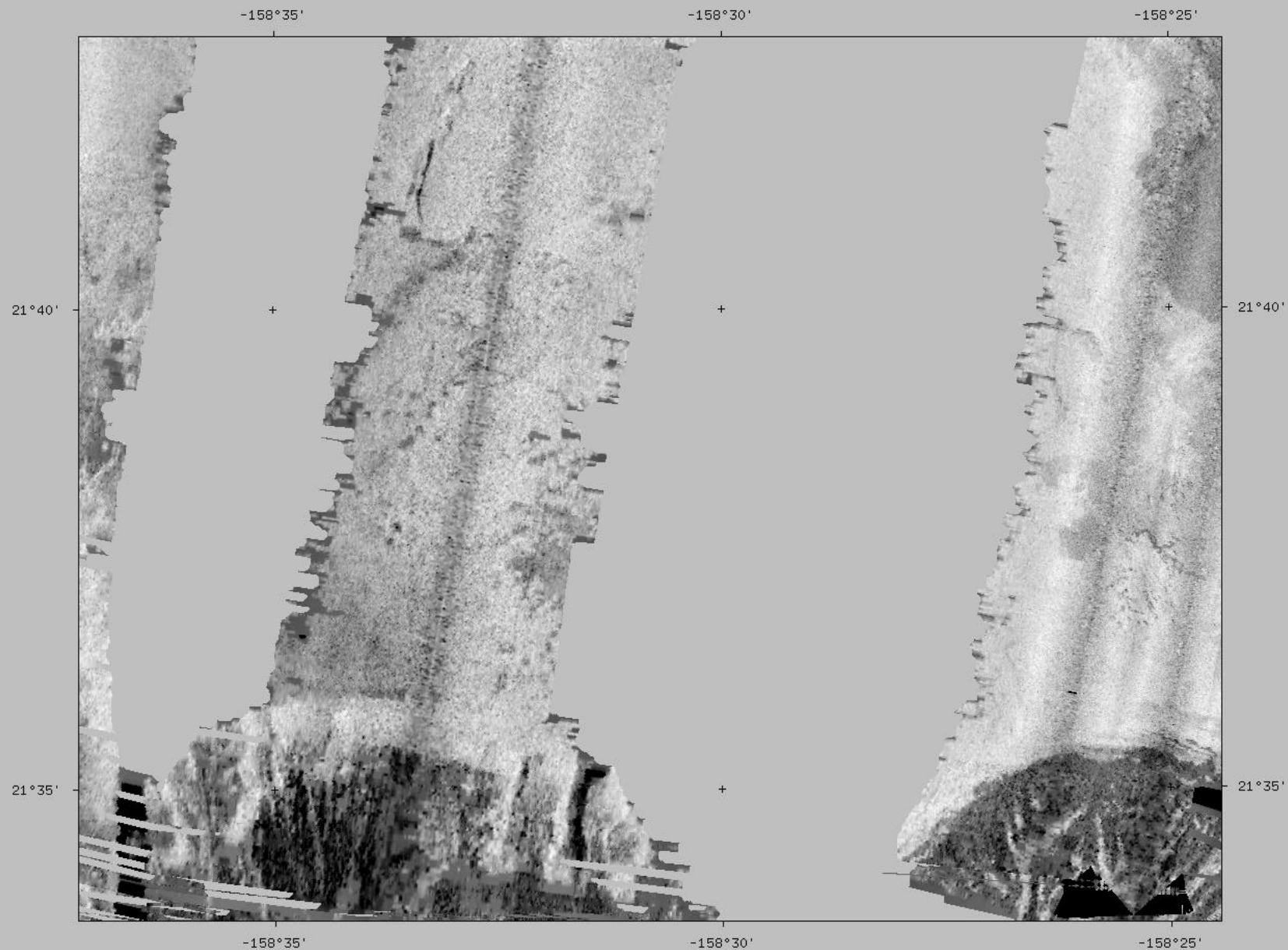
RTOVL 20m Sidescan

- +     5,50e+01  1,40e+02



RTOVL 20m Sidescan

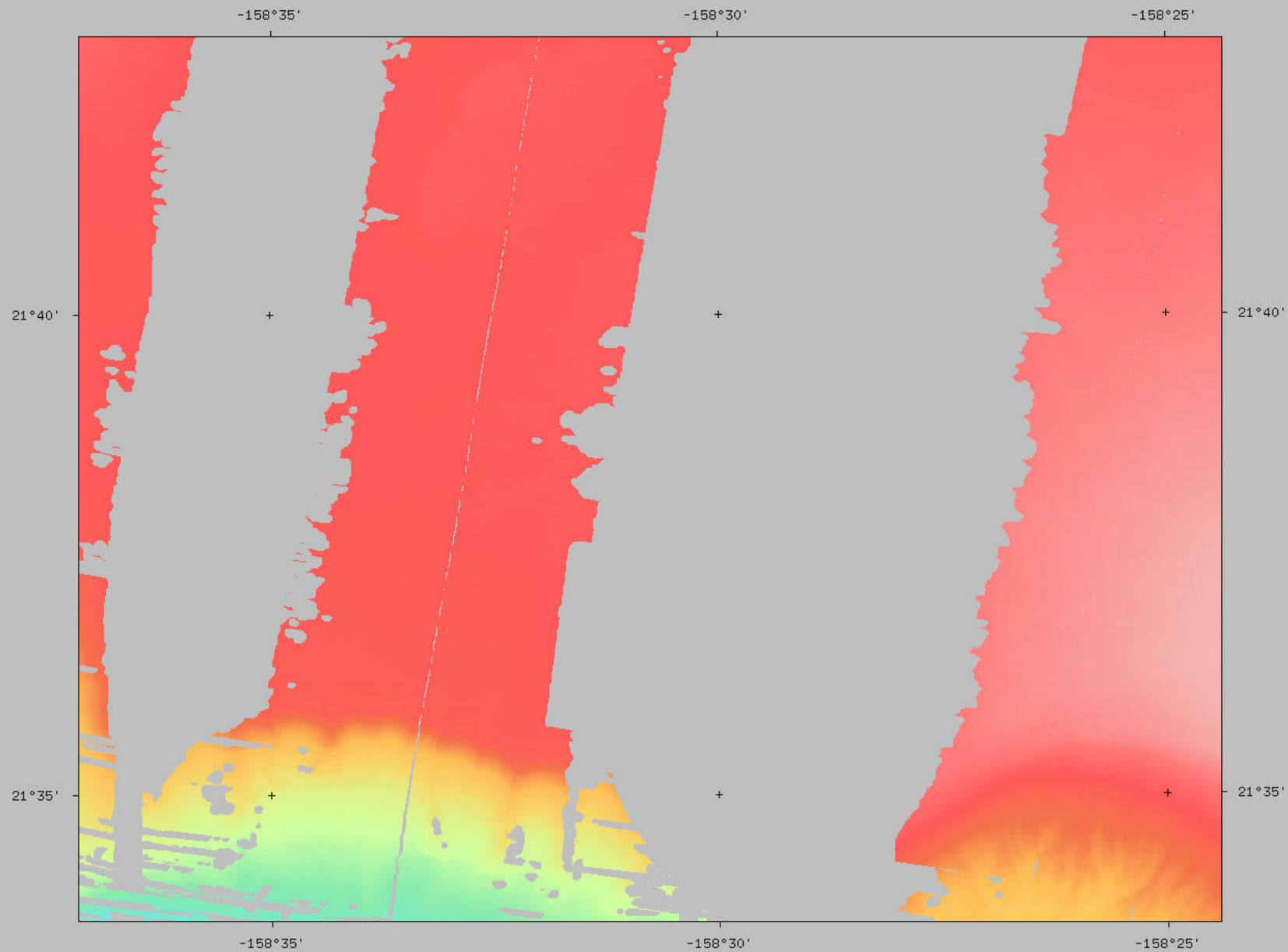
- +     5,50e+01  1,40e+02



[-158°28,555', 21°40,455', --]

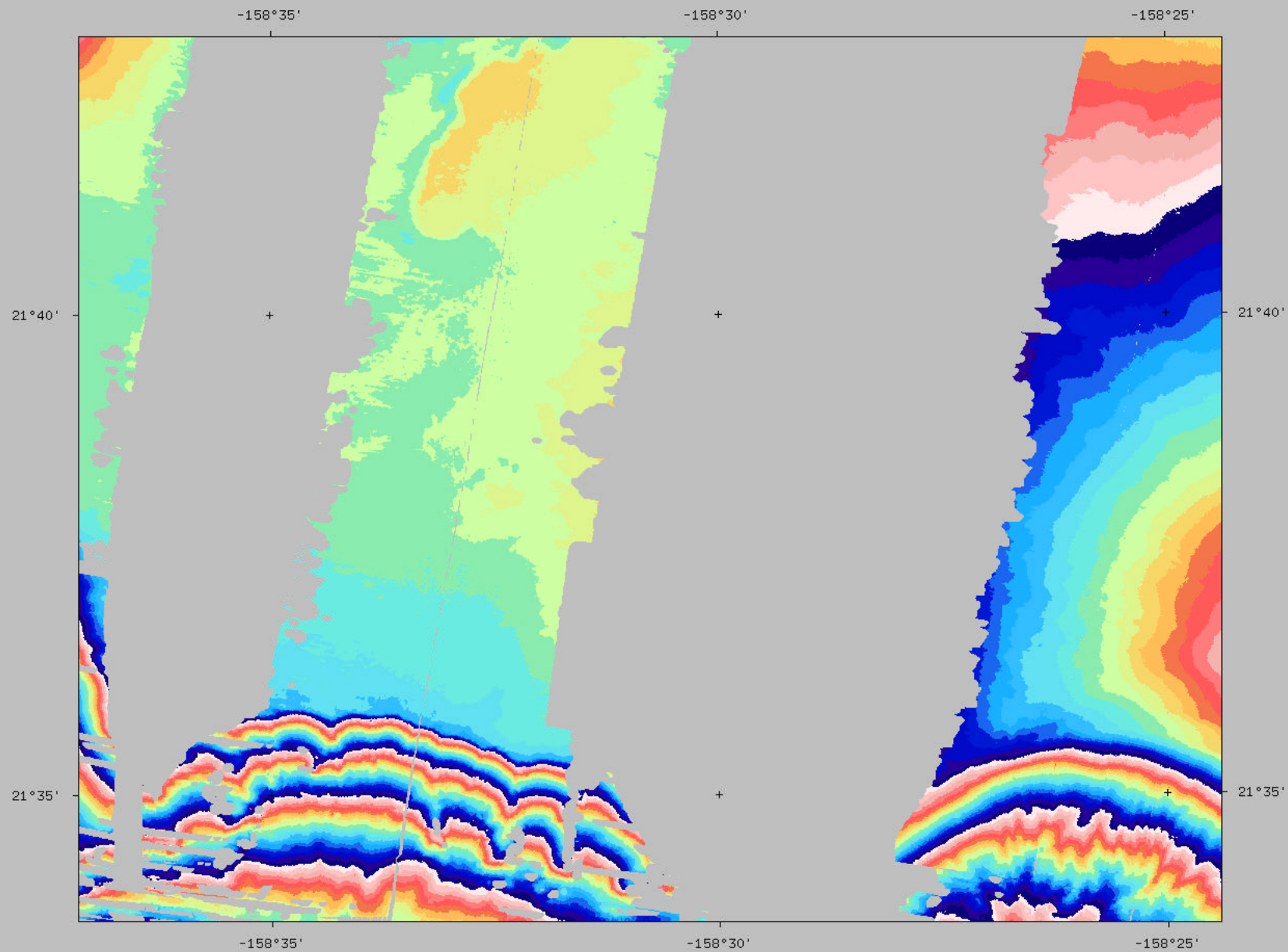
RTOVL 20m Bathymetry

- +      ▲ 250m 0  5000






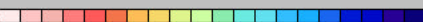


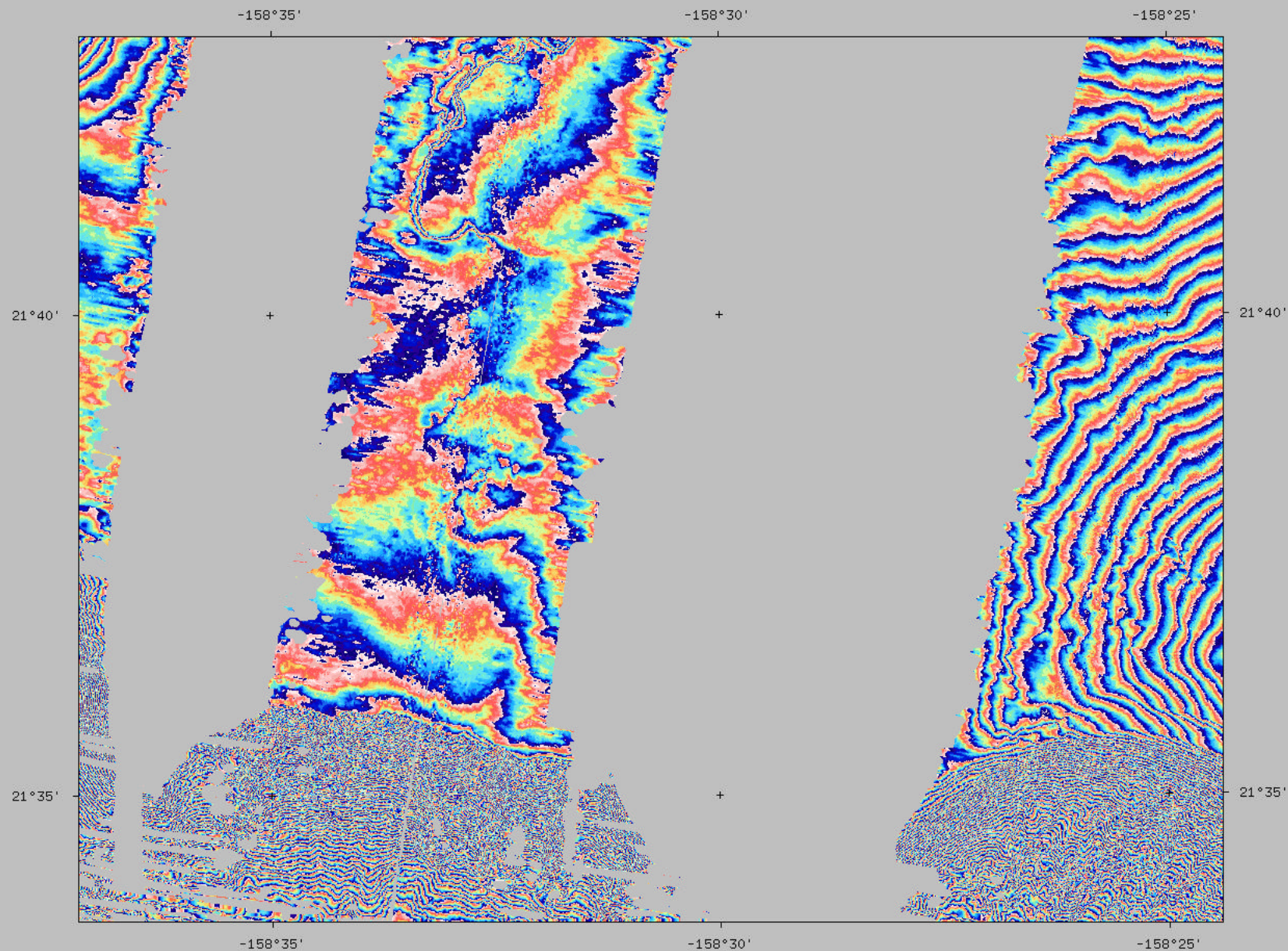
RTOVL 20m Bathymetry

- + U M F G B ▲ 20m 0 400



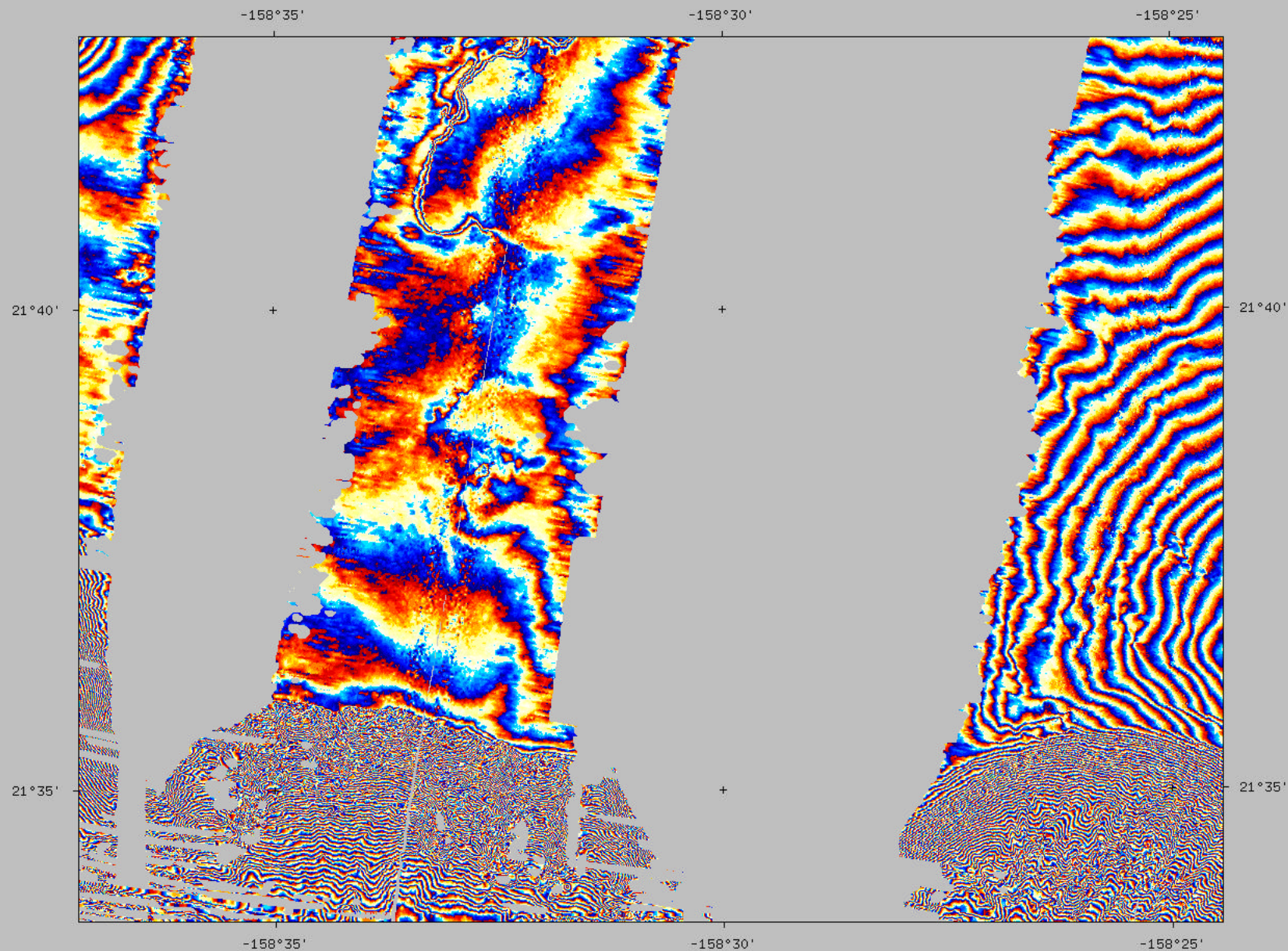
RTOVL 20m Bathymetry

- +      ▲ 1m 0  20



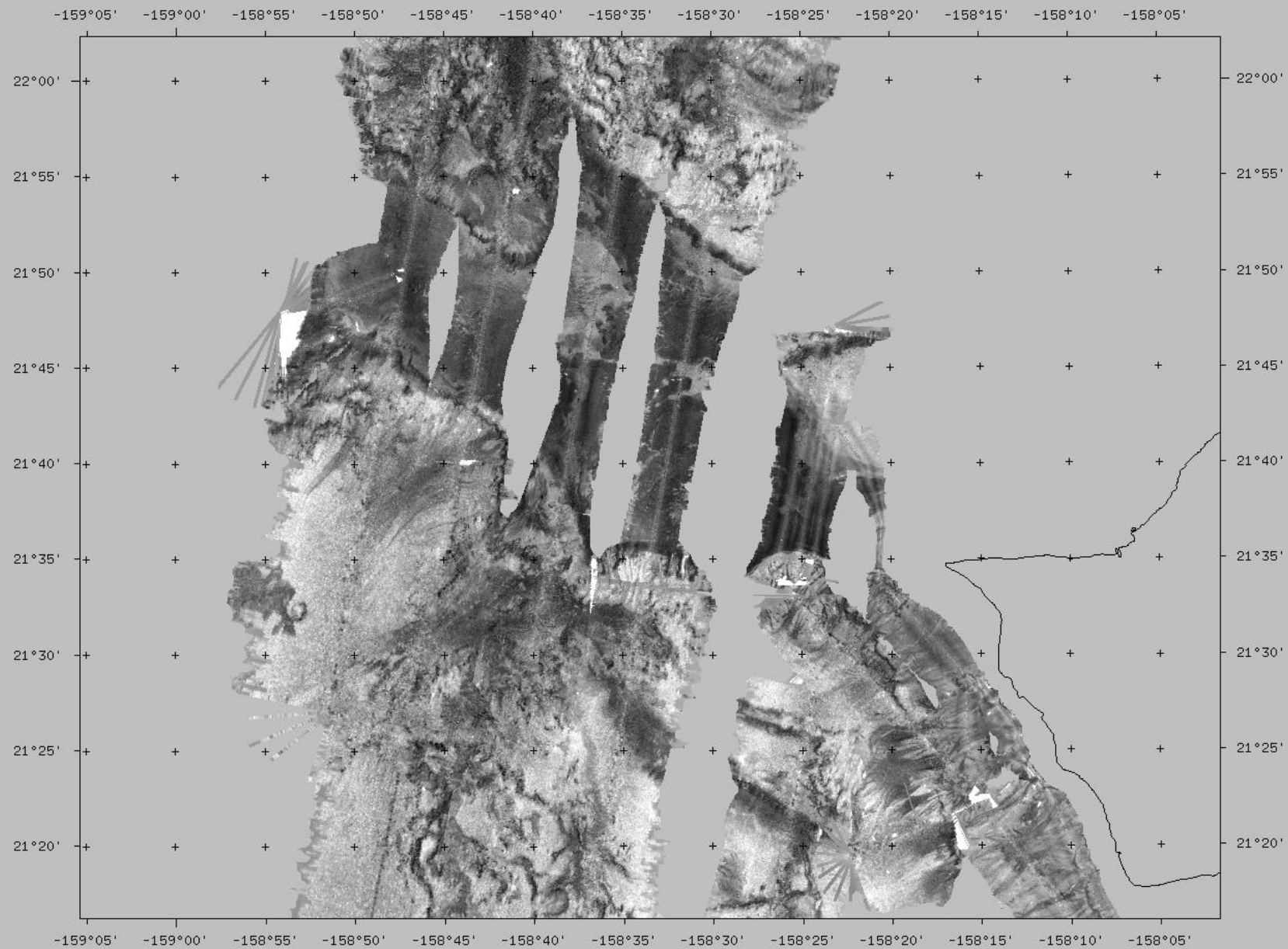
RTOVL 20m Bathymetry

- +      ▲ 1m 0  20



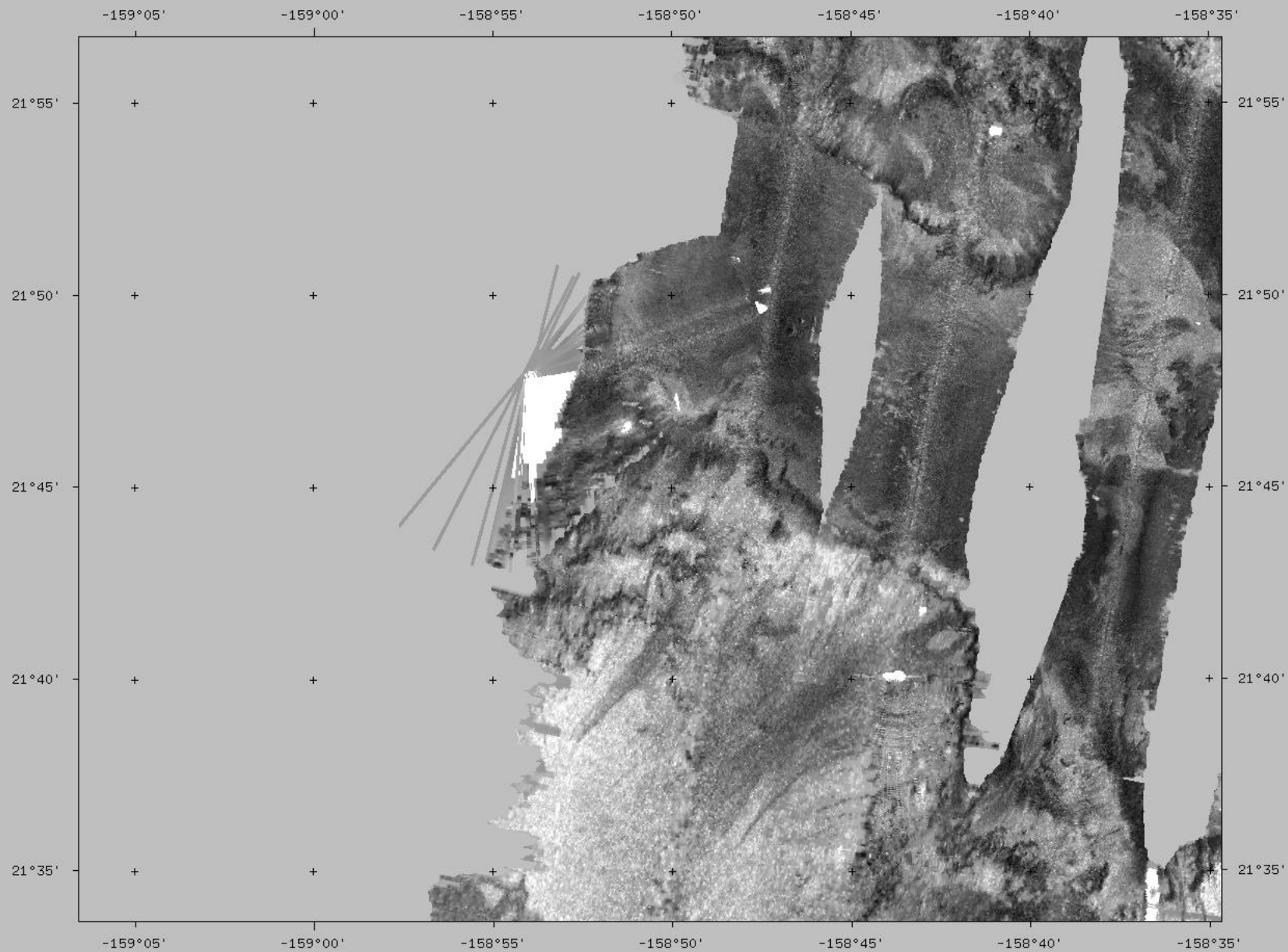
RTOVL 100m Sidescan

- +     5,50e+01  1,40e+02

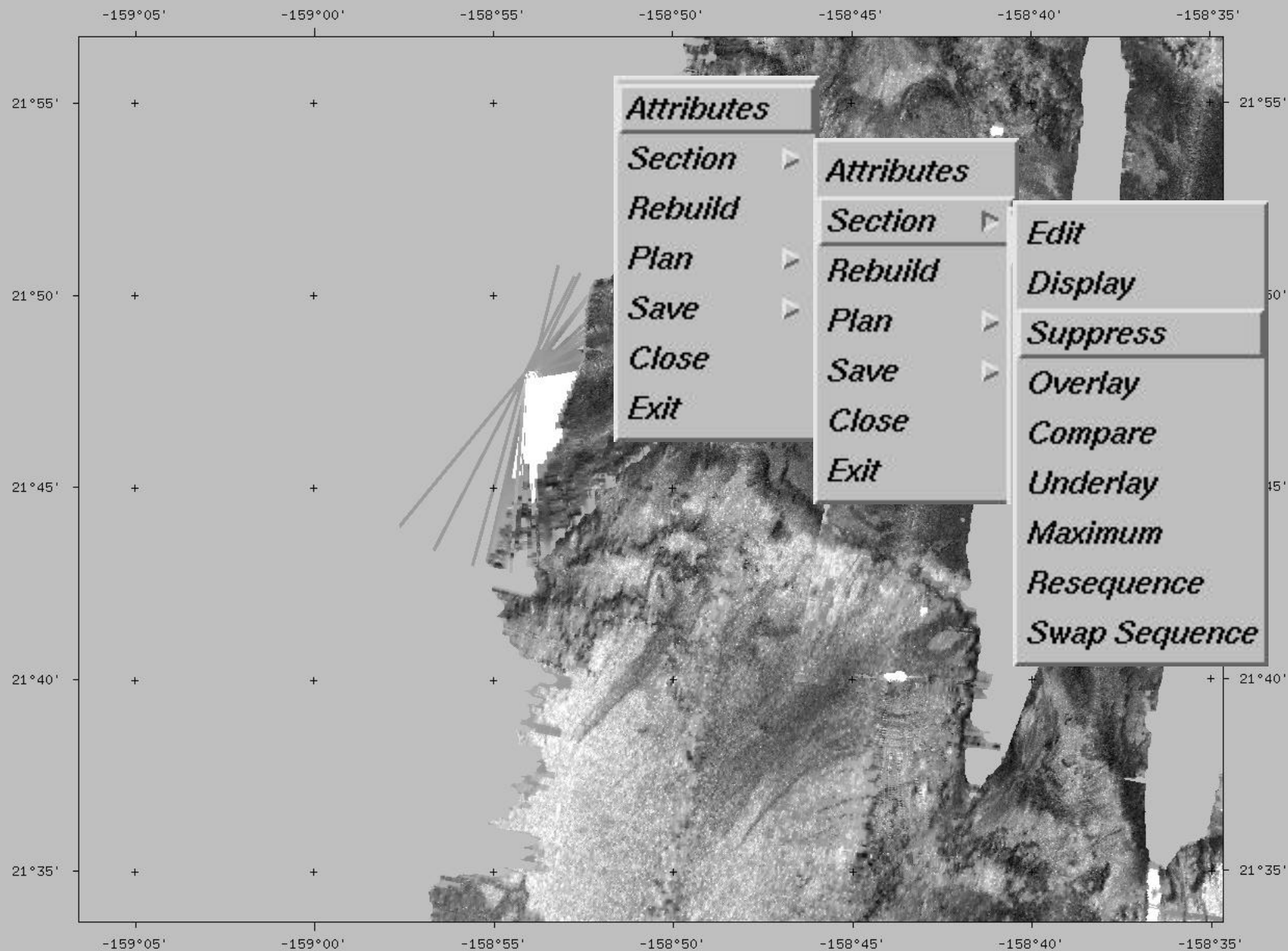


RTOVL 50m Sidescan

- +     5.50e+01  1.40e+02

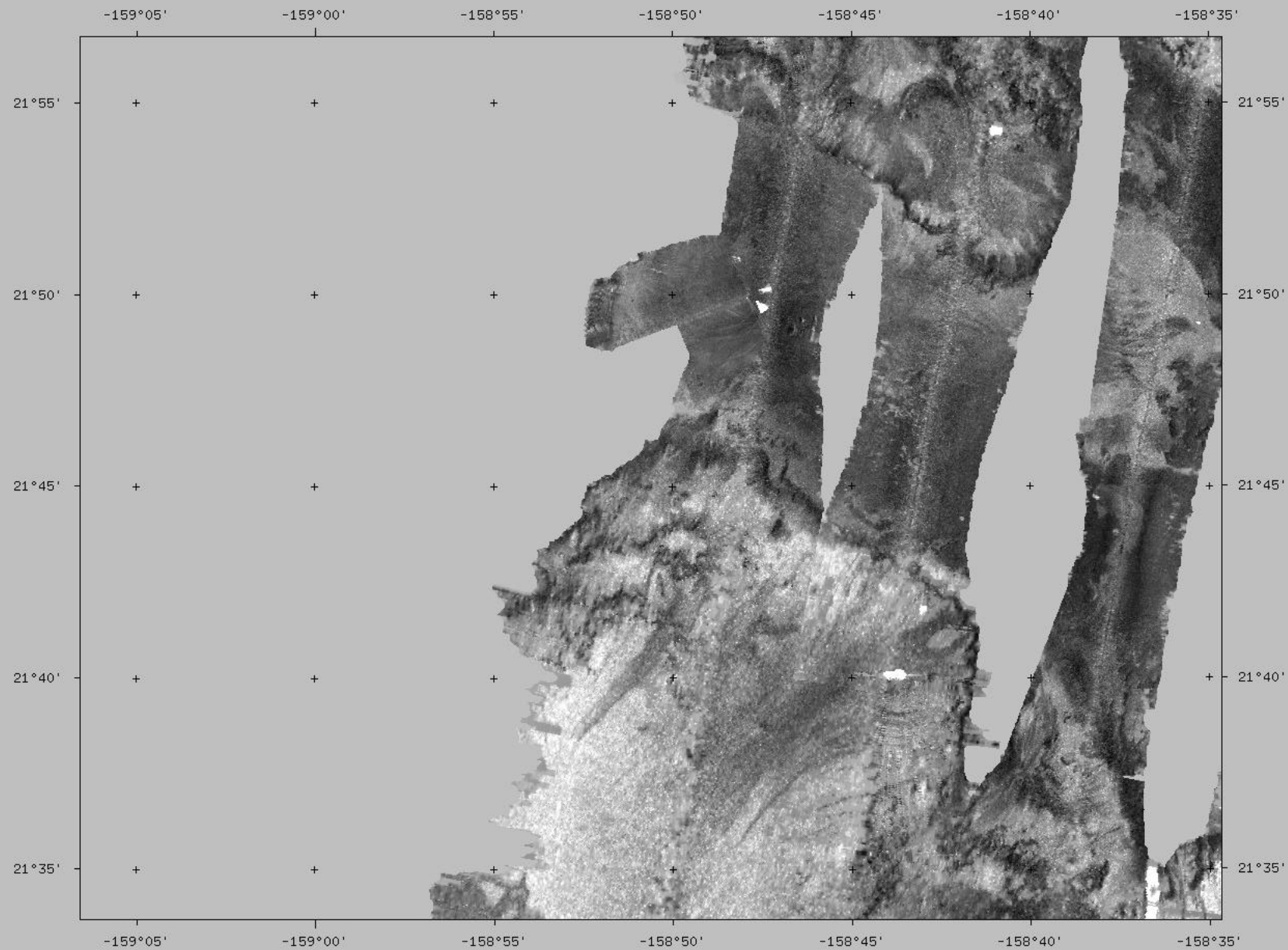


- + [U] [M] [F] [S] 5,50e+01 1,40e+02



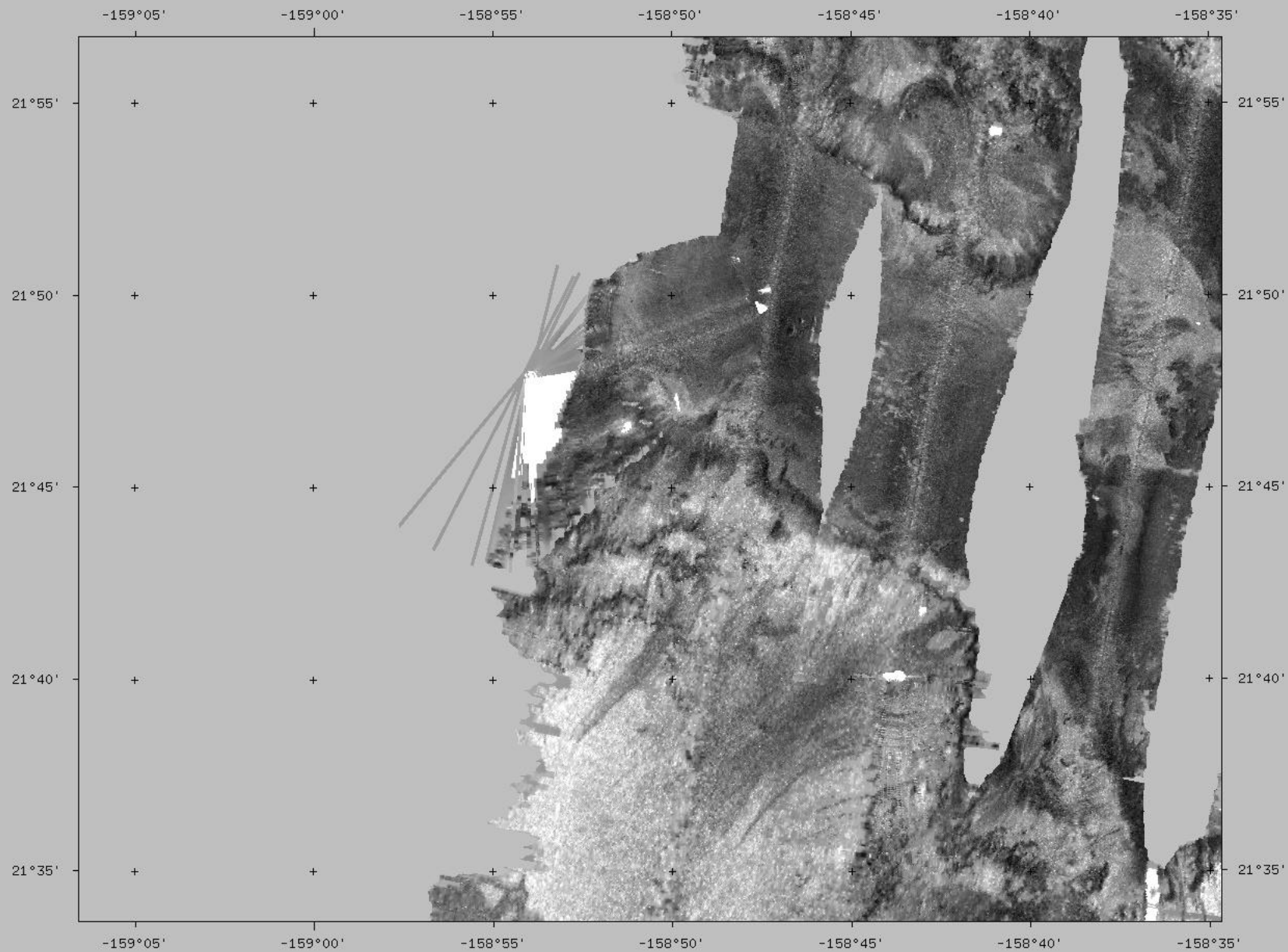
RTOVL 50m Sidescan

- +     5,50e+01  1,40e+02



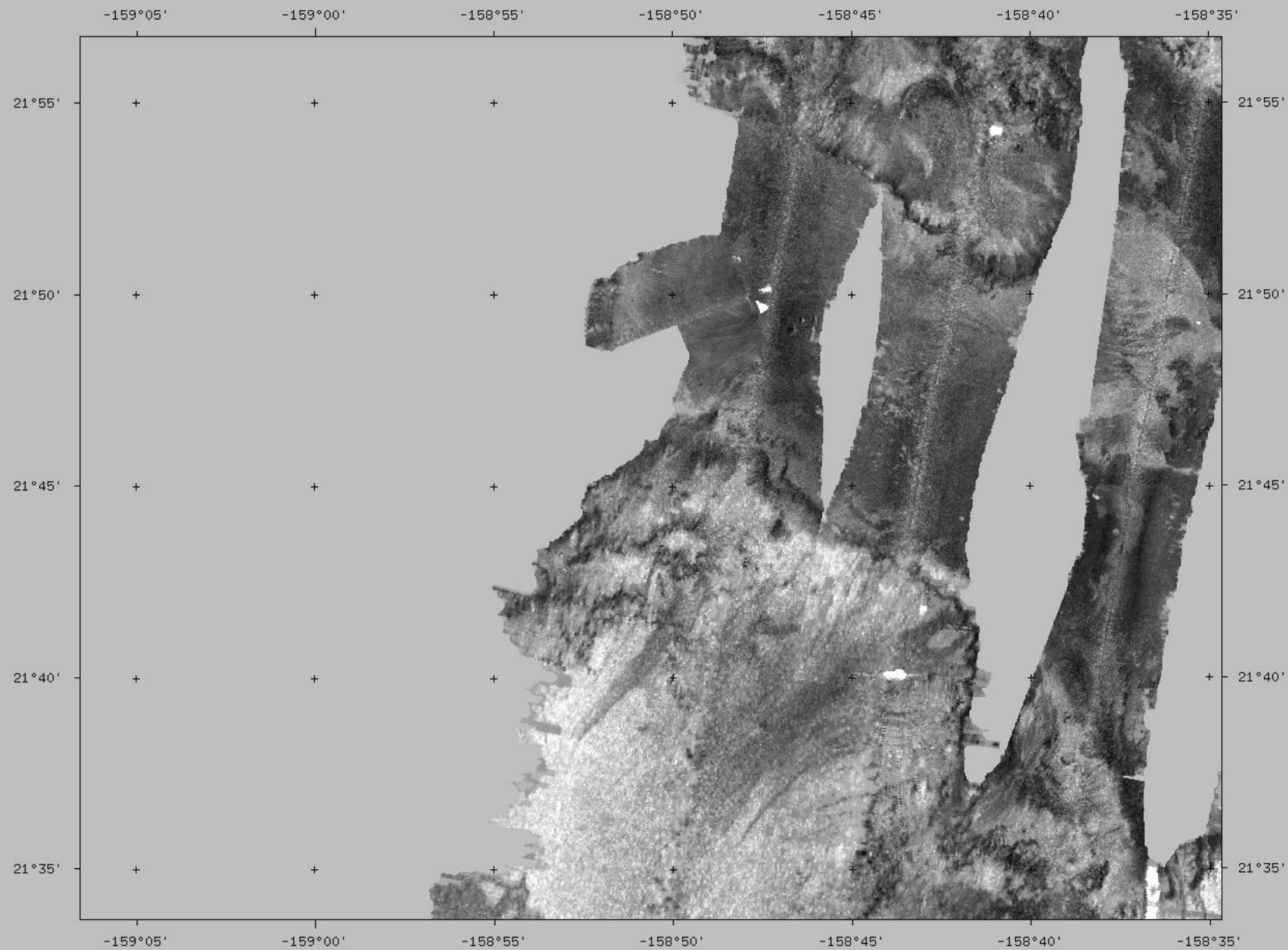
RTOVL 50m Sidescan

- +     5.50e+01  1.40e+02



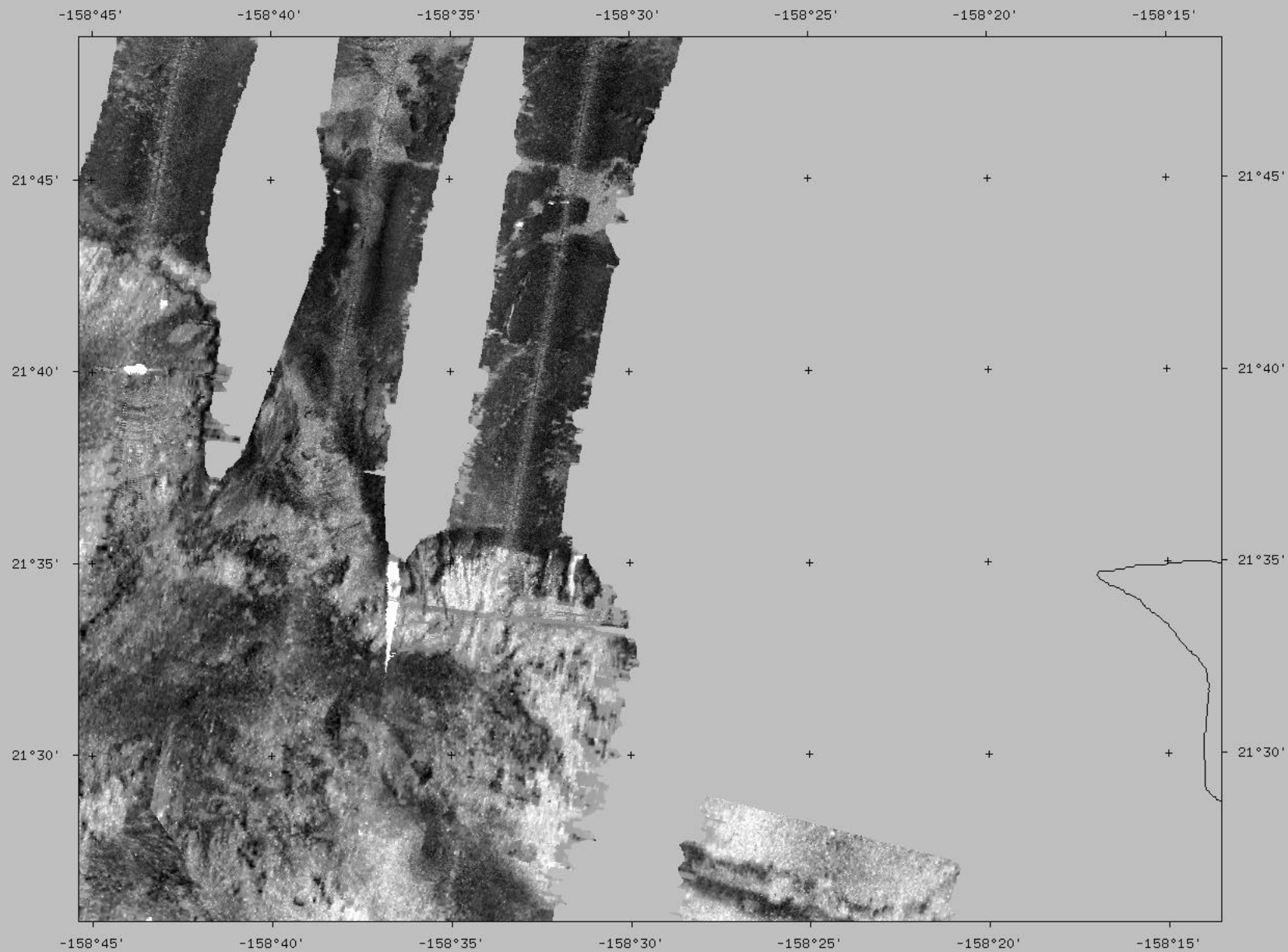
RTOVL 50m Sidescan

- +     5,50e+01  1,40e+02



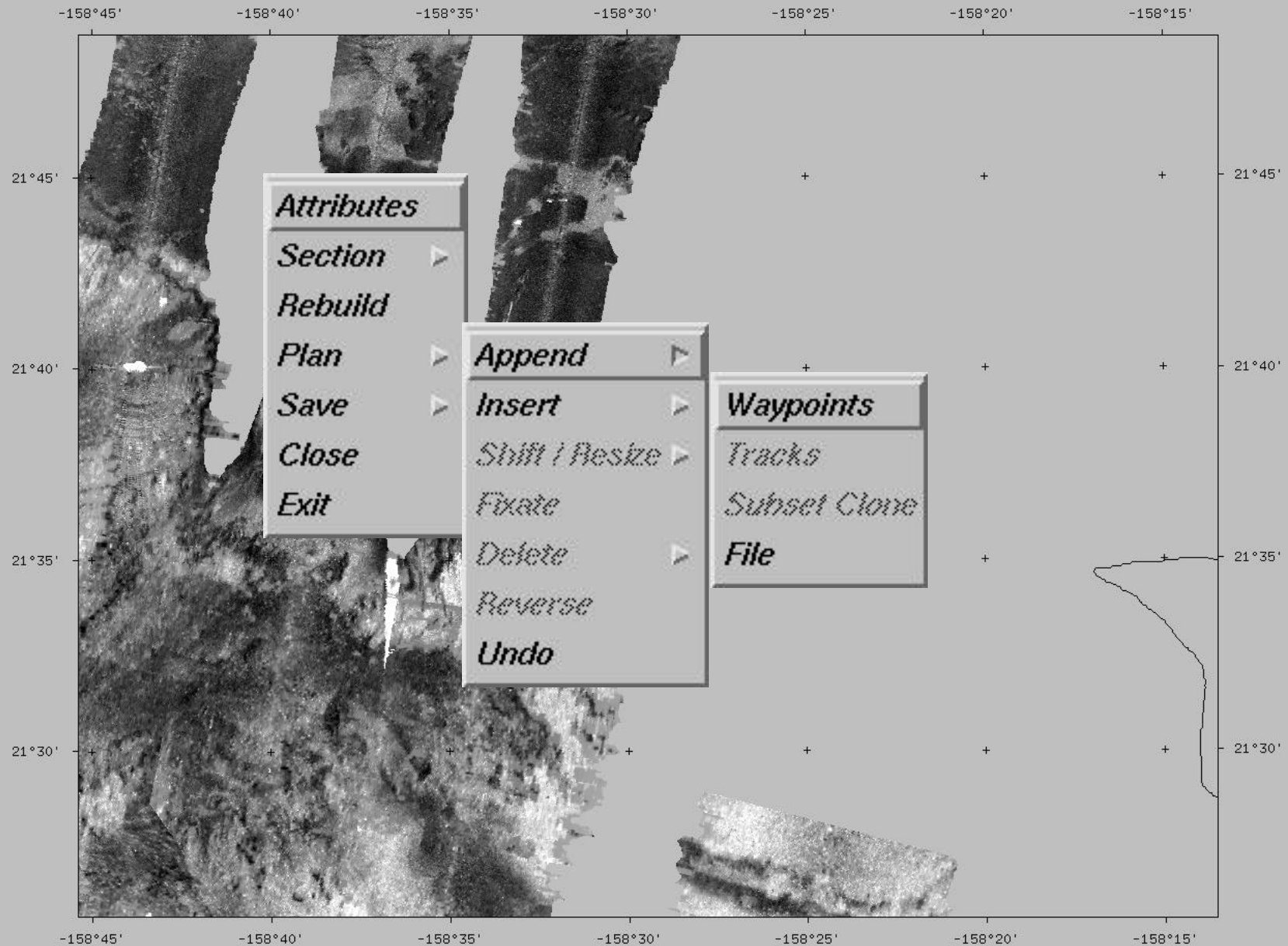
RTOVL 50m Sidescan

- + U M F S 5,50e+01  1,30e+02



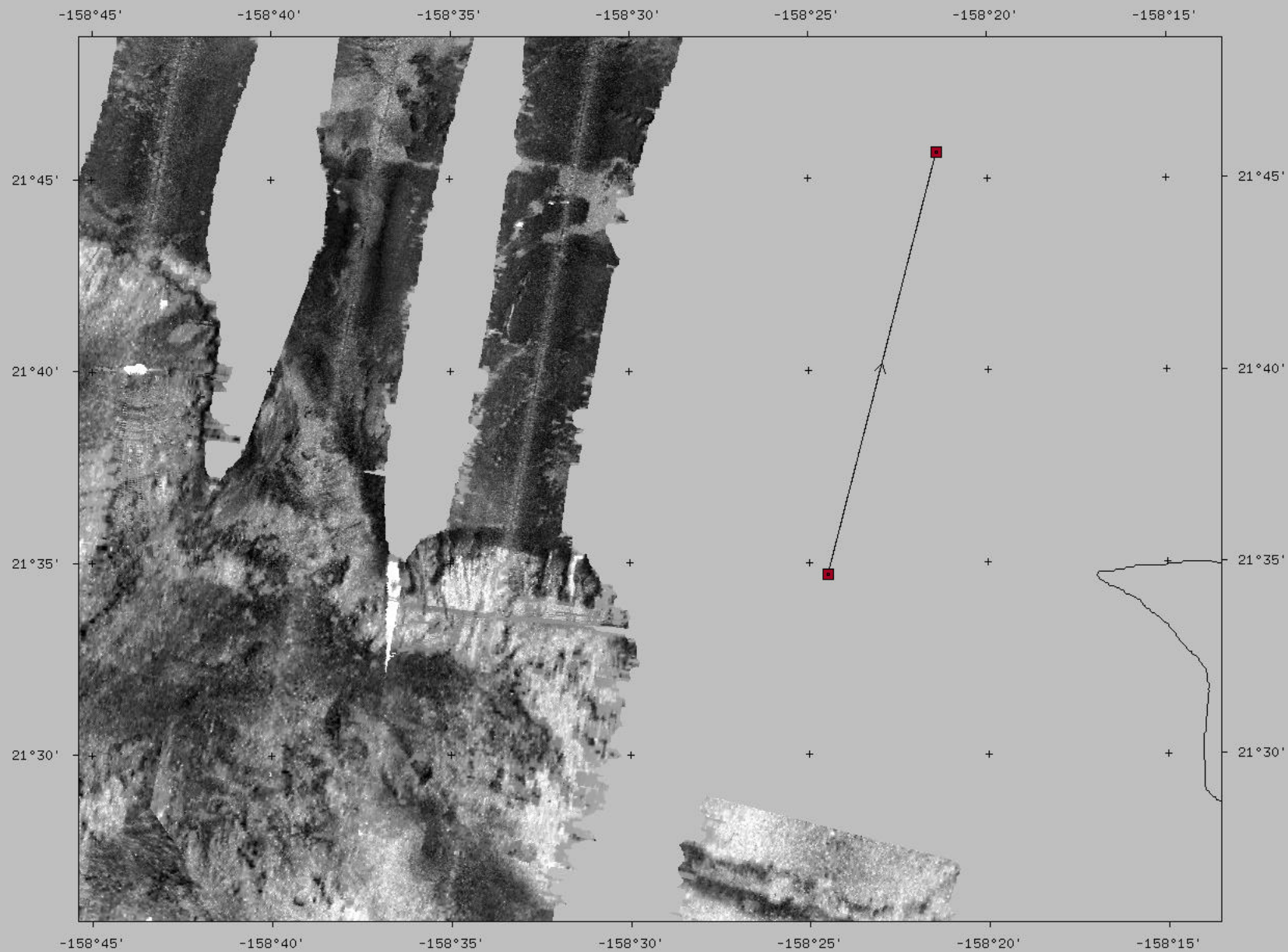
RTOVL 50m Sidescan

- +     5,50e+01 1,30e+02



RTOVL 50m Sidescan

- + U M F S 5.50e+01 1.30e+02



RTOVL 50m Sidescan

- +     S 5,50e+01  1,30e+02

RTOVL Plan Tracks

Number of Tracks:

Location  Left  Right

Total Swath Width:

Track Overlap:

Continue

Cancel

21°45'

21°40'

21°35'

21°30'

-158°45'

-158°40'

-158°35'

-158°30'

-158°25'

-158°20'

-158°15'

21°45'

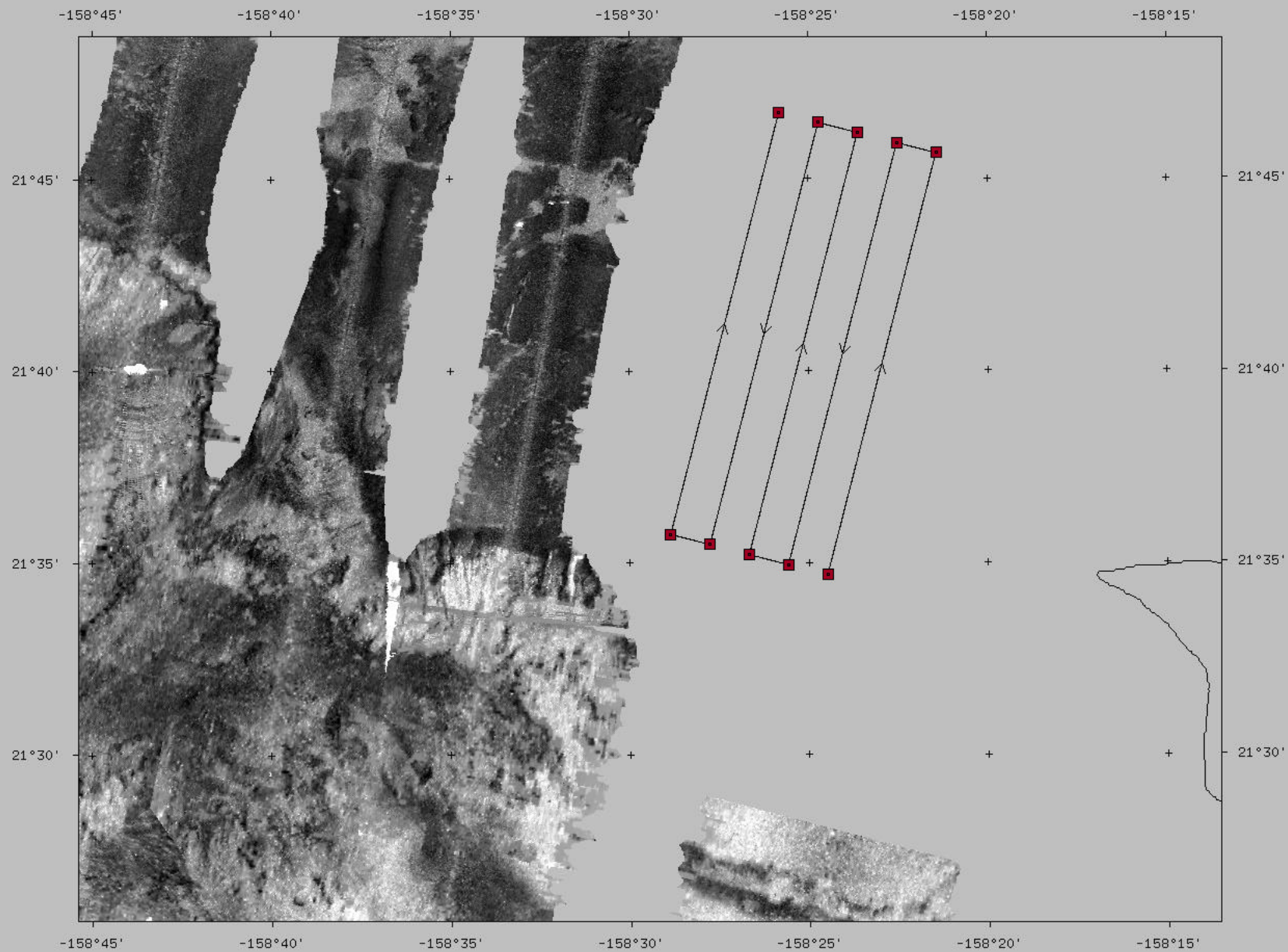
21°40'

21°35'

21°30'

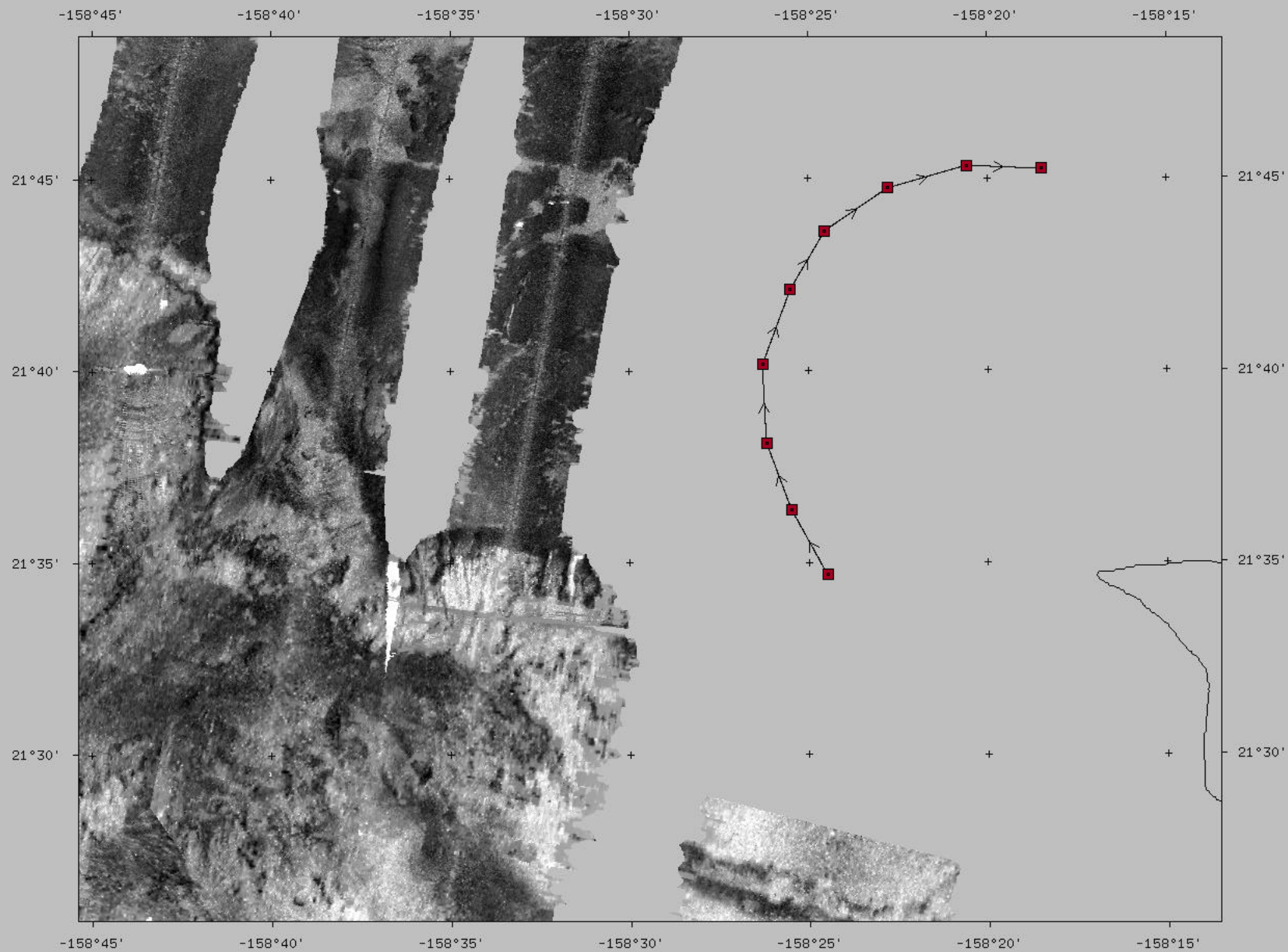
RTOVL 50m Sidescan

- + **U** **M** **F** **S** 5.50e+01 1.30e+02



RTOVL 50m Sidescan

- + U M F S 5.50e+01  1.30e+02



[-158°18.309', 21°48.432', --]

RTOVL 50m Sidescan

- +     S 5,50e+01  1,30e+02

-158°45' -158°40' -158°35' -158°30' -158°25' -158°20' -158°15'

21°45'

21°40'

21°35'

21°30'

Append

Insert

Shift / Resize

Fixate

Delete

Reverse

Undo

Waypoints

Tracks

Subset Clone

File

21°45'

21°40'

21°35'

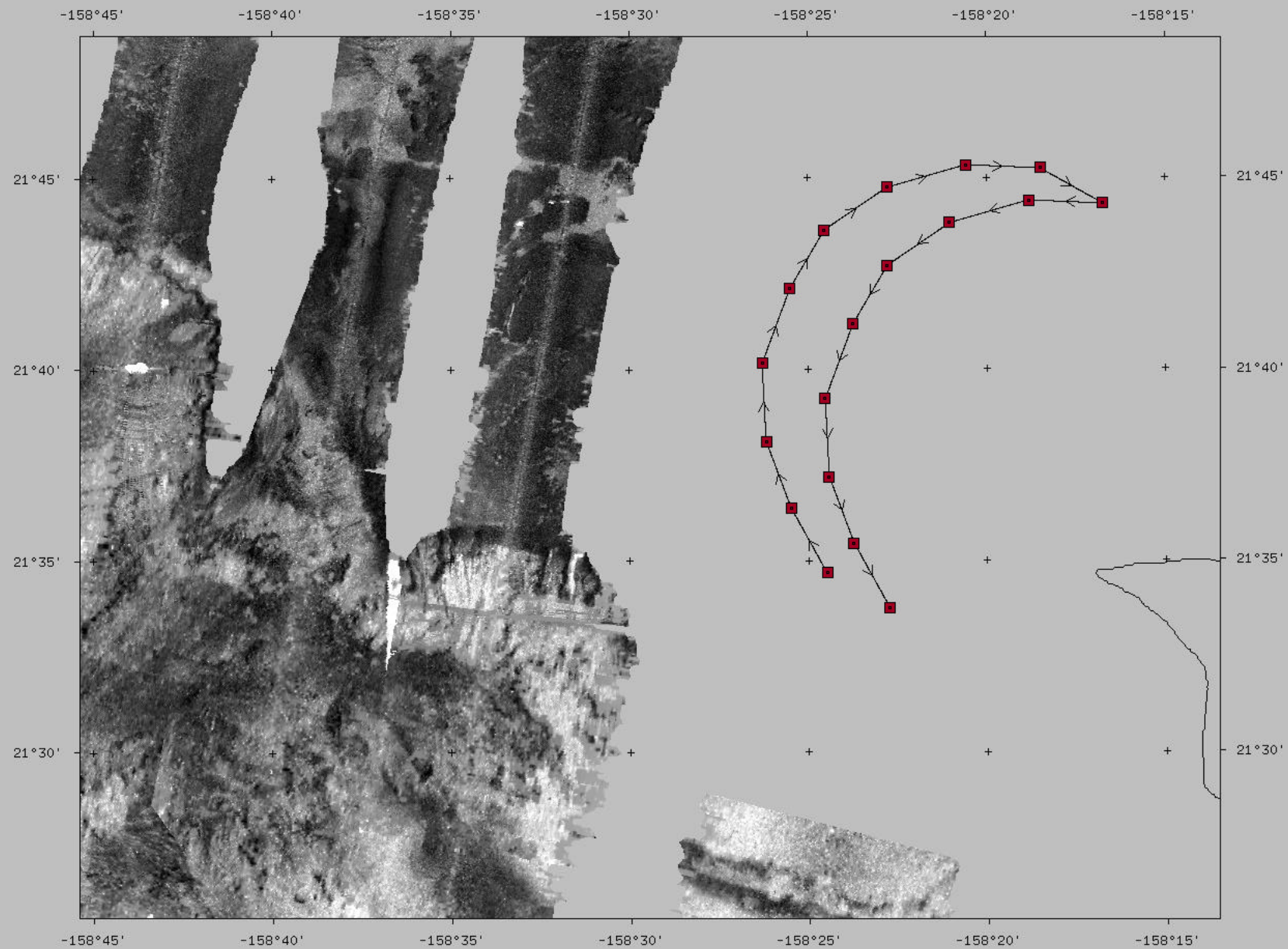
21°30'

-158°45' -158°40' -158°35' -158°30' -158°25' -158°20' -158°15'

[-158°18.309', 21°48.432', --]

RTOVL 50m Sidescan

- + **U** **M** **F** **S** 5,50e+01 1,30e+02



RTOVL 50m Sidescan

- + **U** **M** **F** **S** 5,50e+01 1,30e+02

-158°45' -158°40' -158°35' -158°30' -158°25' -158°20' -158°15'

21°45'

21°40'

21°35'

21°30'

-158°45' -158°40' -158°35' -158°30' -158°25' -158°20' -158°15'

Append

Insert

Shift / Resize

Fixate

Delete

Reverse

Undo

21°45'

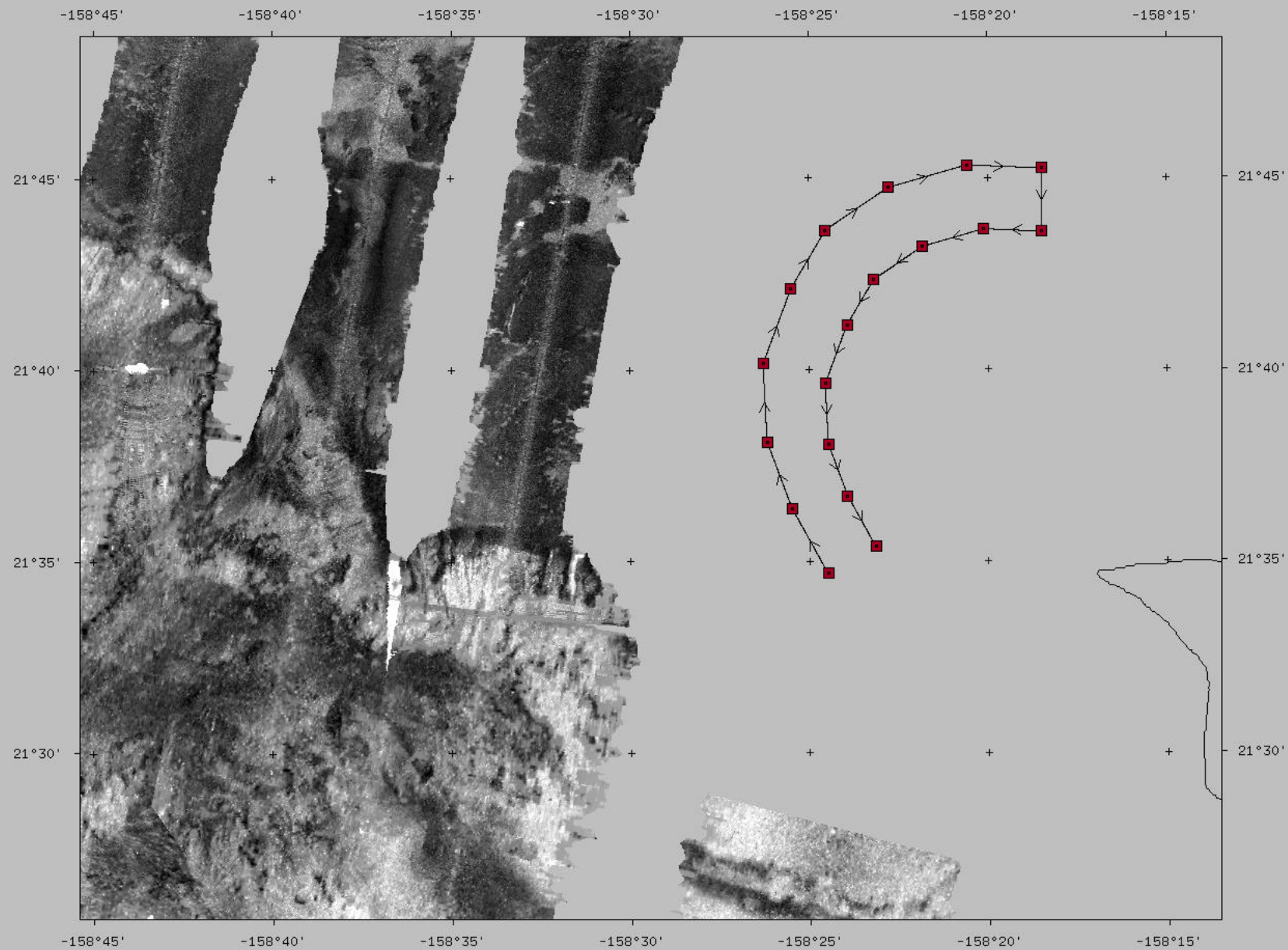
21°40'

21°35'

21°30'

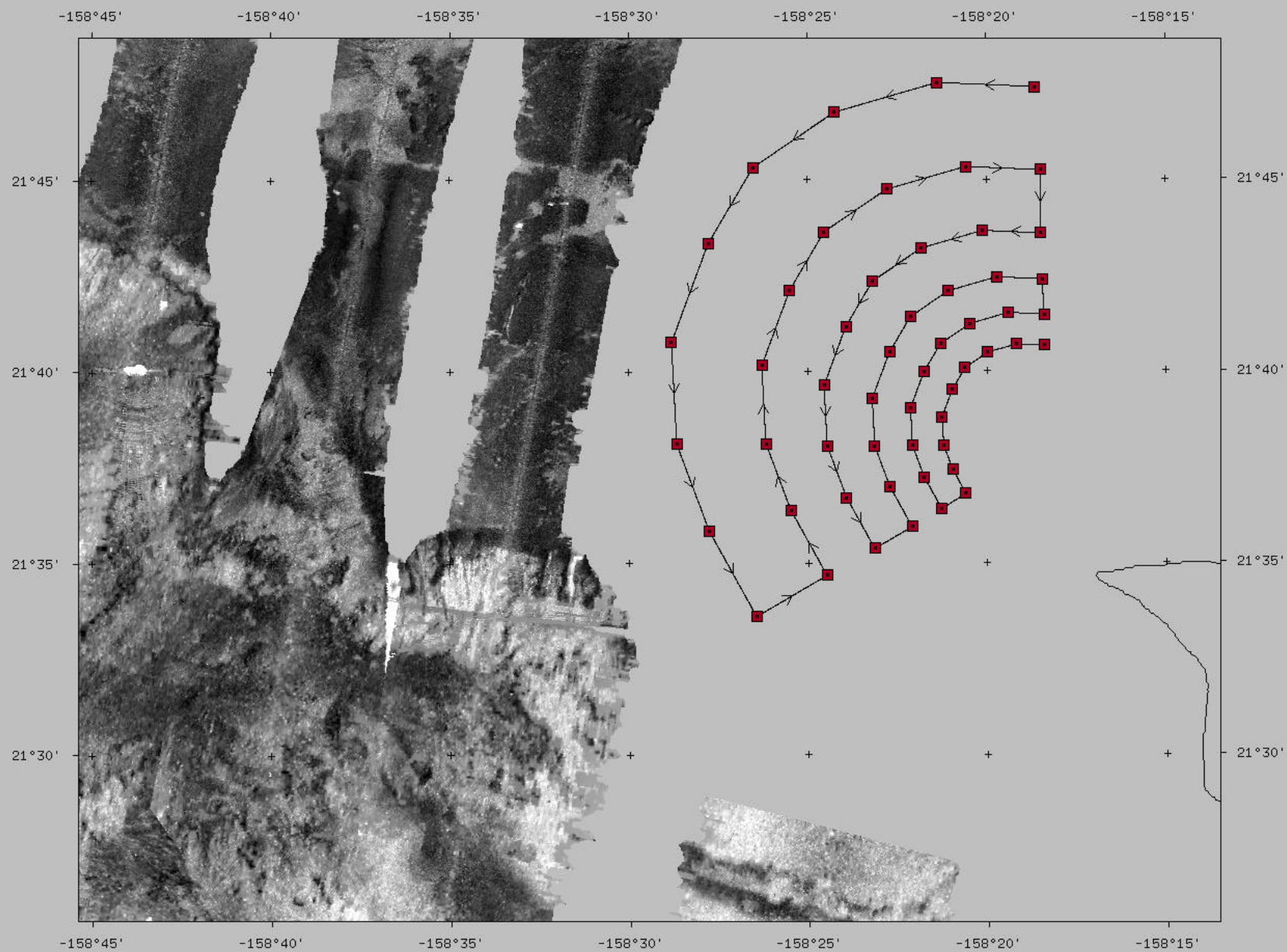
RTOVL 50m Sidescan

- + **U** **M** **F** **S** 5.50e+01 1.30e+02



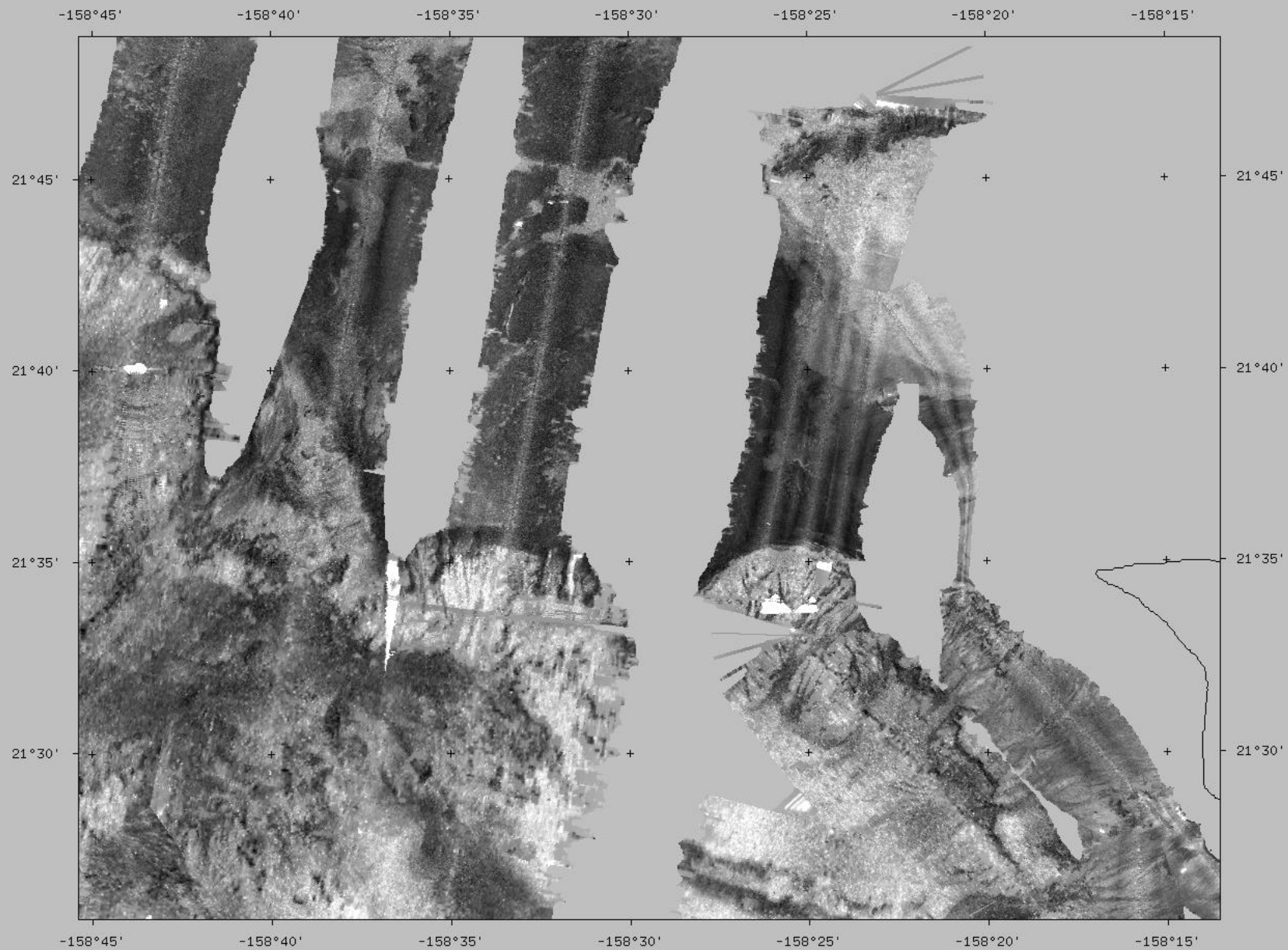
RTOVL 50m Sidescan

- + U M F S 5.50e+01  1.30e+02



RTOVL 50m Sidescan

- +     5.50e+01  1.40e+02



Kilo Moana Real-Time Display

- Works on a variety of multibeam & SSBS sonar systems
- Allows science users to interact with multibeam bathymetry and backscatter charts without compromising data acquisition
- See a demonstration of the software in action after talk

Future Plans

- More robust survey planning (waypoint export/import)
- Helm display for better communication with bridge

For More Information

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Roger Davis: rbd@soest.hawaii.edu