

# Plankton NET Interface for Mocness Systems – Next Steps



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# Acknowledgements



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# Plankton NET Interface for Mocness Systems

## Topics:

- Recap of the Development of the PKI system
  - Current Operational Status
    - Strobe system
      - Future goals and the next steps

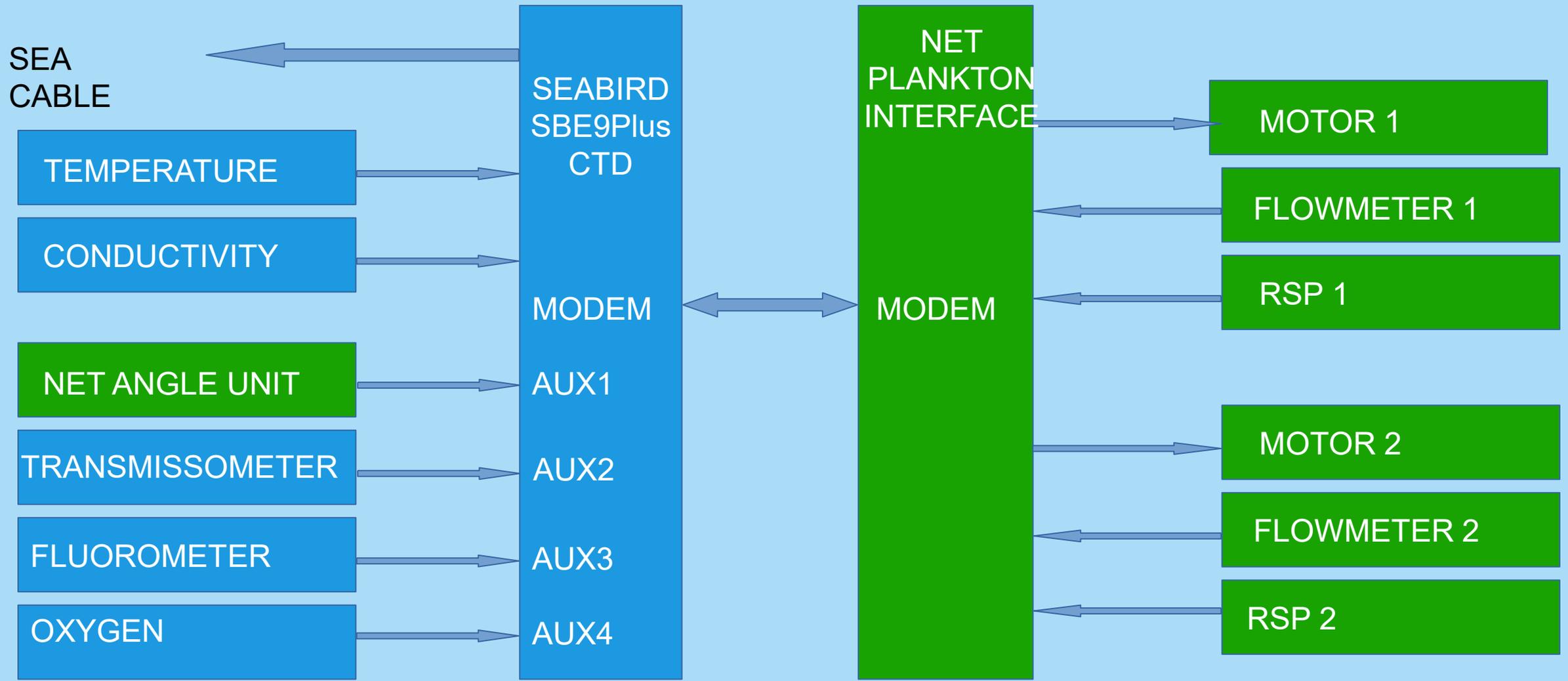
# Plankton Net Interface – What is it?



The Plankton Net Interface allows the ability to use the Seabird SBE9Plus CTD on Moccness Systems in place of the original CTD and controller unit.

- Acquires and stores Real-time data from the CTD.
- Controls the NET motor and trips the Plankton nets.
- Acquires and stores Flow Meter data and computes volumes.
- Acquires and stores data from the GPS via RS232 or UDP ports.
- □ isplays data on strip charts and XY plots.
- Acquired data can be played back and displayed.
- Data is stored in the Seabird data format.

# PKI SYSTEM BLOCK DIAGRAM



The idea of being able to use a SBE9Plus CTD on the Mocness has been around for many years.

In 2015, development began on the software and hardware. An early prototype was completed.

April 2016 - The prototype was tested on a cruise on the R/V Oceanus and used again on the R/V Sikuliaq in January/February 2017. The reports that came back from these cruises were positive overall but reported that there were a few issues with the software. The detailed information that they sent proved instrumental in helping to fix these issues.

# Early Development Timeline



In 2017, NSF granted funding to allow for the fabrication of new PKI and net angle units to be distributed to six UNOLS institutions.

The cases were made out of 7075 Aluminum And Black anodized.

These units were built and shipped out in late 2017 and early 2018.

PKI Unit  
15.75" L  
5.0" W  
16.0 Lbs



Net Angle Unit  
5.0" L  
4.0" W  
5.5 Lbs

Throughout 2018, these PKI systems were used successfully on many Mocness deployments. The institutions that received them had reported back that the PKI unit that they received was working very well and appreciated how improved this system was over the original one.

However, in early 2019 the technicians at Oregon State had noticed that excessive pitting and blisters had formed on the outside of the pressure housings of both the PKI unit and the NET Angle sensor.

This pitting problem was reported back to STS on February 2019. Pitting was subsequently found on some of the units sent to other institutions. Shortly after receiving these reports STS sent out a recall notice on February 8, 2019 to all UNOLS Mocness users to return these units back to SIO/STS for evaluation/repair as soon as possible.

# Pitting Problems



The SIO MPL machine shop investigated the cause of the pitting and suggested that there may have been something wrong with the batch of 7075 material that the cases were made from. 7075 is an aluminum/zinc alloy and if the zinc component had migrated to the surface due to either faulty material or improper heat treating or anodizing then it could result in pitting.

Using a new batch of material the SIO machine shop built new housings to replace the ones that were not repairable. These housings were completed in about five months.

All PKI Units and NET Angle units have been returned to their owners by the end of June 2019.

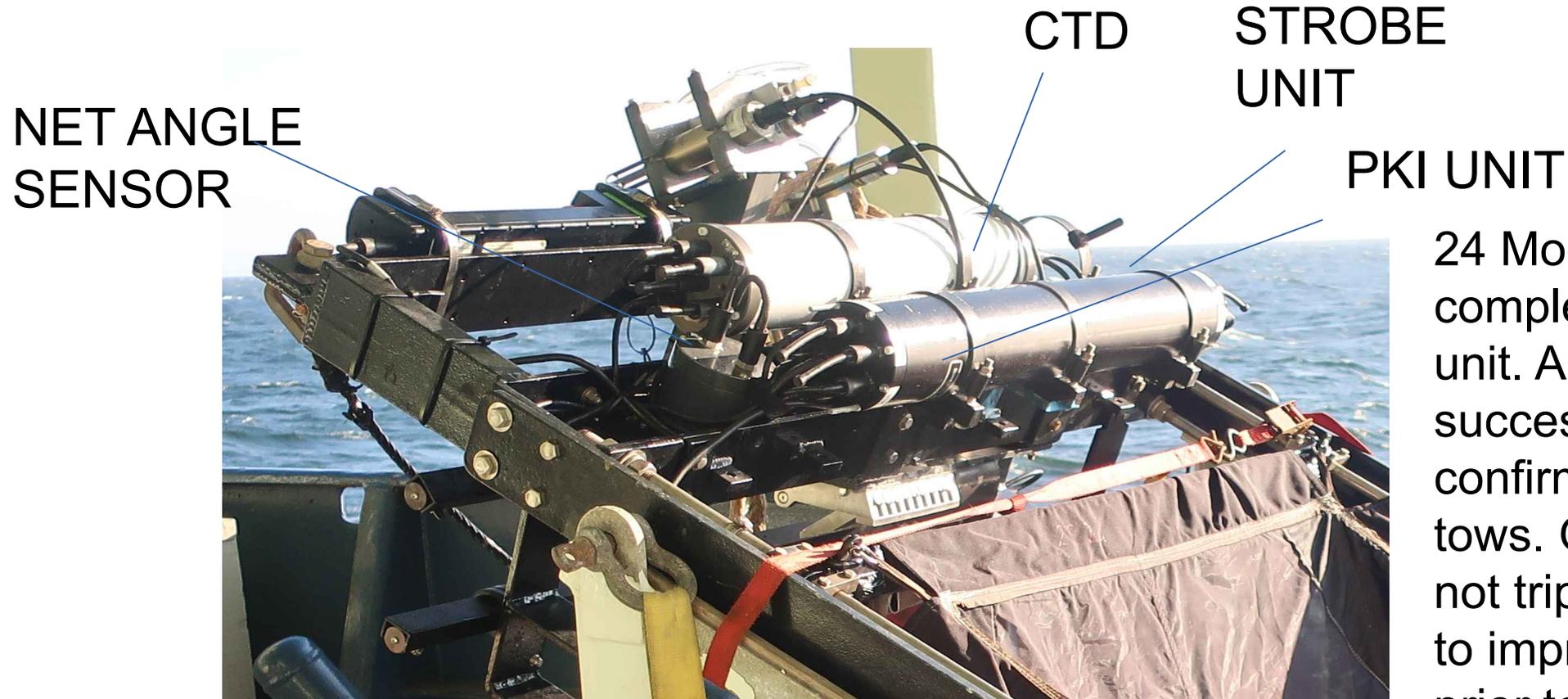
Two more sets of PKI and Net Angle units were built in 2019. There are currently a total of 8 sets of production units at this time not counting the original prototype.

1. United States Antarctic Program
2. University of Alaska Fairbanks R/V Sikuliaq
3. Bermuda Institute of Ocean Sciences
4. Oregon State University
5. University of Rhode Island
6. University of Hawaii
7. Scripps Institution of Oceanography
8. University of Miami

# Current Status



The SIO 1M2 10 NET mocness with the PKI Unit was recently used in August 2019 on the R/V Atlantis. The cruise was part of the CCE-LTER Network. (California Current Ecosystem - Long Term Ecological Research).



24 Mocness tows were completed using the PKI unit. All Nets were successfully tripped and confirmed on 23 of the tows. On the tow that did not trip/confirm it was due to improper Net preparation prior to the tow.

# Current Status



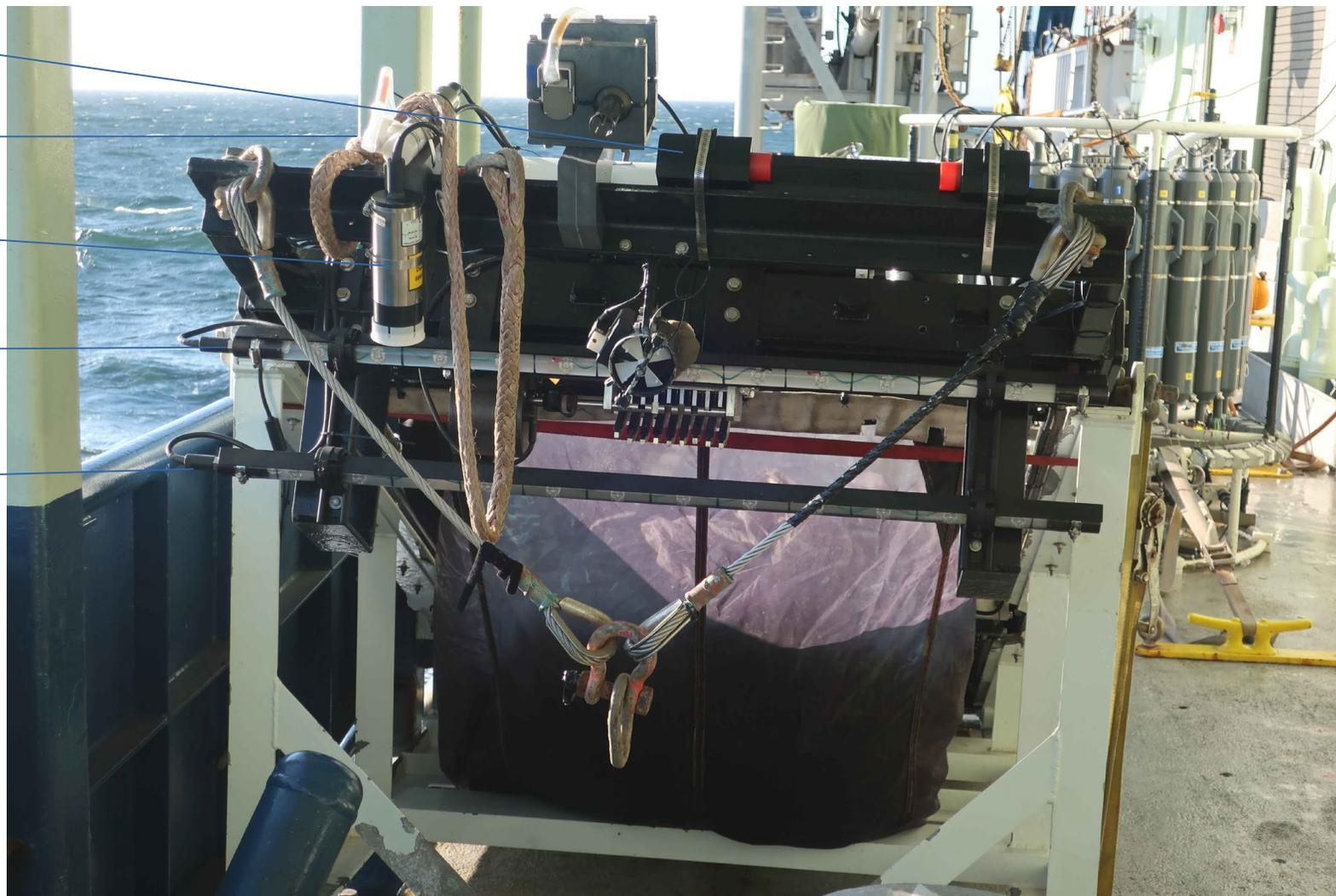
Transmissometer

Oxygen

Fluorometer

STROBE LED BAR #1

STROBE LED BAR #2



# Screenshot 1 – Setup Page

Get\_Setup.vi

Setup\_Acquisition

General

Shipname

Cruise

LeadingName

TOW #

Net Size(m)

Primary Flow Cal

Secondary Flow Cal

AdvanceC 0

AdvanceC 1

MotorSteps

Net Size 2(m)

CTD\_Port

Com Port

Baud

MCNTRL\_Port

Com Port

Baud

NMEA\_Ports

Com Port

Baud

Port\_Type

UDP Port

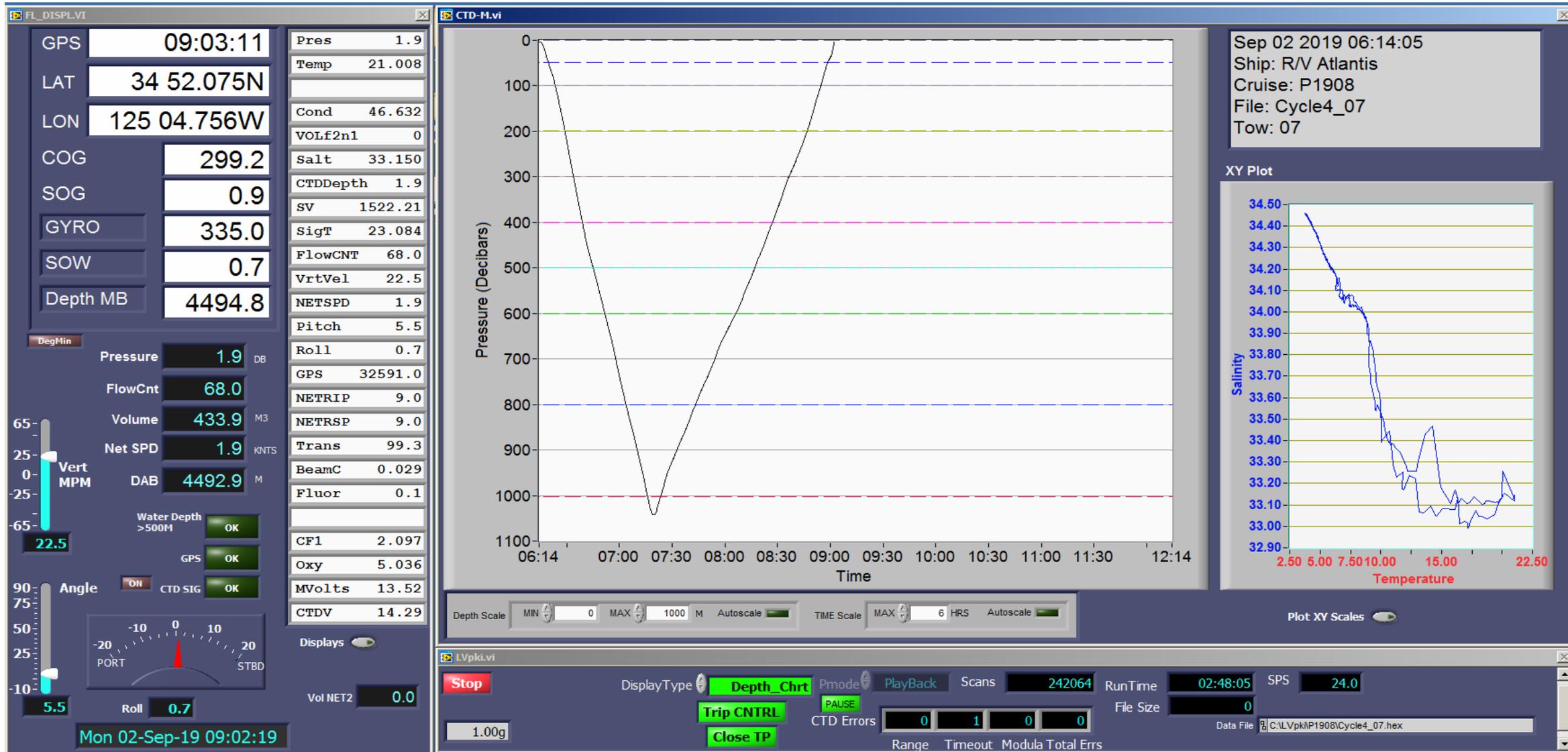
Make FM2 the primary Flowmeter

XMLCon file

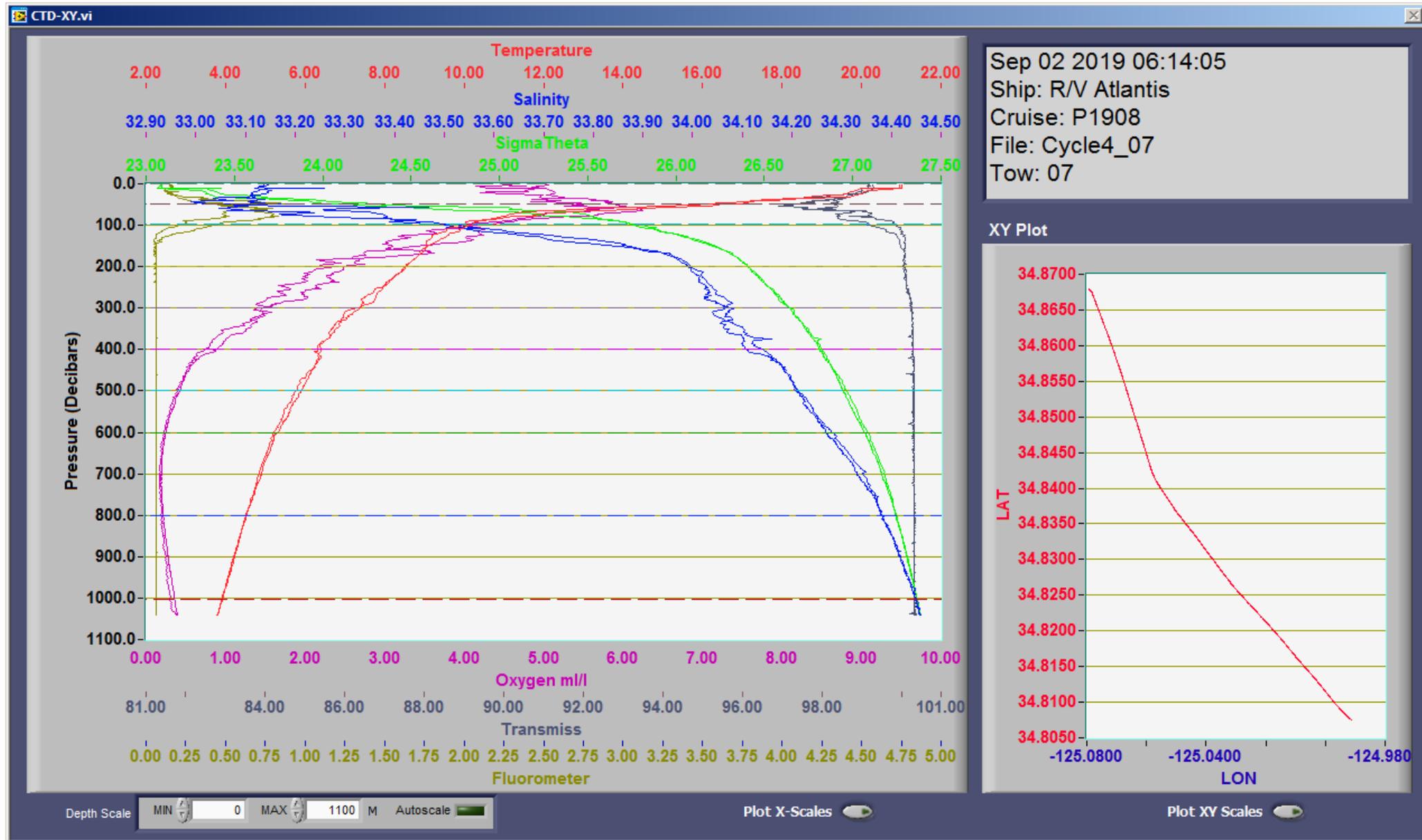
Press OK when ready

\* Playback mode parameters are changed by editing the header field in the HEX file and/or changing coefficients in the xmlcon file.  
\* The only control on this page that is used in playback mode is the XMLcon file selector.

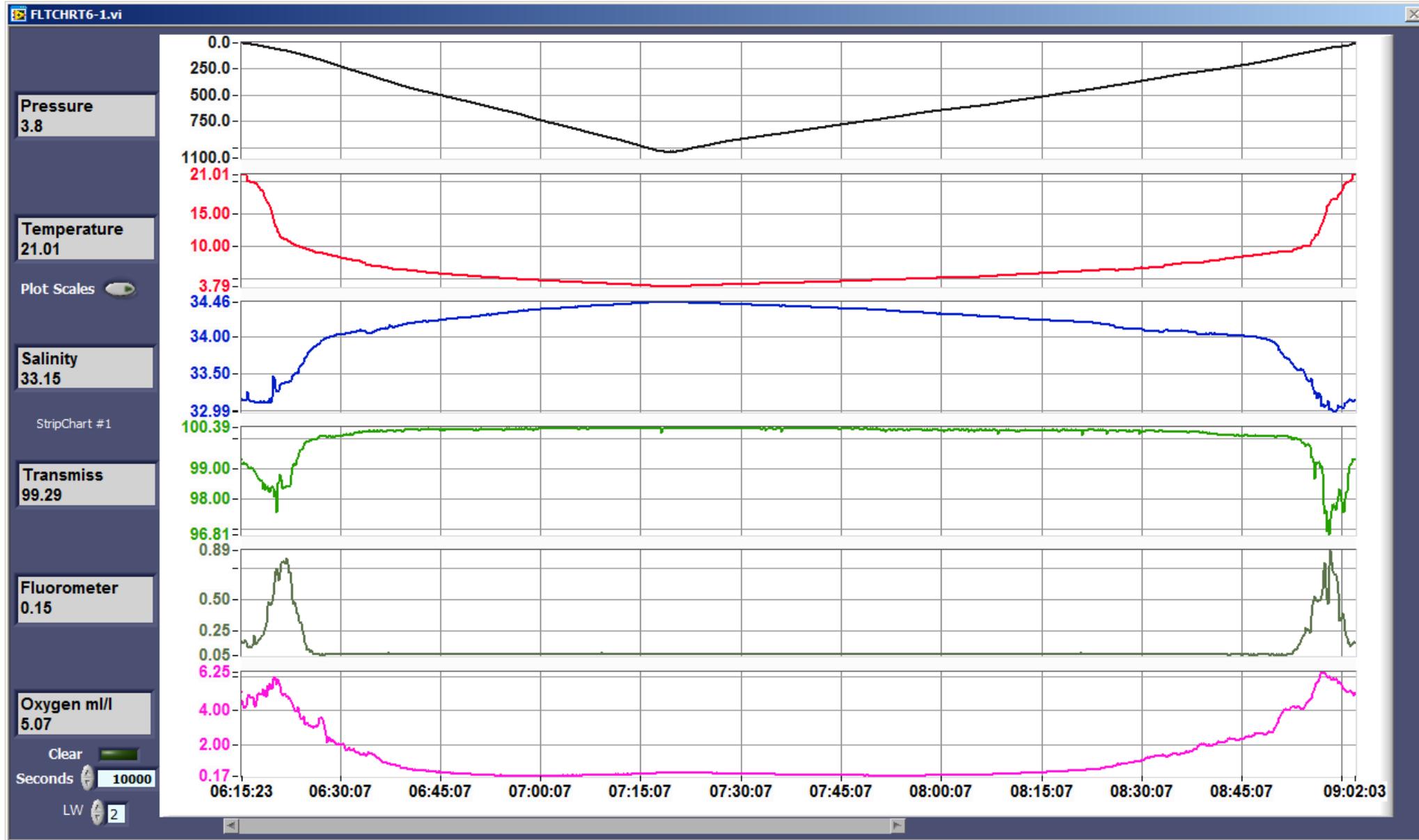
# Screenshot 2 – Mocness Depth Plot



# Screenshot 3 Multi XY Plot



# Screenshot 4 - StripCharts



# Screenshot 5 – NET Trip Page



### TRIP CONTROL

	Trip RSP	Date	Time	Pres	Net Angle	Flow Cnts	Volume
1	<input checked="" type="checkbox"/>	190902	072320	1002.5	36.3	825	4333.0
2	<input checked="" type="checkbox"/>	190902	074317	801.5	45.4	424	1918.0
3	<input checked="" type="checkbox"/>	190902	080619	600.5	44.1	552	2567.4
4	<input checked="" type="checkbox"/>	190902	081657	500.3	43.6	266	1245.8
5	<input checked="" type="checkbox"/>	190902	082709	400.1	43.0	258	1211.8
6	<input checked="" type="checkbox"/>	190902	083627	300.1	44.2	244	1123.9
7	<input checked="" type="checkbox"/>	190902	084649	200.1	40.0	258	1277.2
8	<input checked="" type="checkbox"/>	190902	085435	99.8	40.6	196	958.7
9	<input checked="" type="checkbox"/>	190902	085827	49.3	43.1	102	482.7
10	<input type="checkbox"/>			0.0	0.0	0	0.0

Trip Count	<input type="text" value="9"/>	Flow Cnts	<input type="text" value="68"/>	Flow Cnts2	<input type="text" value="0"/>	Motor Volts	<input type="text" value="13.522"/>
Confirms	<input type="text" value="9"/>	VOL	<input type="text" value="433.9"/>	VOL 2	<input type="text" value="0.0"/>	CTD Volts	<input type="text" value="14.288"/>
Modem Data	<input type="text" value="68,0,9,9,0,1252,1323,0,0,0,178"/>			CNF TIME	<input type="text" value="11.958"/>		

Modem Serial Port Status

FM2 Primary

Strobe Box

Reset Trip Count

Reset Flow Count

Single Step Motor

MANUAL CONFIRM

TRIP CNT++

TRIP CNT--

CNFM CNT++

CNFM CNT--

UNLOCK

Trip in Progress

Motor ON

RSP

Trip NET

STROBE OFF

Interval ms

PulseWidth ms

Intensity %

STROBE STR\_Volts

In 1993 Doug Sameoto and Alex Herman of the Bedford Institute of Oceanography published their work on strobe-related increases in euphausiid catches (Sameoto et al 1993, Herman et al 1993).

Dr Peter Wiebe of the Woods Hole Oceanographic Institution had developed a strobe system for the Mocness (Wiebe et al 2013).

In 2017 Dr Mark Ohman of the Scripps Institution of Oceanography had acquired funding to purchase a similar strobe system. However, he was unable to get a working system in time to meet his schedule so he contacted STS to see if we could design and build a new strobe system in the required time frame.

In 2018/2019 the STS strobe system was built and designed to either interface through the PKI unit or to function independently as a stand alone system.

## **Overall size and shape:**

2 LED BARS 1M long mounted above the top of the net opening directly in front of the MOCNESS

## **Number of LEDS:**

Each Light bar has 12 LED sets, each set with 3 adjacent LEDS.  
Total of 36LEDs per Light bar.

## **Wavelength range**

Peak LED output approximately 505 nm

## **Strobe interval**

100 -10,000 ms

## **Strobe pulse width**

2 - 100 ms.

## **Software controls**

On/Off, Flash Interval, Pulse width, Flash intensity (ranging from 0 to 100%)

During the August 2019 CCE-LTER cruise on the Atlantis the strobe was turned on for 9 tows to 1000M depth. This is the first cruise that this new strobe unit was used and it worked flawlessly throughout the cruise. During night tows the strobe was clearly visible to 30 Meters below the surface. During this cruise the strobe brightness was set at 50% with a pulse width of 40ms at a 1HZ pulse rate.

Dr. Mark Ohman said that while it is too early to report on the effects that the strobe had in regards to the amount of bio-volume as compared to when the strobe is off he did say that on several tows with the strobe on that they were able to capture three vampire squid. No vampire squid were captured when the strobe was off. The strobe was turned on for 9 tows and it was turned off for 15 tows.

# Future goals and the next steps



Now that the PKI units have been completed and used successfully we can consider what we would like to accomplish to ensure future support for Mocness systems.

Some topics for discussion:

1. Flowmeters – What alternatives are available?
2. Motors
3. Response switch reliability issues.
4. Providing for backup systems.

Bill Fanning had recently reported that Mocness Flowmeters are still available and can still be purchased from the manufacturer for \$2750 EA.

Possible Alternative sources:

TSK Tsurumi-Seiki Co.,Ltd - (Approximate price: \$1250-\$1550)

This is the same flowmeter but does not have the magnetic reed switch interface. This would need to be added after purchase.

General Oceanics Model 2031H (Approximate price: \$652)

This flowmeter has a hall effect sensor and needs a 3-wire connection. It is possible to accommodate it in the PKI unit.

Valeport Model 001 (Approximate price: \$2900)

This flowmeter does have a magnetic reed switch interface.

Mocness Motor units can probably be purchased from the manufacturer. Scott Ferguson had reported that he did try to get a quote but received no response. Scott searched around and found that the internal stepper motor is not available from anyplace else.

One of the weaknesses of this motor is that it has very little torque. Occasionally when the tension on the net lanyards becomes a bit too tight then the motor cannot turn.

This particular motor has a two wire connection that is not found on any standard stepper motor that is in use today. One alternative is to replace the motor with a standard bipolar stepper and install a stepper interface inside the PKI unit. The bipolar steppers have plenty of torque. In addition it is possible to incorporate an encoder onto the stepper in order to send back the motor position information back to the ship. This would indicate a positive confirmation that the motor turned.

The RSP switch configuration has historically been a weak point as it did not always confirm a net trip even in cases where the net did trip.

However, in the past couple of years, many users had reported that since they have started using the PKI system then they have had fewer issues with getting a confirmation signal after a net trip.

In cases when the RSP does not confirm then it is most often due to the RSP switch assembly slipping up or down on the support rod. This can be corrected by tightening the securing bolts as tight as possible to reduce slippage problems. The switch should be located as high as possible on the bar and still able to confirm all nets. A slight downward angle on the switch lever has also been found to be helpful.

At this time we are still open to new ideas to improve the ability to confirm net trips.

# CONCLUSION



The STS Plankton Net Interface system has evolved over the past few years to one that can reliably accommodate the use of a seabird CTD on a Mocness system. We had a few hurdles with getting the pressure housing pitting issue resolved. In addition, the software had a few bugs in the beginning but thanks to the shipboard technicians who reported back on these issues the program was improved substantially and is now working very well. We can now move on to continue improving other components of the Mocness system such as the motor, flowmeter and confirmation sensor.



For more information Contact

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Latest software and documentation:

<ftp://somts.ucsd.edu/users/cmattson/Mocness/LVpki/>

Sources Cited:

Sameoto, D. D., N. Cochrane, and A. Herman 1993. Convergence of acoustic, optical, and net-catch estimates of euphausiid abundance: use of artificial light to reduce net avoidance. *Can. J. Fish. Aquat. Sci.* 50: 334-346.

Herman, A.W., Cochrane, N.A., Sameoto, D.D., 1993. Detection and abundance estimation of euphausiids using an optical plankton counter. *Marine Ecology Progress Series* 94, 165-173

2013 Wiebe, P.H., G.L. Lawson, A.C. Lavery, N.J. Copley, E. Horgan, and A. Bradley. 2013. Improved agreement of net and acoustical methods for surveying euphausiids by mitigating avoidance using a net based LED strobe light system. *ICES Journal of Marine Science.* (2013) 70(3): 650-664 doi:10.1093 /icesjms/fst005.