Hybrid Efficiency versus Optimized Conventional Installations

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Thanks to the European Union for funding the HYbrid MARine (HYMAR) project

Serial and parallel:





Non SMO Marine Diesel Engine be [g/kWh]



STEYRMOTORS





C ESP

Initial HYMAR assumptions:

- Engine within 5% of peak efficiency, i.e.
 230/0.95 = 242 g/kWh
- 90% generator electrical efficiency, i.e.
 242/0.9 = 269 g/kWh
- 90% electric machine + controller efficiency, i.e.
 269/0.9 = 299 g/kWh
- 85% TPPL efficiency, i.e. 299/0.85 = 352 g/kWh (lithium-ion would be 90+% efficient)



Boat speed (knots)

C ESP



RATING ; 38.0 kw / 3000 rpm





Electric machine + controller efficiency





Courtesy BluWav & © Nigel Calder & ESP







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Percentages versus liters:

- The percentage fuel savings at low speeds can be high (e.g. >50% at 3.25 knots) trending towards 100% (e.g. elimination of dockside idling)
- The absolute savings are low (e.g. 0.5 l/h at 3.25 knots)
- The percentage fuel losses at higher speeds may be relatively low (e.g. 18% at 7.5 knots)
- The absolute losses are relatively high (e.g. 1.3 l/h at 7.5 knots)
- In any application with sustained periods of operation above the cross-over speed, the losses will outweigh the gains for a net loss of fuel efficiency

Energy displacement:

- The assumption so far has been that all energy for propulsion comes from an engine
- This is necessarily so for the conventional system but not the hybrid
- The hybrid can significantly alter the efficiency equation by incorporating other sources:
 - Shorepower
 - Renewables (solar and wind)
 - Regeneration on sailboats
 - Fuel cells
- Even if the hybrid is less efficient when its energy comes from the generator, it can be more efficient overall – e.g. Chevy 'Volt'/Opel 'Ampera' drivers average 111 mpg

The limits of energy displacement:

- The duty cycle of boats is radically different to that of cars...
- Shorepower and regeneration are *absolutely* limited by battery capacity; it takes a lot of batteries to get even a 20 mile range *at less than ½ power...*
- Solar and wind are *relatively* limited by battery capacity
- The relatively high loads of even a modest propulsion demand will rapidly exceed the capability of solar and wind, and/or deplete battery banks

Serial versus parallel

- A serial system must have enough electric power for the worst-case situation
- A parallel system only needs enough power to maneuver in harbor
- The powerful motor in a serial system will result in the inefficient area of operation migrating into harbor maneuvering and other low-speed, low power (e.g. motorsailing) applications
- The smaller motor in the parallel system will be more efficient to lower boat speeds
- The parallel system always includes the battery losses whereas the serial does not when in diesel-electric mode

Serial versus parallel:

- The parallel system captures all the efficiency benefits below the 'cross-over' speed without paying any of the penalties above it
- Both systems eliminate dockside idling, enable pollutionfree harbors, and consolidate engine run hours
- The parallel system requires far less battery capacity
- The parallel system can exploit non-engine energy sources just as well as the serial
- The bottom line: with either system, it will be extremely difficult to beat the efficiency of a well optimized conventional installation in any application that involves sustained operation at, or above, 'cruising' speeds