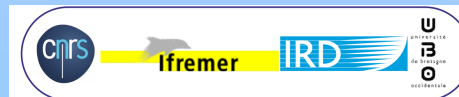


# **CIAM :** **a frame for ADCP deployment** **Châssis d'Instrumentation Autonome de Mesures**

**Service Techniques d'observation in-situ**  
**Laboratoire de Physique des Océans**



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Michel HAMON



Pierre BRANELLEC



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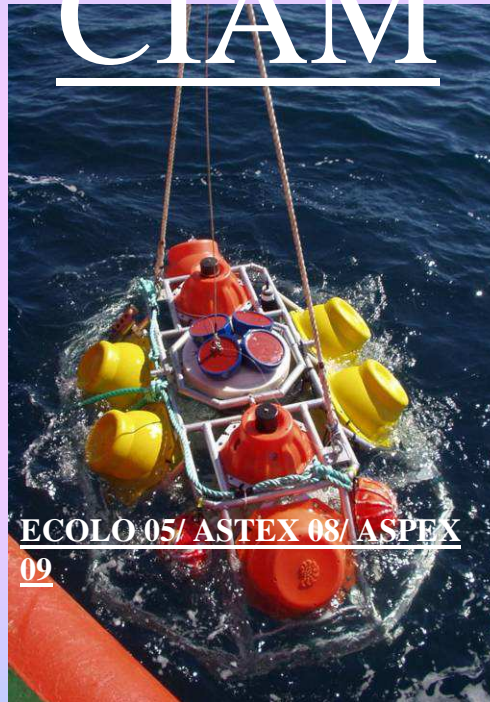
Philippe LE BOT



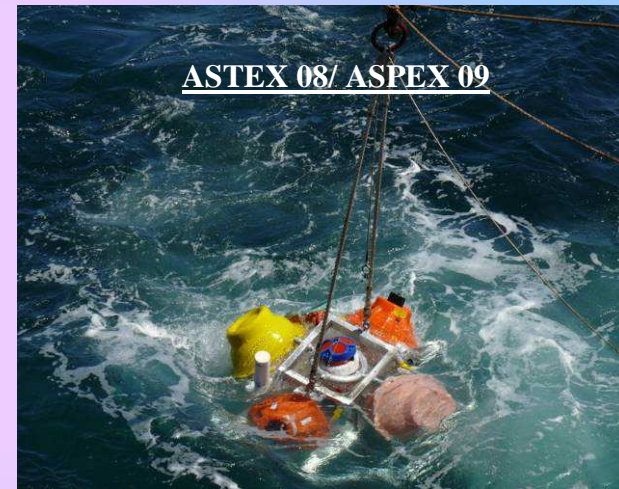
Olivier PEDEN



OVIDE 05/ ASTEX 08



ECOLO 05/ ASTEX 08/ ASPEX 09



ASTEX 08/ ASPEX 09



Olivier MENAGE

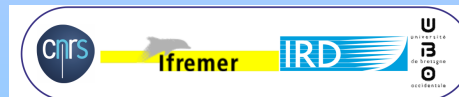


Stéphane LEIZOUR

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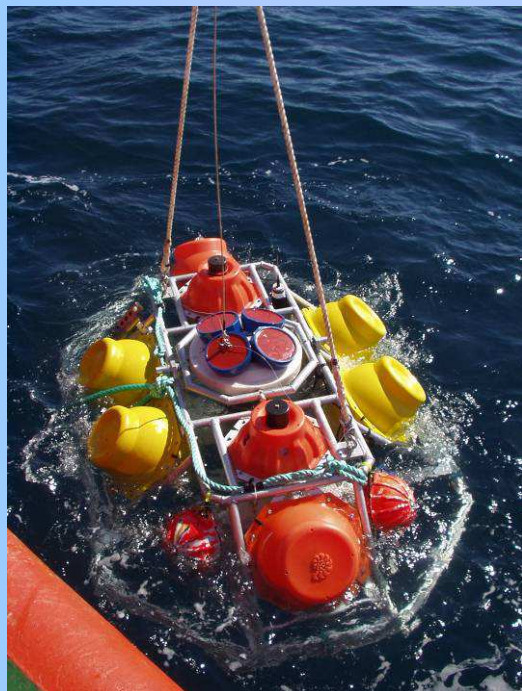


# CIAM : needs

- Long term measurement in harsh environments : natural conditions, human activities, ...
- Deployment : dropped from the surface
- Recovery : weight released by acoustic commands
- Alternative to mooring lines



## Two versions



75 Khz or 150 Khz

- Aluminium Structure
- Nautilus glass speres
- RDI ADCP
- SBE 37
- In house small releases
- Ixblue acoustic commands
- Argos beacon
- (Stain) steel weight

300 Khz or 600 Khz



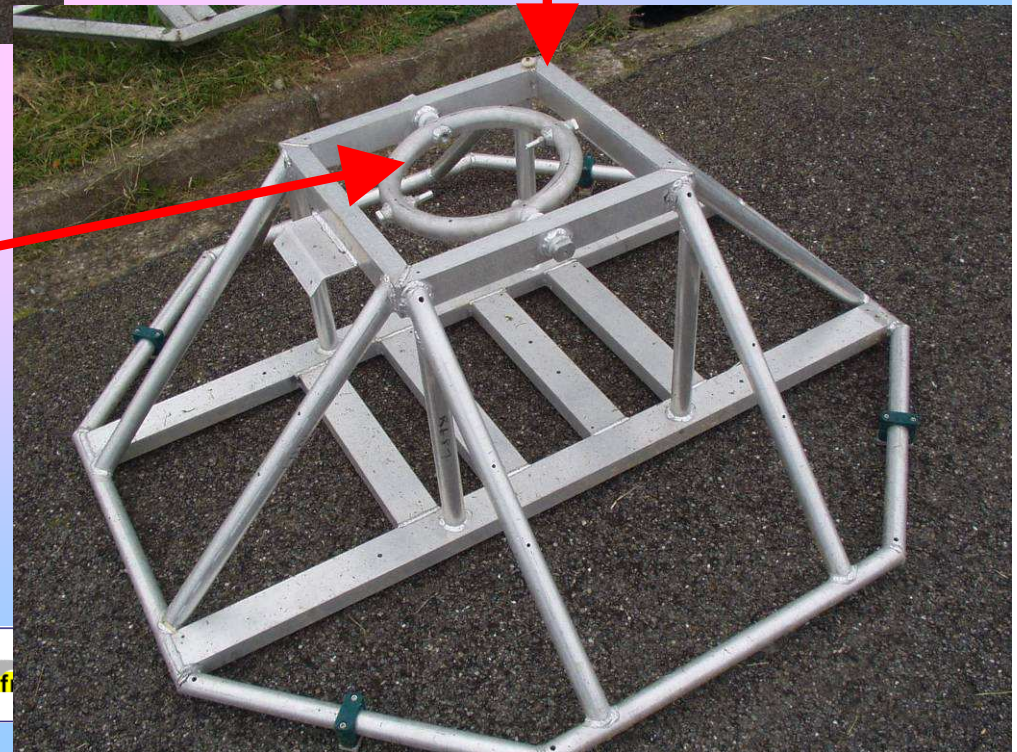


## Aluminium frames (Al 6060)

3 x 2 x 0.60 m

1.50 x 1.50 x 0.60 m

**Gimbal for ADCP**  
→ **Vertical profiles**



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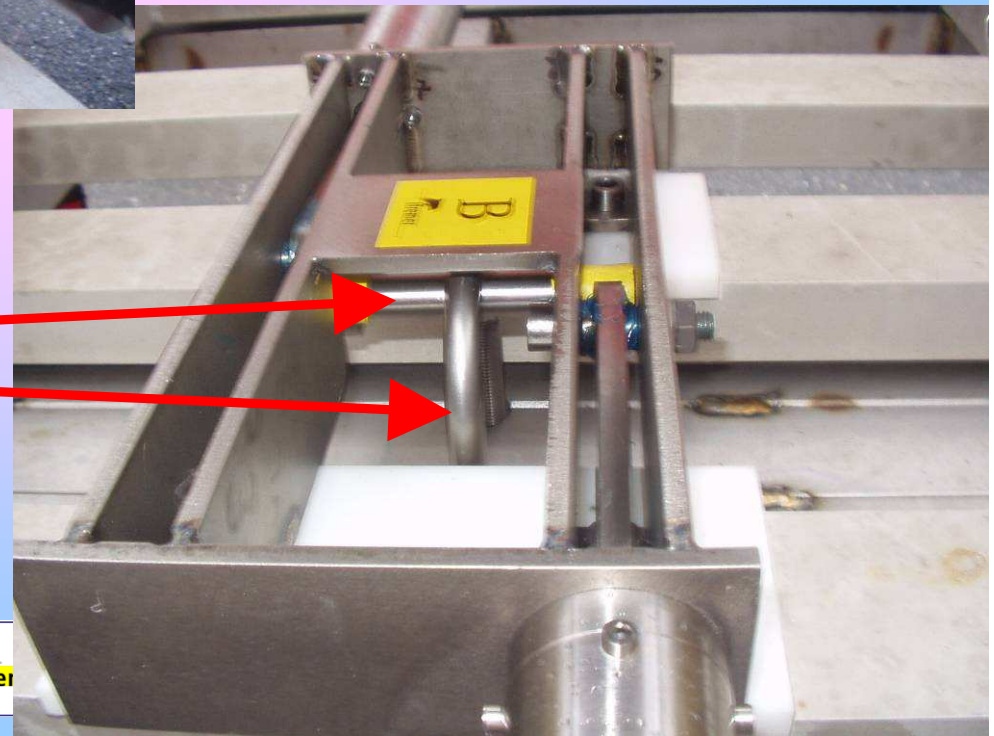






**2 x Titanium release**

**Stirrup and axis :  
mounting weight/frame**

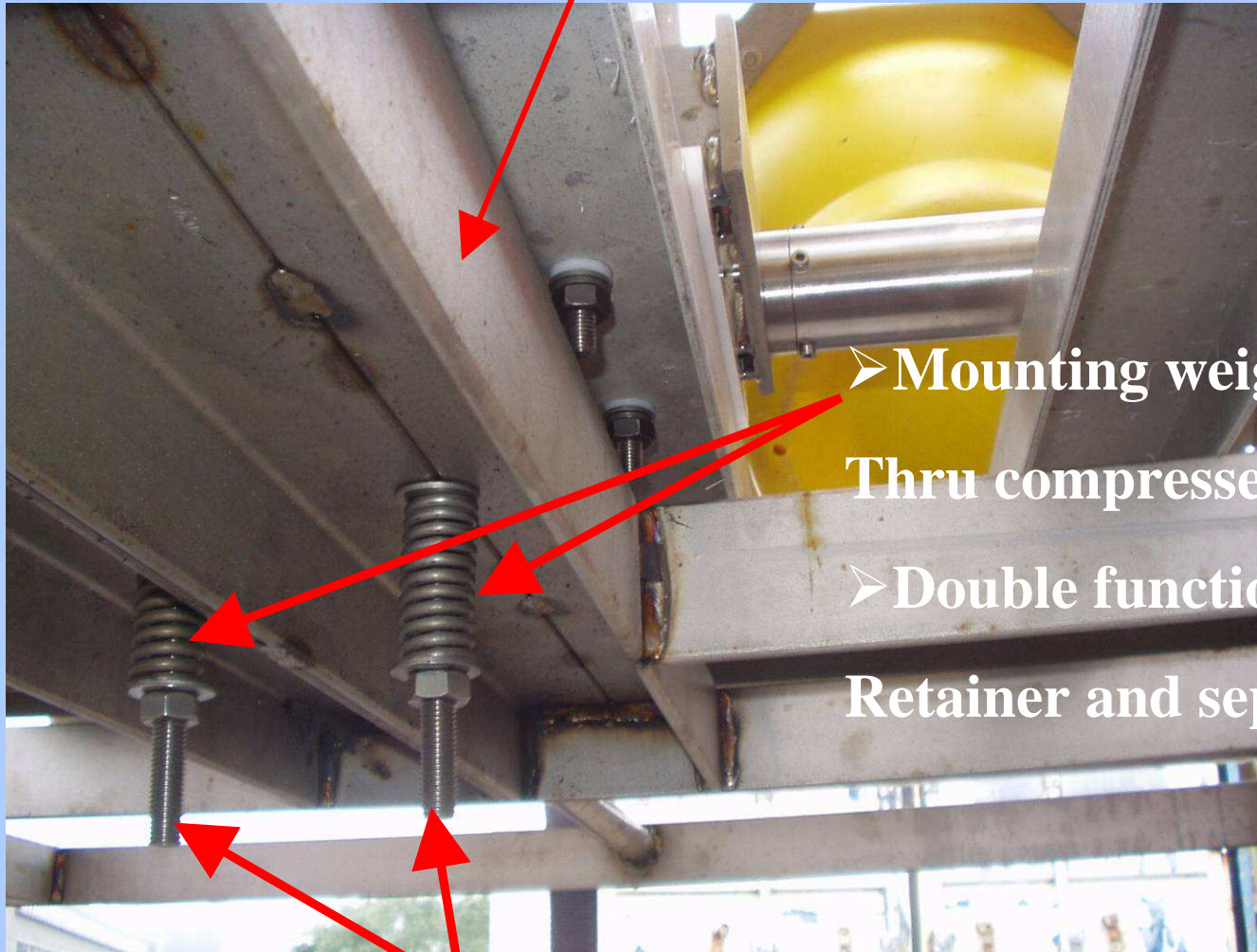


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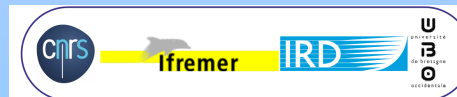
**Weight**



- Mounting weight / frame  
Thru compressed springs
- Double function :  
Retainer and separation

**Stirrup**

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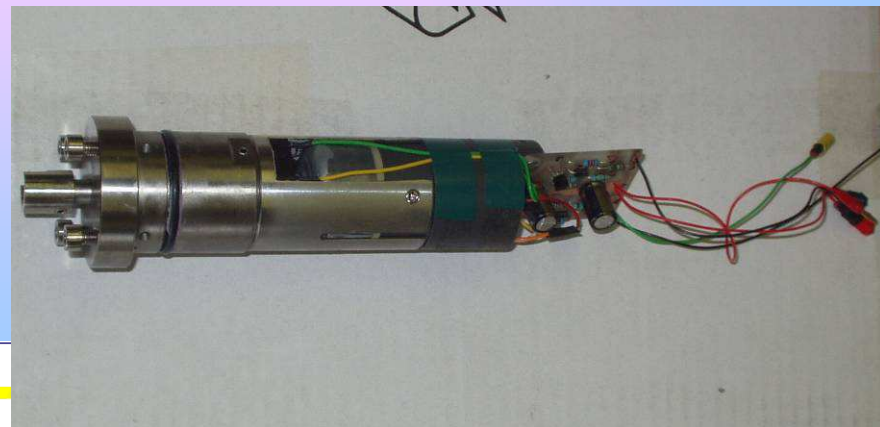


## In house small release



- IXBlue AR9 acoustic controller
- Nautilus glass sphere 13"
- Titanium container TA6V
- Pressure 600 bars
- Buoyancy +30 N
- Release load 120 kg

- Maxon gear motor
- Powered by acoustic controller



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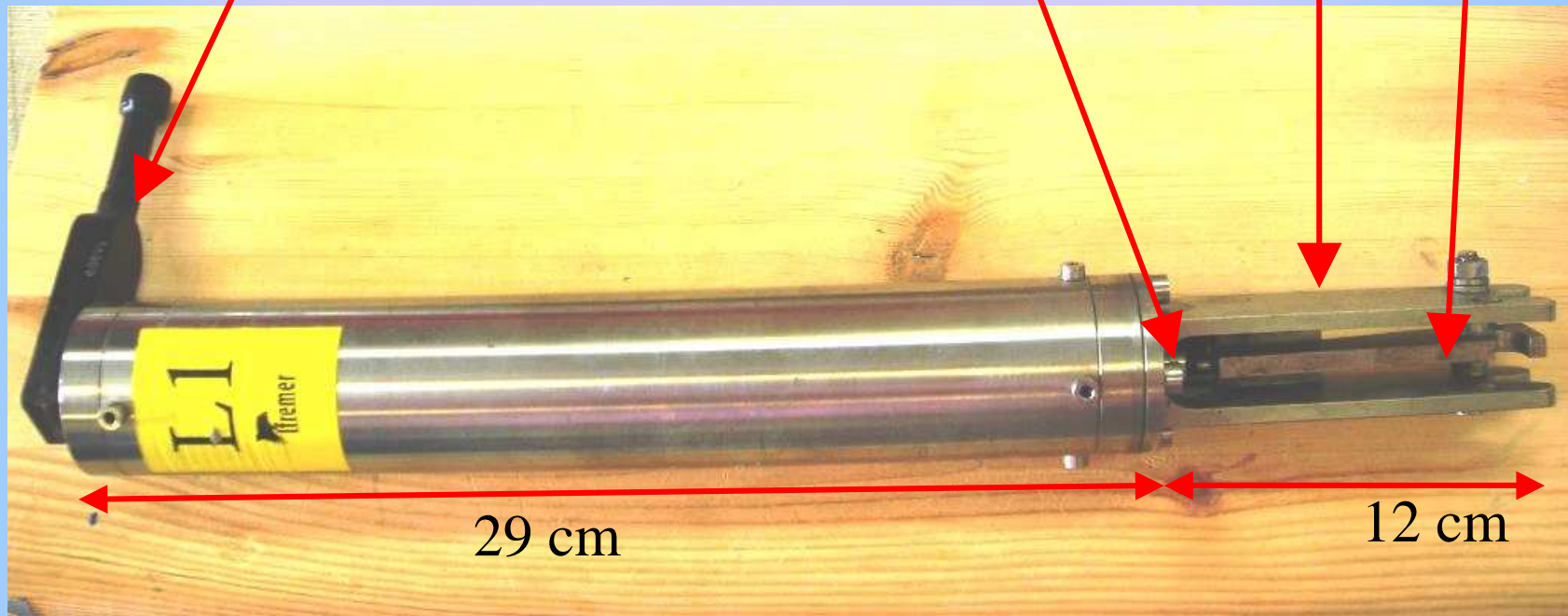


Connexion : power, release  
command, execution return

Release socket

Pivoting arm

clevis



## Applications



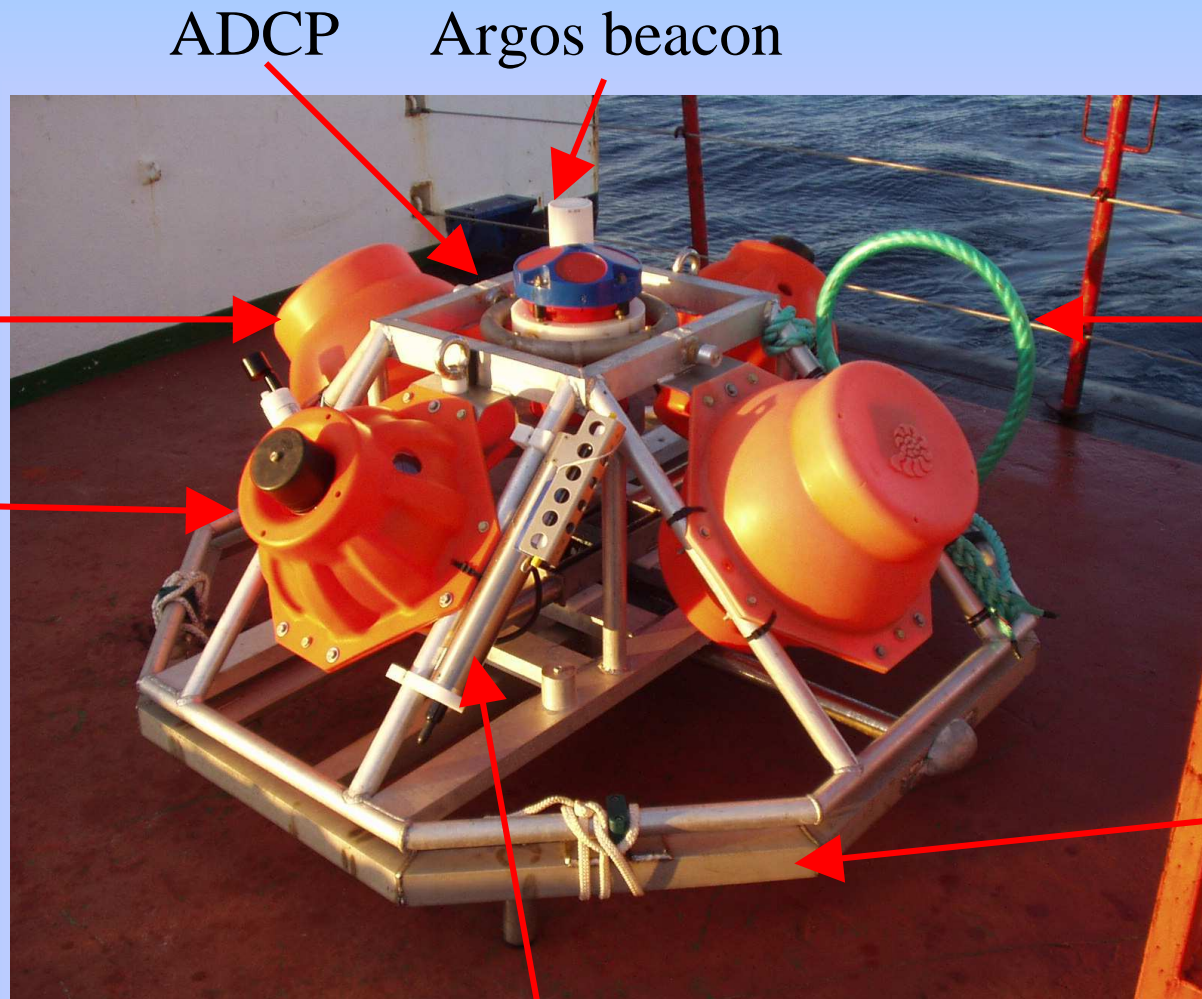
- Drifting instrumented float to monitor mud avalanches in submarine canyons : loosely weighted to be moved by a mudslide
- OBS : lowtop version
- Release on pressure or time for freefall instruments
- ...

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## Frame with ADCP 300/600 kHz



ADCP

Argos beacon

Floats

Recovery rope

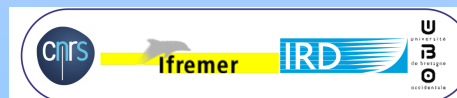
Acoustic controller

Weight  
~100kg

SBE37 P, T, C sensors

In air weight ~350 kg

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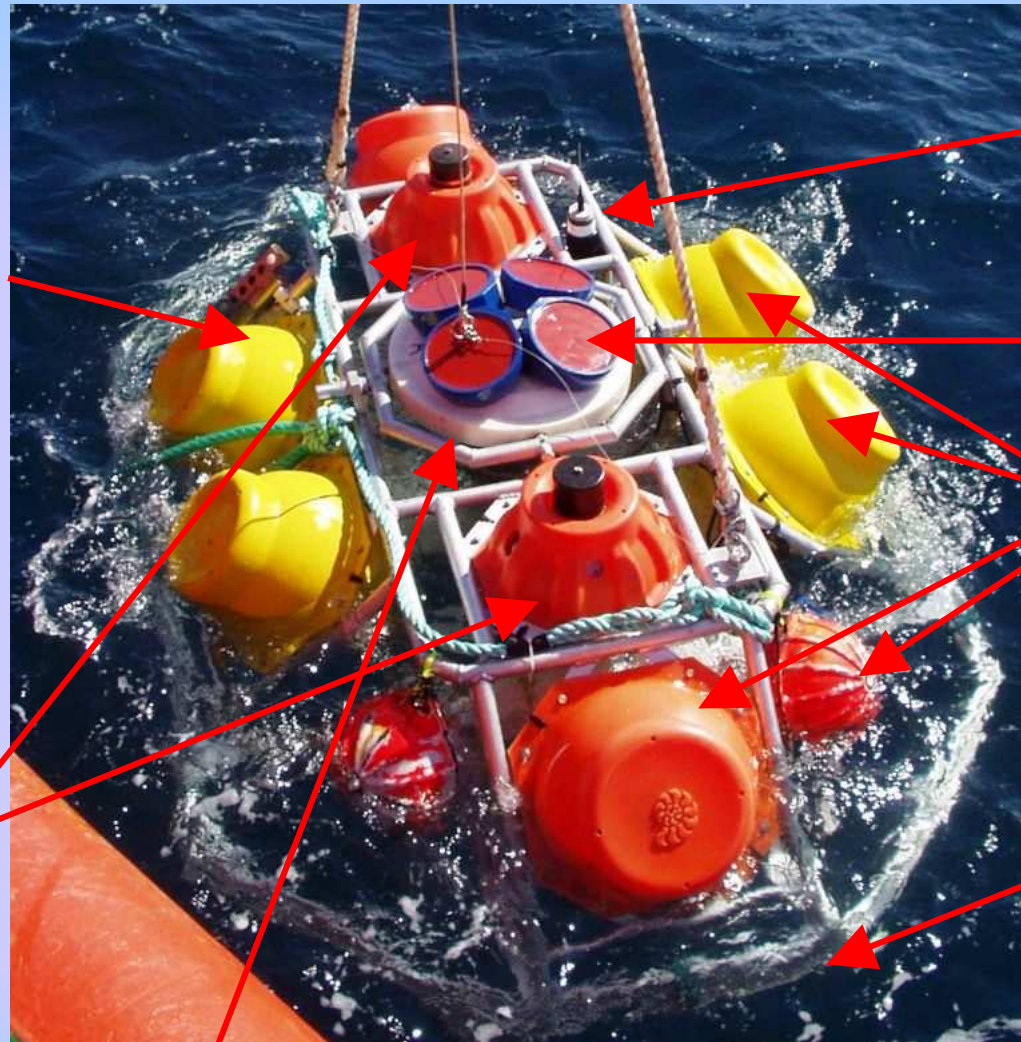




# Frame for ADCP 75/150 kHz

SBE37  
P, T, C sensors

Acoustic  
controller



Argos

ADCP

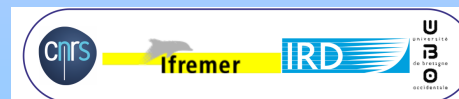
Buyoancy

Weight ~120  
kg

Gimbal

In air weight ~450 kg

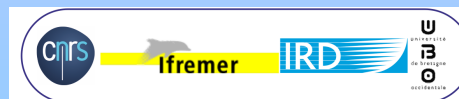
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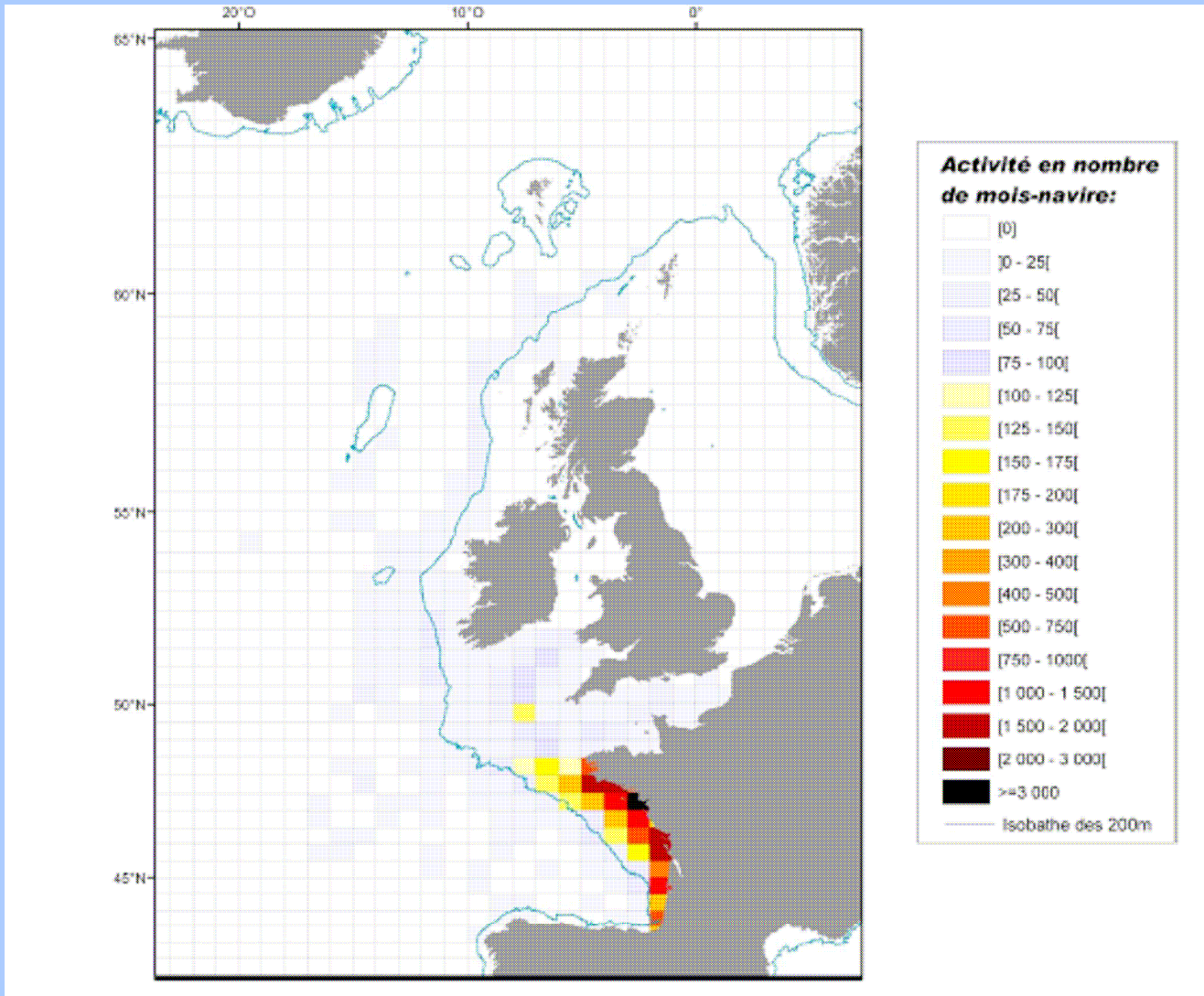




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# Deployments assessment

	Deploy (#)	Recov (#)	Trawl (#)	Length (month)	ADCP (month)	SBE (month)	Comments
WH 300	17	12	5	135	128	131	
WH 150	7	4	3	62	46	62	1 ADCP flowded due to trawling 1 ADCP stopped due to corrosion on connector
WH 75	11	9	2	98	89	90	1 ADCP flowded due to corrosion on connector 1 SBE37 flowded due to trawling Lost 2 acoustic transducers
<b>Total</b>	<b>35</b>	<b>25</b>	<b>10</b>	<b>295</b>	<b>263</b>	<b>283</b>	
<b>Percent</b>		<b>71</b>	<b>29</b>		<b>89</b>	<b>96</b>	

## Key points

**Mudding**

Change weight design : add foots

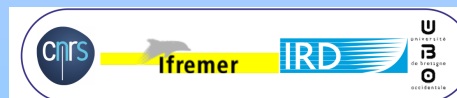
**Transducer**

Protective grid. Setting the sphere upside down

**Trawling**

??????????? / Communicate ?

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# Conclusions

- Robustness
- Easy to deploy
- Instruments stability and verticality
- Autonomy
- From shallow to deep water : limited by instruments pressure ranges
- Alternative to mooring lines
- Small releases
- Extension with pop-up buoys : SYREDOMY

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