

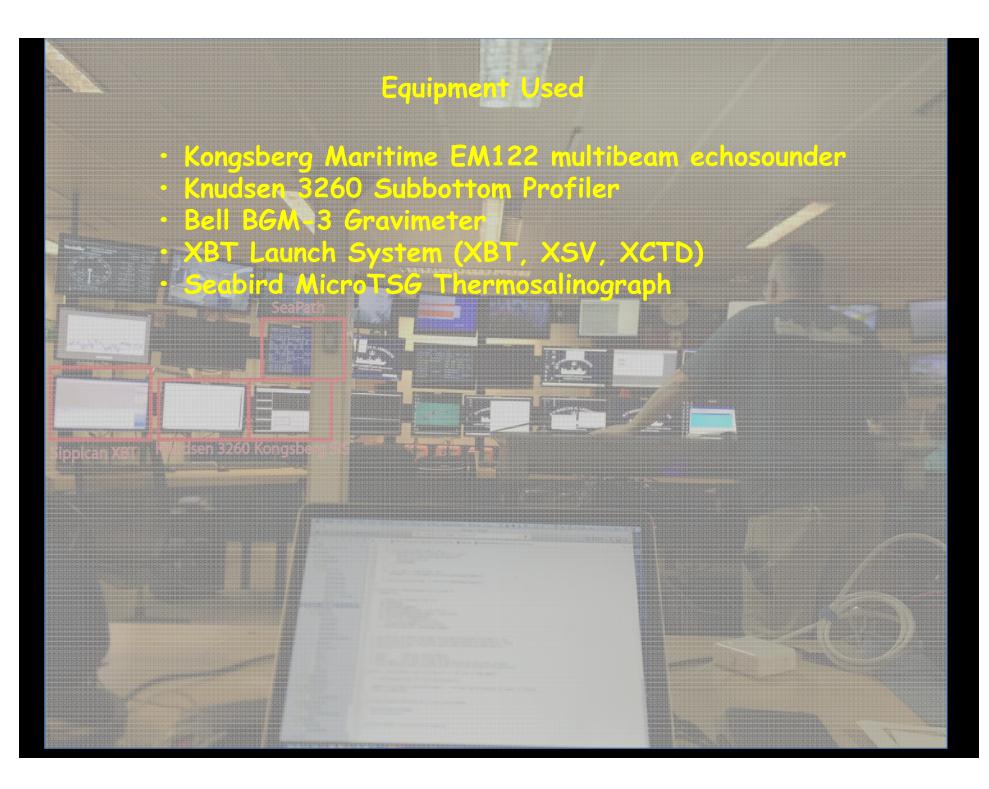
planned tracklines

### Cruise Calendar

Departed NYC	30 July
Transit to Patch Test Site	30-31 July
Patch Test Site	1 August
Commenced MBES Mapping.	2 August
Medical Evacuation	17-19 August
Completed MBES Mapping	27 August
Transit to Woods Hole	.28-29 August

# Cruise Summary

Total Trackline10,796 km (5,829 nmi)
Total Area Mapped157,166 km² (45,822 nmi²)
Total Time Mapping24.5 days
Total Transit Time2.0 days
Medical Evacuation2.0 days



#### Patch Test Results

### XBT calibrated with XCTD

Patch Test determined no adjustments necessary

Pitch: -0.23°

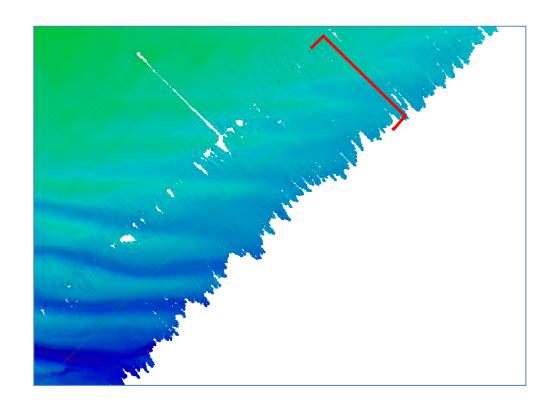
Roll: -0.54°

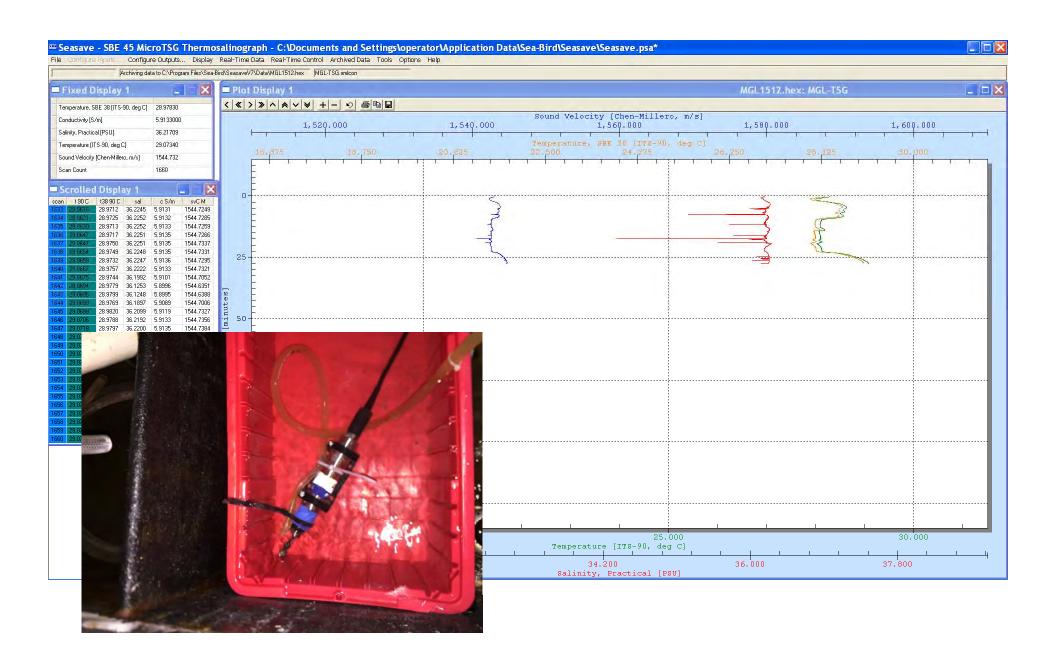
Yaw: 0.43°

Timing: 0.0 ms

# Issues Early On

- · Micro SV vs. TSG
- Synchronization of EM122 and Knudsen
- · Attitude data served through UDP packets(?)
- · bad weather-bubble sweep





Lamont-Doherty Earth Obe		OFFICE OF MARINE OPERATION DOCUMENT	
PREPARED BY: Robert C. Koprowski	EFFECTIVE	DATE: 8/26/2015	DOCUMENT NO:
SUBJECT: Kongsberg EM122 Multibeam Synchronization with Knudsen Chirp 3650 SBP Array	REVISION:1.	1	Page 1 of 5

Distribution	Initial
Return	To





LAMONT DOHERTY EARTH OBSERVATORY
OFFICE OF MARINE OPERATION
Kongsberg EM122 Multibeam Synchronization with Knudsen Chirp
3650 Sub-bottom Profiler Array

1.0	First Draft	08/21/2015	RCK
1.1	Second Revision Complete	08/26/2015	RCK
DEV/	DESCRIPTION	DATE	ADDDOVED



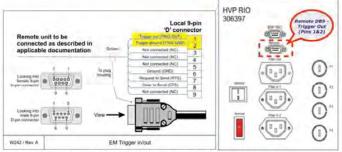


Figure 2.1 - Wiring Diagram Female DB9 Pin out signals and the Remote Connection port

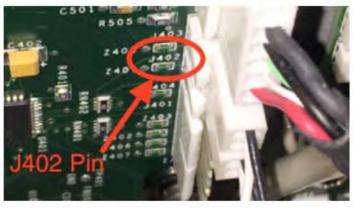
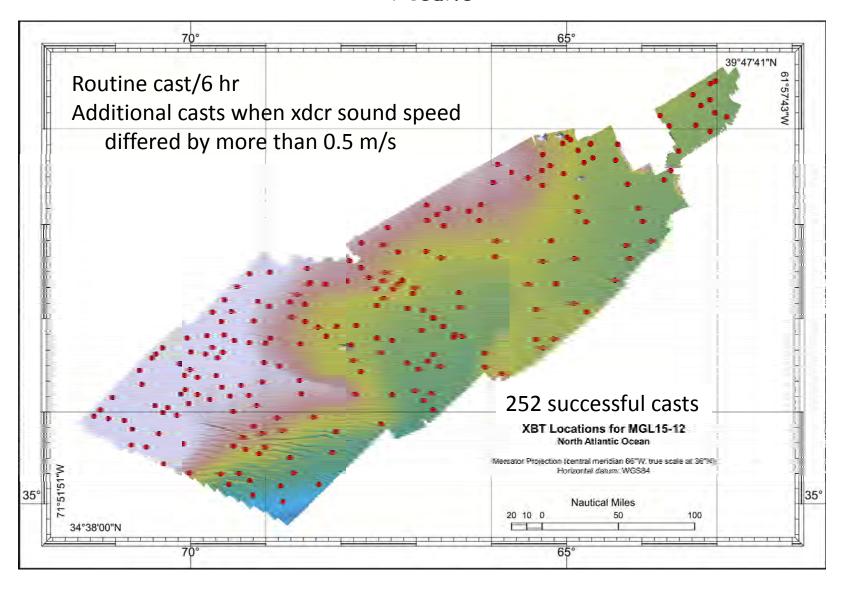
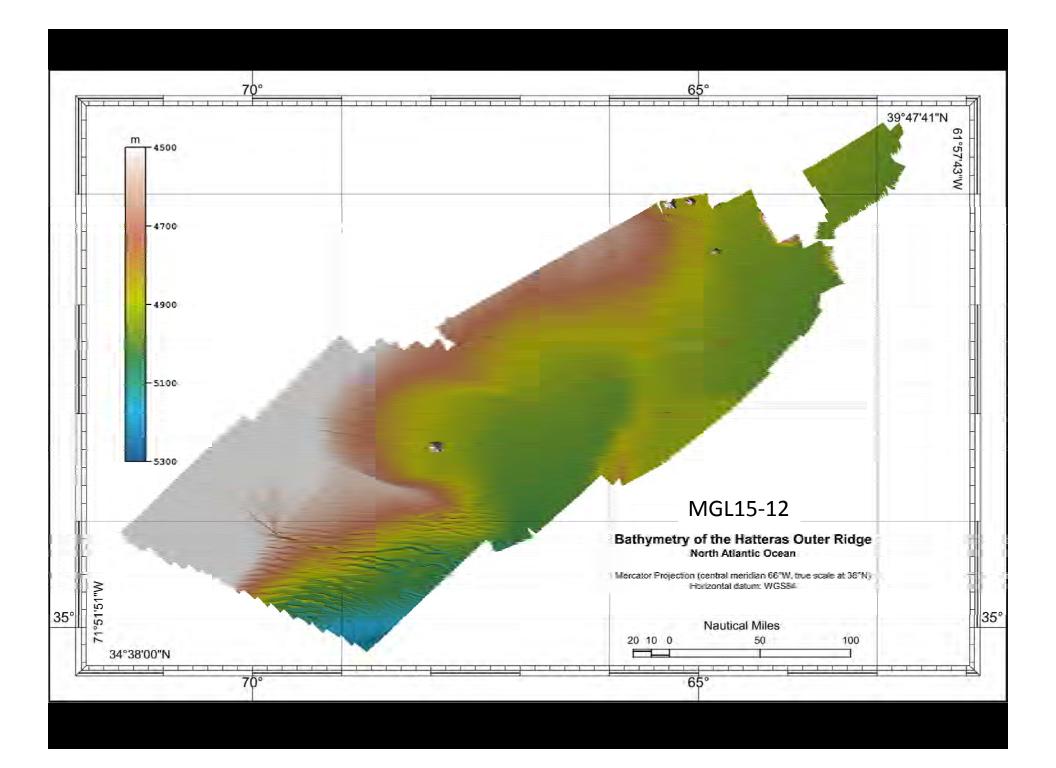


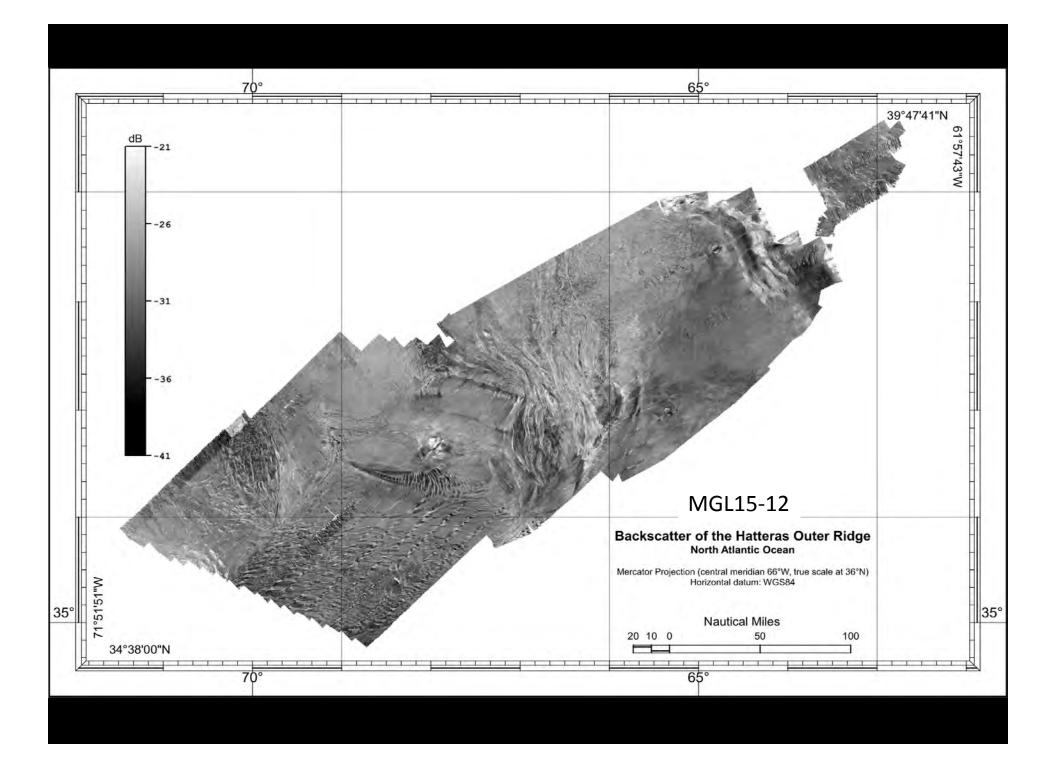
Figure 2.2 - Knudsen Chirp 3650 Processor Module board J402 pins for Aux BNC ports

Date	Time	Туре	No.	Disabl.	Message	
2015 08 11	12:34:47	3	2501		(PU Sensor) Attitude/Velocity on PU port UDP5 is missing.	
2015 08 11	12:34:52	3	722		EM122: Attitude Velocity data not valid for ping	
2015 08 11	12:34:57	3	2501		(PU Sensor) Attitude/Velocity on PU port UDP5 is missing.	
2015 08 11	12:35:00	122	650		(DDS) Echo sounder EM122_109. Frequency of received AttVel datagrams on PU UDP5 is less than 90% of e Expected/received (Hz): 90.00/0.00	
2015 08 11	12:35:07	3	2501		(PU Sensor) Attitude/Velocity on PU port UDP5 is missing.	
2015 08 11	12:35:09	3	722		EM122: Attitude Velocity data not valid for ping	
2015 08 11	12:35:17	3	2501		(PU Sensor) Attitude/Velocity on PU port UDP5 is missing.	
2015 08 11	12:35:27	3	722		EM122: Attitude Velocity data not valid for ping	
2015 08 11	12:35:27	3.	2501		(PU Sensor) Attitude/Velocity on PU port UDP5 is missing.	
2015 08 11	12:35:37	3	2501		(PU Sensor) Attitude/Velocity on PU port UDP5 is missing.	
2015 08 11	12:35:45	3	722		EM122: Attitude Velocity data not valid for ping	
2015 08 11	12:35:47	3	2501		(PU Sensor) Attitude/Velocity on PU port UDP5 is missing.	
2015 08 11	12:35:57	3	2501		(PU Sensor) Attitude/Velocity on PU port UDP5 is missing.	
2015 08 11	12:36:00	122	650		(DDS) Echo sounder EM122_109. Frequency of received AttVel datagrams on PU UDP5 is less than 90% of e Expected/received (Hz): 90.00/0.00	
2015 08 11	12:36:03	3	722		EM122: Attitude Velocity data not valid for ping	
2015 08 11	12:42:53	1	205		Checking XYZ: 2 Datagram too small	
2015 08 11	13:09:25	3	2503		(PU Sensor) GGA on PU port COM1 is missing.	

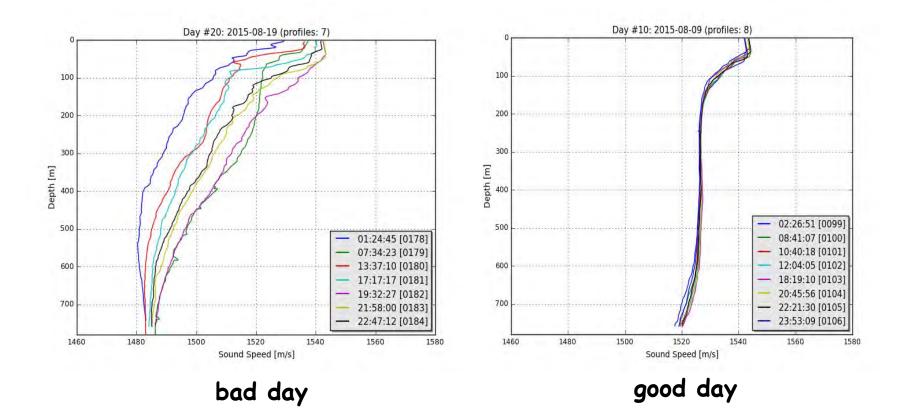
### Results

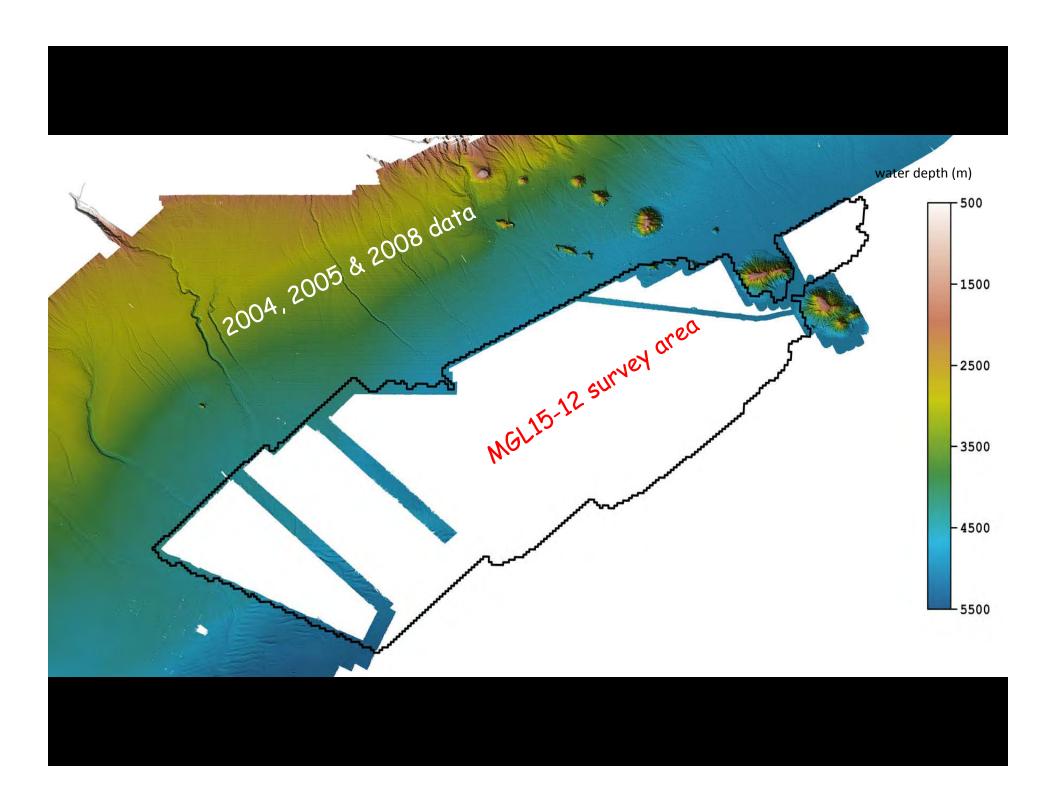




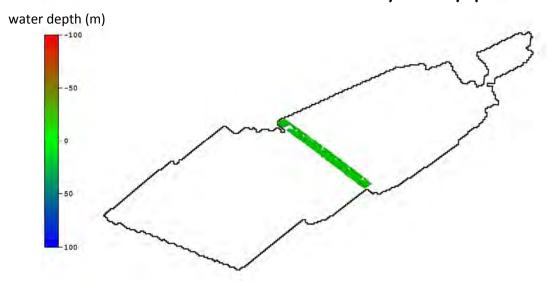


## example of daily XBT casts

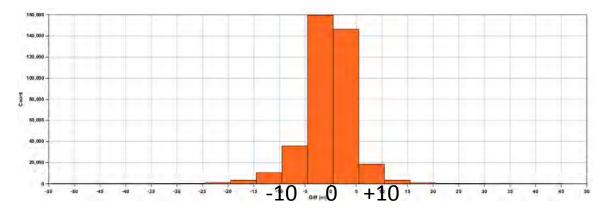




### cross-line check of bathymetry precision

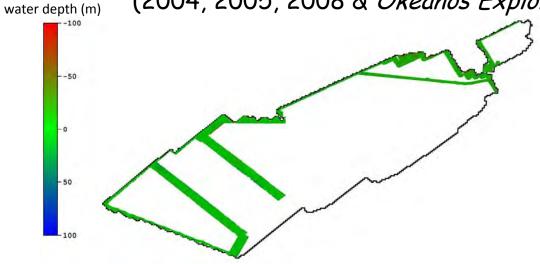


Surface difference ( $\Delta$ ) between main survey area and cross lines.  $\Delta$  Range from -54 to +45 m, with mean  $\Delta$  =-0.3 m and  $\sigma$  = 4.7 m

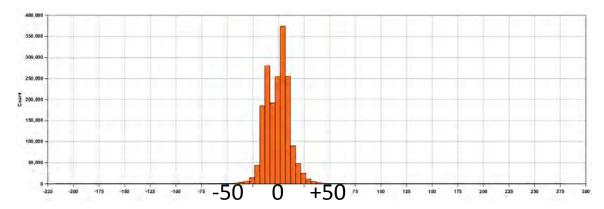


Histogram of surface differences ( $\Delta$ ) between main survey area and cross lines.

cross-line check of bathymetry precision (2004, 2005, 2008 & Okeanos Explorer)



Surface difference ( $\Delta$ ) between main survey area and cross lines.  $\Delta$  Range from -215 to +274 m, with mean  $\Delta$  =-0.8 m and  $\sigma$  = 11.6 m



Histogram of surface differences ( $\Delta$ ) between main survey area and cross lines.