# NDSF Jason Update

# 2026 Schedule

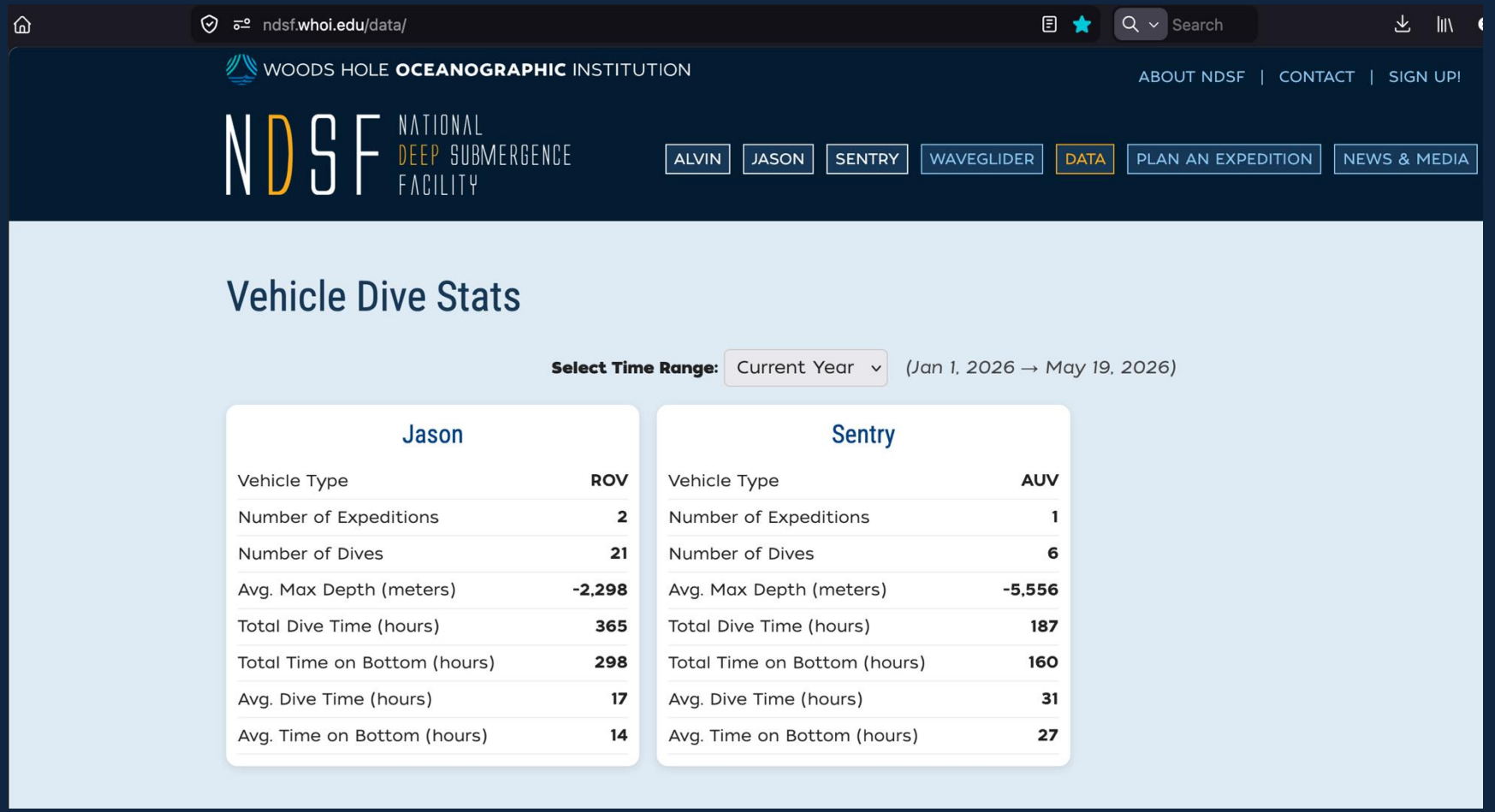
- ✓ Chave+Rapid Response, AT50-45, EPR
  - ✓ + Endurance Energy deployment
- ✓ Beinart, TN-452, Vent Snail Adaptation/Lau Basin
  - ✓ + Endurance Energy deployment
- Kelley, RR2607, Axial/OOI-RCA
- Wilcock, RR2608, Axial/COSZO
- Chadwick, RR2609, Axial
- Zumberge, RR2615, Kilauea GNSS-A
- Potemra, RR2616, ACO

Approx. 1/3rd of scheduled days completed

# Statistics and Metadata Access

## ndsf.whoi.edu/data

- Updated shortly after each expedition
- Historical reference
- Jason/Sentry/Alvin
- Jason:
  - Sealog
  - Config Pics
  - Dive Metadata



# Logistics

Logistics planning has been impacted by:

- delayed vessel schedule rollouts
- lack of significant logistics infrastructure in developing countries
- ocean freight carrier dependency


Appreciate the dedicated support from ships/operators/schedulers and our logistics team!

# Staffing

- The (necessary) staggered publishing of 2026 schedules, along with last-minute changes to mobilizations, has made it difficult to get our staffing rolled out for the whole year at once
- The mROV development has also partially contributed to the situation
- Acknowledge this has made it challenging for PI's to finalize their own staffing plans in some cases, we are working as quickly as possible to resolve

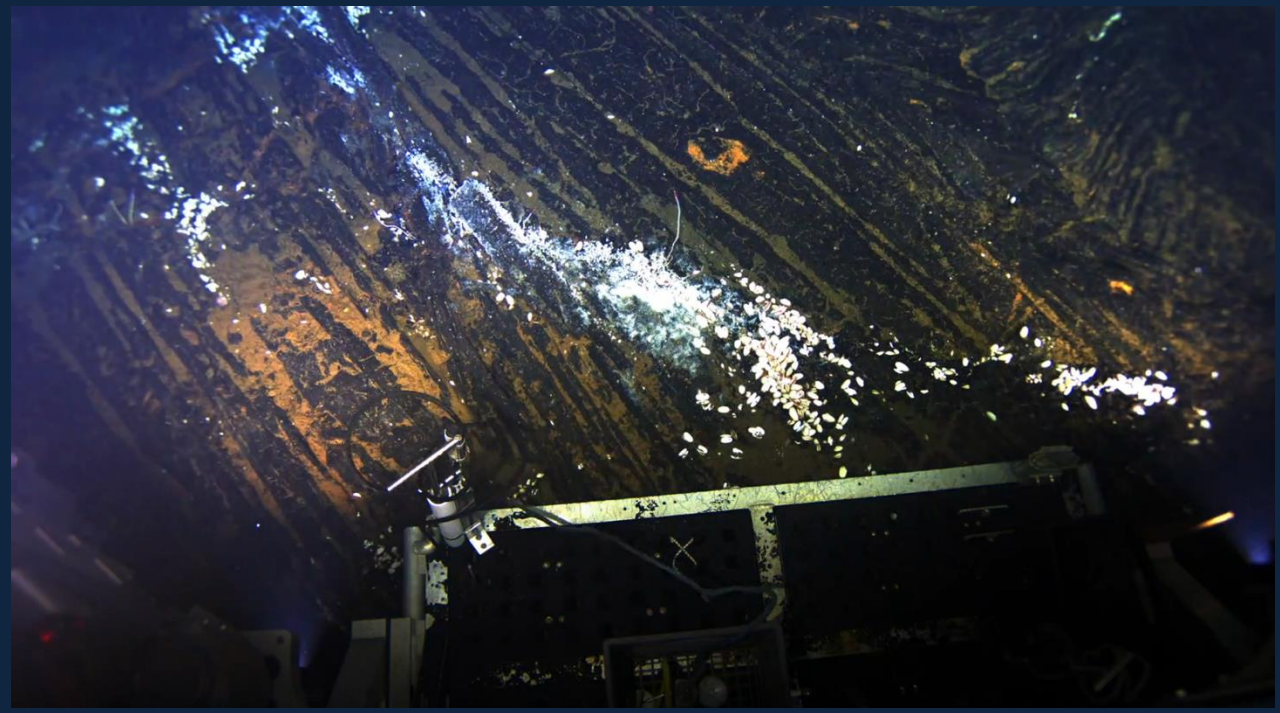
# System Issues

- Several unexpected vehicle power losses due to failing HV GFM card
- Blueview sonar failure, appears to be partially flooded
- Jason DP integration with TGT did not work, relied on calling moves to the bridge
- Swing arm function impacted by worn bushings and related components

# Fixed Focus Camera Selected

**Marine Imaging Technologies**

- 24MP Fixed Focus
- Vehicle powered
- Ethernet comms
- Live view
- Intervalometer functionality
- Full resolution images captured internally or with topside software

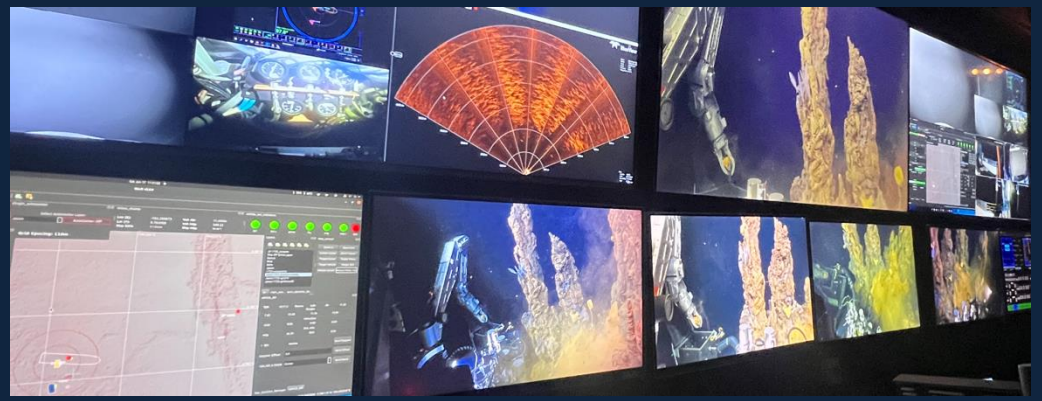


**Moving Forward**

- Purchase in the works
- One camera plus cabling
- Possibly ready for late 2026 ops

# Upcoming 2026/2027

- Heavy lift sled maintenance prior to Kelley
- Control van Jetway
  - Evaluation by vendor being scheduled soon to determine if permanently damaged or repairable
- Major RAPP Winch maintenance will start after Chadwick
  - Full tear down/mechanical overhaul
- Vehicle MP in winter 2027
  - Planning in development
- 2027 Schedule
  - Jason team is preparing to support interleaved Jason and mROV operations



# JASON Personnel

**Fred Denton** – *Mechanical Engineer*
**Adam Ensminger** – *Electrical Engineer*
**Mario Fernandez** – *Expedition Leader/Mechanical Eng.*
**Chris Hadalton** – *Electrical Engineer*
**Peter Hall** – *Mechanic*
**Tim Joyce** – *Software Engineer*
**Chris Judge** – *Electrical/Expedition Leader*
**Kevin Kavanagh** – *Logistics*
**Ben Pietro** – *Logistics*
**Akel Kevis-Sterling** – *Expedition Leader*
**Scotty McCue** – *Data Engineer*
**Jeremy Paulus** – *Mechanical Engineer*
**James Pelowski** – *Data Engineer*
**Hugh Popenoe** – *Electrical Engineer*
**Amanda Sutherland** – *Mechanical Engineer/Data*
**Ben Tradd** – *Expedition Leader/Mechanical*
**Tom Trudel** – *Mechanical Engineer*
**Isaac Vandor** – *Software Engineer*
**Korey Verhein** – *Electrical Engineer*
**Ronnie Whims** – *Mechanic*


**mROV Support**

Jason Engineering and technical personnel continue supporting mROV development, which includes upcoming sea trials

# ndsf.whoi.edu/jason

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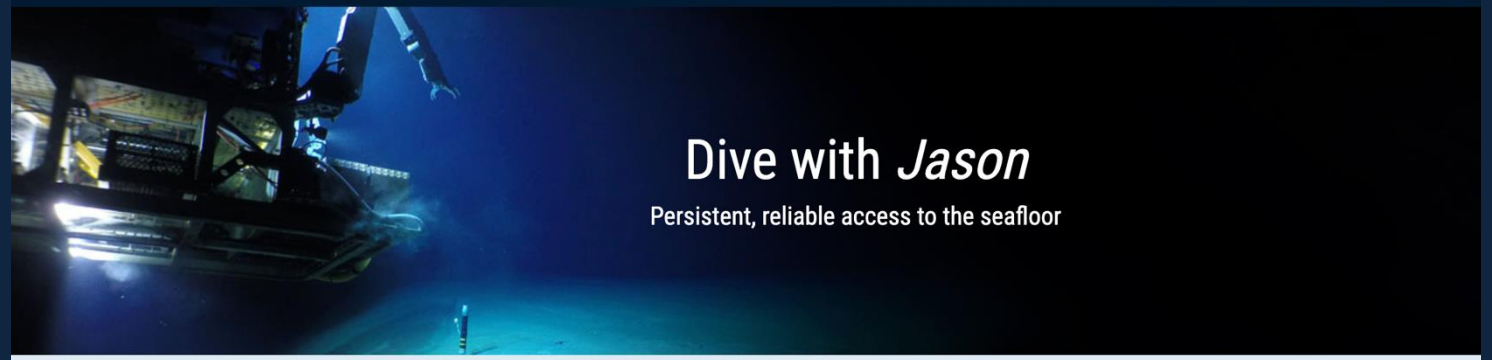
ALVIN | JASON | SENTRY | WAVEGLIDER | DATA | PLAN AN EXPEDITION | NEWS & MEDIA



## Dive with *Jason*

Persistent, reliable access to the seafloor

### ROV JASON

- Team
- Capabilities
- Specifications
- Systems, Sensors & Sampling
- User Supplied Equipment
- Data

## ROV *Jason*

*Jason* is a remotely operated vehicle (ROV) system designed and built by WHOI's Deep Submergence Laboratory and funded by the National Science Foundation to allow scientists to have access to the seafloor without leaving the deck of a ship.

*Jason* can be operated as either a two-body or a single-body ROV, depending on mission requirements. A 10-kilometer (6-mile) reinforced fiber-optic cable delivers electrical power and commands from the ship to the vehicle, which then returns data and live video imagery throughout a multi-day dive.

### Jason Dive Stats

| | |
|---|---|
| Vehicle Type | ROV |
| Number of Expeditions | 154 |
| Number of Dives | 1,760 |
| Avg. Max Depth (meters) | -1,748 |
| Total Dive Time (hours) | 25,111 |
| Total Time on Bottom (hours) | 20,326 |

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