ACTIVE HEAVE COMPENSATION

UNOLS East Coast Winch Pool

Purpose

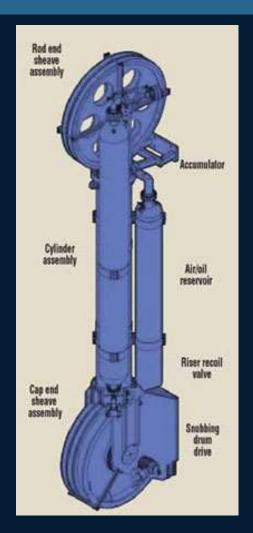
Why

- Reduce Package Movement
 - ROV Docking
 - Steady Sampling
- Remove Slack Conditions
- Alleviate Snap Loading
- Lessens Package Kiting

Methods of Compensation

Slack Tensioner

- Limited Range
 - +- 3.5 meters
- Multiple Sheaves
- ComplicatedMaintenance
- Complex Set Up
- Difficult Running



Example



Bobbing Crane



- Limited Motion
 - **-** +-1.25 meters
- □ Fixed Installation
- Complicates Wire Path

No Example



Active Heave Compensation

- Electric and Hydraulic
- Expensive MRU
- High Accuracy
- Ship Survey



Example: Industry



Example: In ECWP Shop



Example: JASON AHC Off



Example: JASON AHC On



Typical Factors

Expected

- Perfect Survey
- Centimeter Accuracy
- □ 60 M/Min

Actual

- Approximate Survey
- Half Meter Accuracy
- □ 100 M/Min

Considerations

- Elevated velocities from the winch drum through the sheave train
- Package velocity approximately 0 M/S
- Low tension variation

The MRU

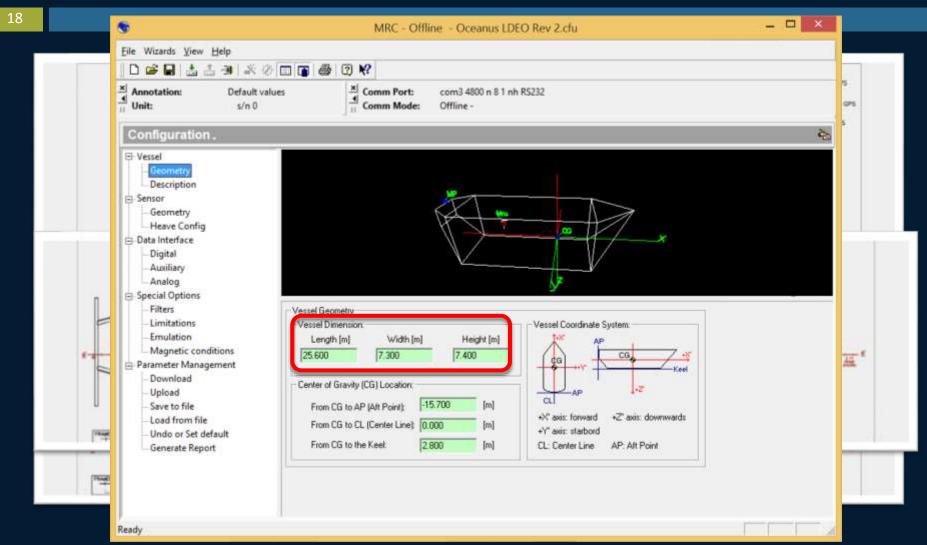
Expensive Piece of Kit

- □ \$30K
- Calibration
- Placement
- Other Uses
- Out Put

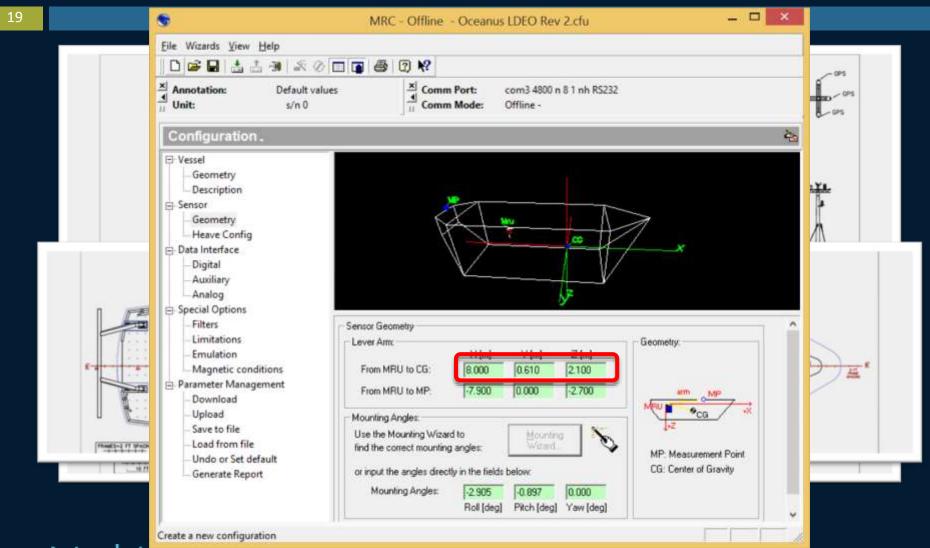


The Survey

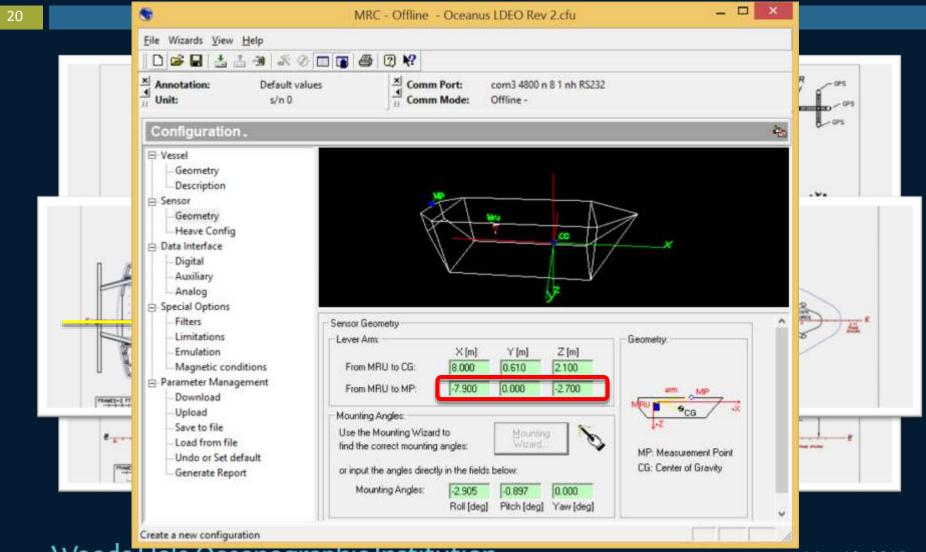
Ship CG



MRU Placement



Overboarding Point



Woods Hole Oceanographic Institution

Method

- Simple Survey
- Calculation of Movement Around CG
- Lever Arms

Innovations

MRU Distribution



- Centralize the MRU
- Single "perfect" survey
- Allow for multiple overboarding points
- MRU stays on ship
- Allows for use with portable systems
- Possible lag

New MRUs

- Kongsberg Series 5
- MultipleOverboarding Points



New Concept



- Heave Sensor
- Small
- No Survey
- Place on any Sheave

Questions