The Ocean Exploration Trust (OET) based in New London, CT owns and operates the E/V NAUTILUS
Its initial partner was the Center for Ocean Exploration at GSO/URI with its Inner Space Center.
Ocean Exploration Trust
Board of Directors presently includes

- **(URI/GSO)** Graduate School of Oceanography, University of Rhode Island, Center for Ocean Exploration, Director Dr. Robert Ballard
- **(WHOI)** Woods Hole Oceanographic Institution, Director Dr. Mark Abbott
- **(UNH/CCOM)** University of New Hampshire, Center for Coastal and Ocean Mapping, Director Dr. Larry Mayer
- **(USM/GCRL)** University of the Southern Mississippi, Gulf Coast Research Laboratory, Director Dr. Monty Graham
Prior to Acquiring the E/V NAUTILUS we operated Mobile Systems from 1984 - 2008
From 2000-2008 we operated the ARGUS/HERCULES ROV system on a broad range of vessels.
OET and its Partners with funding from OET and NOAA’s Office of Ocean Exploration and Research (OER) are presently building three new Mobile Systems to Support Multiple Ship Classes from the Global-Class to the new RCRVs at OET’s Homeport at AltaSea within the Port of Los Angeles’ major containerized shipping facility in San Pedro, California within a 1/3rd acre indoor shore facility next to the E/V NAUTILUS.
Components Come to All Three

- Autonomous Surface Vessel (UNH)
- Dual Frequency Side-scan Sonar (OER)
- Mobile high bandwidth satellite system (OET)
- USBL Vehicle Tracking System (OER)
- Vehicle Support van (OET)
- Elevators (OET)
- Launch and Recovery Crane (OER)
UNH’s Autonomous Surface Vessel (ASV)
6,000-meter Edgetech Dual Frequency Side-scan Sonar System in Multiple Configurations
OET’s High Bandwidth Satellite Systems
Portable Direct Drive Winch with 7,000-meter cable and Launch and Recovery Crane
OET’s Vehicle Support Van
USBL Tracking System
OET Elevators
2,000-meter Mobile System

- Wet Lab/Single van Command Center (OET)
- WHOI’s NEREID Hybrid ROV/AUV
- USM’s EAGLE RAY AUV
- USM’s MOLA MOLA AUV
• 4,000-meter system
  – HERCULES I ROV (OET)
  – ARGUS I imaging vehicle either in support of HERCULES I or alone (OET)
  – Two-van Command Center (OER)
  – SENTRY AUV (WHOI)
• 6,000-meter system
  – LITTLE HERC ROV (OET) and HERCULES II
  – ARGUS II (OER) imaging vehicle either in support of ROVs or alone
  – Two-van Command Center (OER)
  – SENTRY AUV (WHOI)