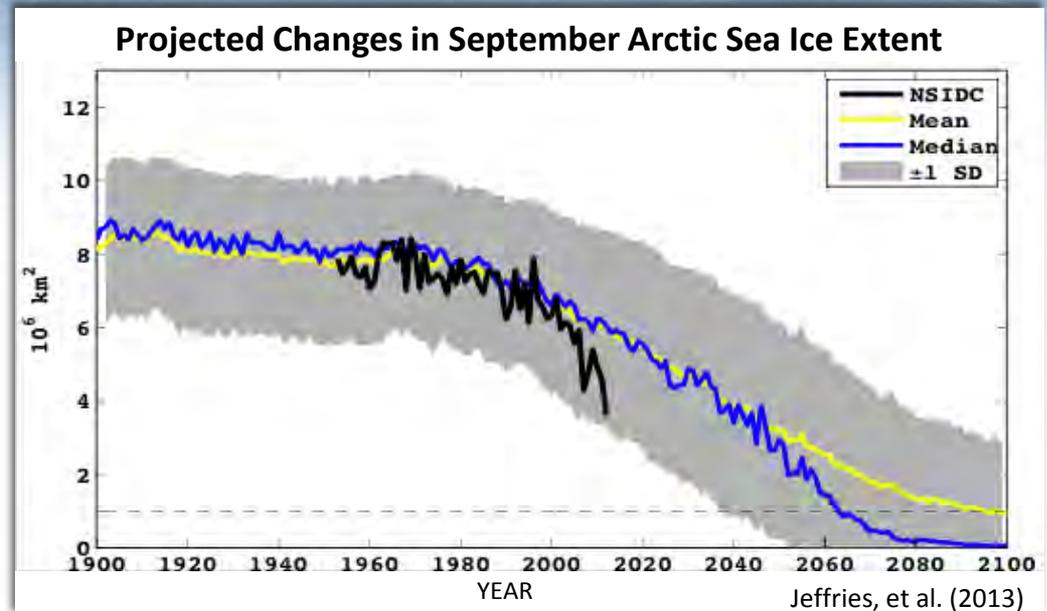
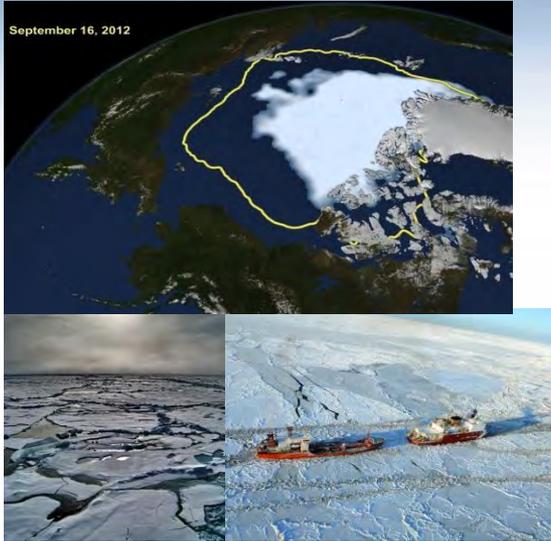




ONR Arctic Research Plans for AICC January 10, 2018

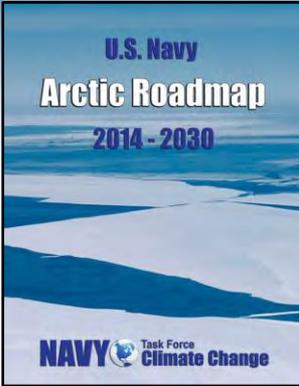
*Dr. Scott Harper
Arctic and Global Prediction Program
Ocean, Atmosphere and Space Research Division
Office of Naval Research
Email: Scott.L.Harper@navy.mil*

The Changing Arctic



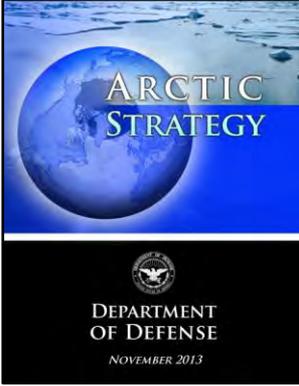
- How little sea ice will there be, and when will the key changes occur?
 - Need better prediction capability underpinned by basic research.
- How is the Arctic region as a whole going to be different?
 - Need research into how the entire Arctic environmental system functions.
- What does the Navy need to know to operate in the Arctic?
 - Need sustained observations and improved predictions of the state of the Arctic.
- How will the changing Arctic affect the rest of the earth, and vice-versa?
 - Need an Arctic environmental system model integrated within global prediction models

Emerging Arctic Requirements



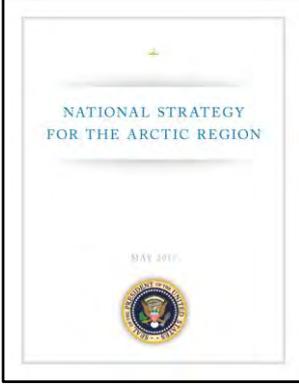
**U.S. Navy
Arctic Roadmap
2014 - 2030**

NAVY Task Force
Climate Change



**ARCTIC
STRATEGY**

DEPARTMENT
OF DEFENSE
NOVEMBER 2013



**NATIONAL STRATEGY
FOR THE ARCTIC REGION**

MAY 2015

Navy's Strategic Objectives for the Arctic Region

- Ensure U.S. Arctic sovereignty and provide homeland defense
- Provide ready naval forces to respond to crises and contingencies
- Preserve freedom of the seas
- Promote partnerships within the U.S. Government and international allies

SOURCES

- The United States Navy Arctic Roadmap for 2014 to 2030, February 2014
- National Strategy for the Arctic Region Implementation Plan, January 2014
- Department of Defense Arctic Strategy, November 2013
- COMSUBLANT/COMSUBPAC Arctic Requirements Letter, Ser N3/0644, 04 SEP 2013
- NORAD-USNORTHCOM FY18-22 S&T Integrated Priority List (STIPL)
- NORAD-USNORTHCOM Arctic Maritime Capability Requirements Study:
 - Phase 1 Final Technical Report, 15 OCT 2015
 - Appendix E, Non-releasable Material, 31 JUL 2015
- Classified Companion to the National Strategy for the Arctic Region, 2014
- N52 Arctic Engagement Plan Memo, 02 APR 2015
- NORAD-NORTHCOM Arctic Capabilities Based Assessment, May 2017

Develop a Framework of Observations and Modeling to Support Forecasting and Prediction of Sea Ice

Lead Agency: Department of Defense (Navy)

"increased certainty and accuracy of sea ice forecasts and predictions, and by showing improved understanding of feedback processes driving sea ice variability"



ONR Arctic Research Program

*To Better Understand and Predict the Arctic Environment
Program Initiated in FY2012*

Major Program Thrusts:

- Improved **Basic Physical Understanding** of the Arctic Environment
- **New technologies** to enable persistent Arctic observations
- Development of new fully-integrated **Arctic System Models**
- **Exploitation of Remote Sensing** for both Basic Understanding and to constrain the new Arctic System Models



Technology Development

An Arctic sensing system must be developed to provide persistent observations that can further scientific understanding, provide long-term monitoring, and help constrain the predictive numerical models.

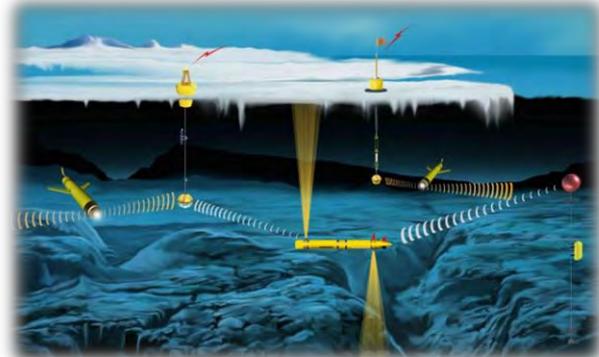
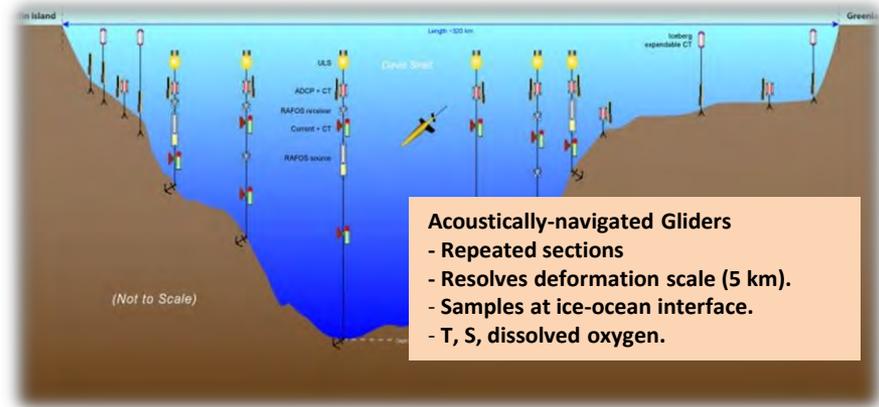
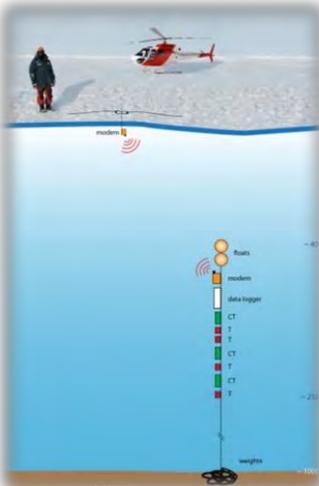
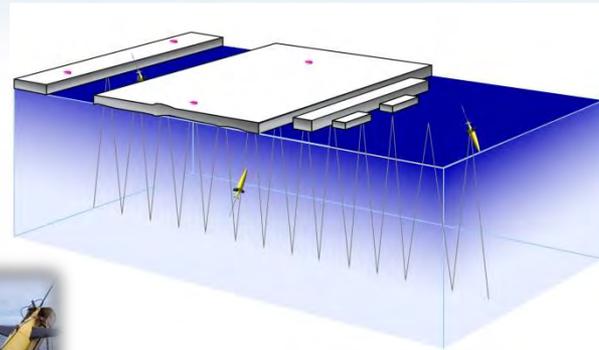
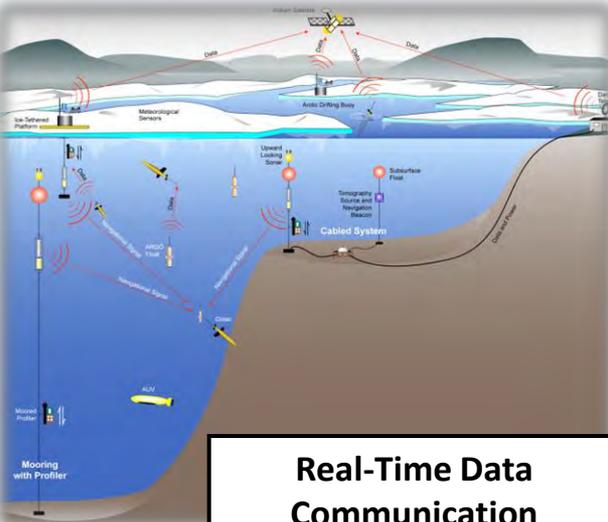
Autonomous platforms – Robust Sensors – Real-time Data Delivery – Key Environmental Variables

Novel Sensing Systems



Autonomous Platforms and Enabling Technologies

Real-Time Data Communication



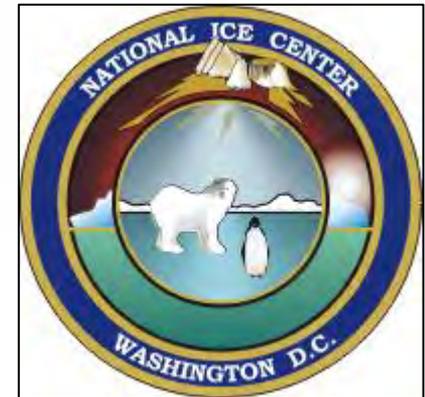
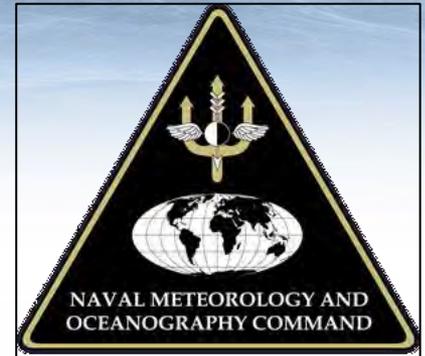
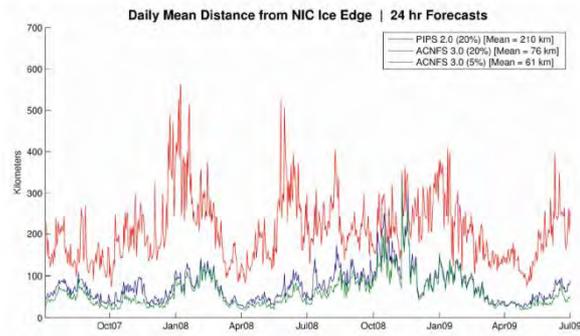
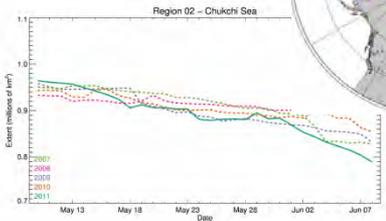
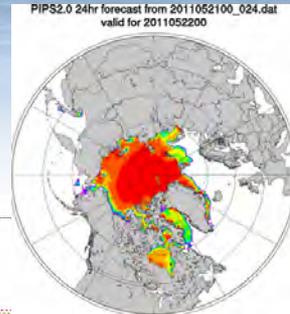
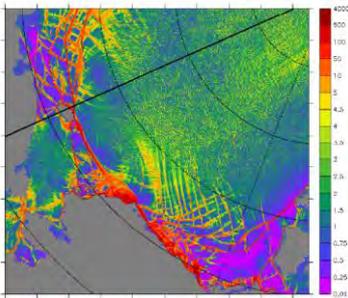
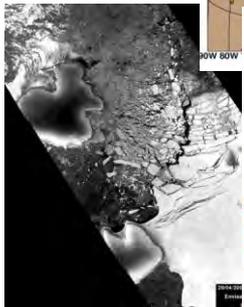
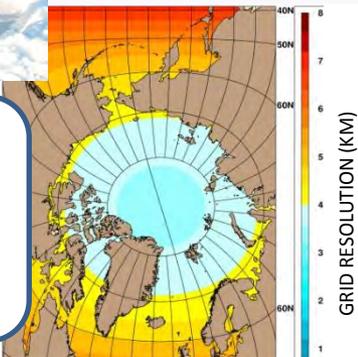


Development and Transition of Arctic Prediction Systems

Fieldwork to better understand key physical processes



Improved physics built into data-assimilating integrated models



Arctic Prediction System Development

Observing System Development

Validation and Verification

Testing, Prototyping and Experimentation

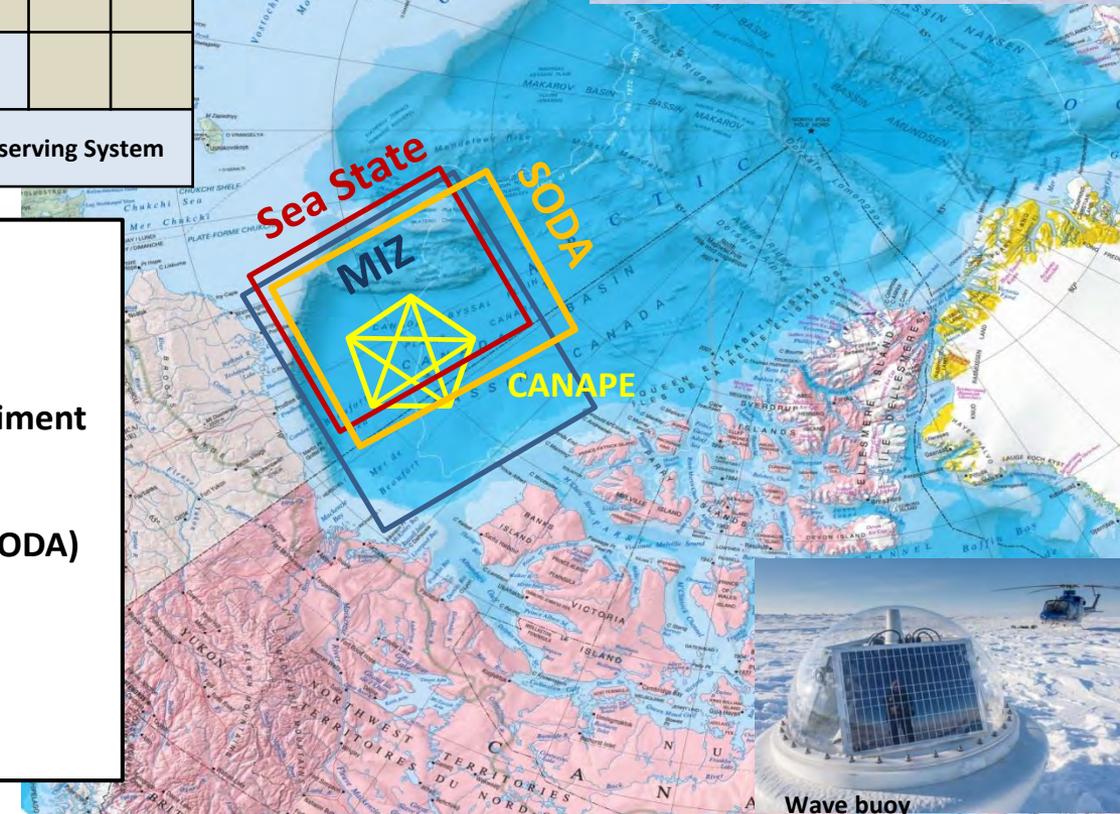
Transition to Operational Use

Transition to Operational Use



ONR Major Arctic Research Initiatives

2012	2013	2014	2015	2016	2017	2018	2019	2020	2021	2022	2023
ONR 'Core' Program, <i>Arctic and Global Prediction</i>											
Marginal Ice Zone DRI											
Waves and Sea State DRI											
CANAPE (acoustics)											
Stratified Ocean Dynamics DRI											
Sea Ice Dynamics Experiment											
Arctic Mobile Observing System											



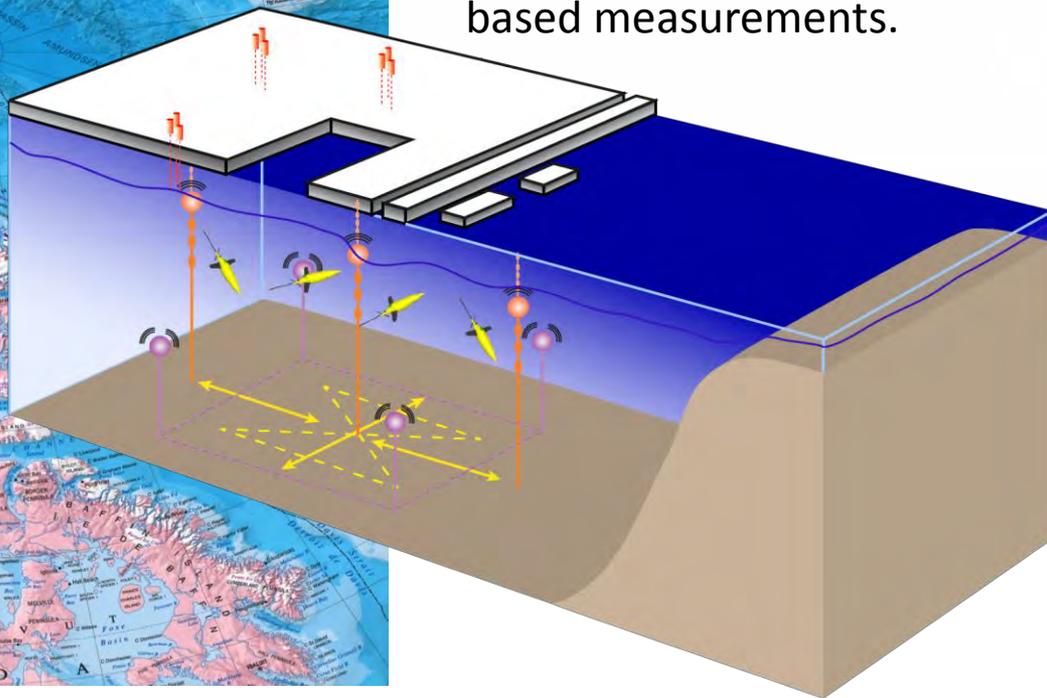
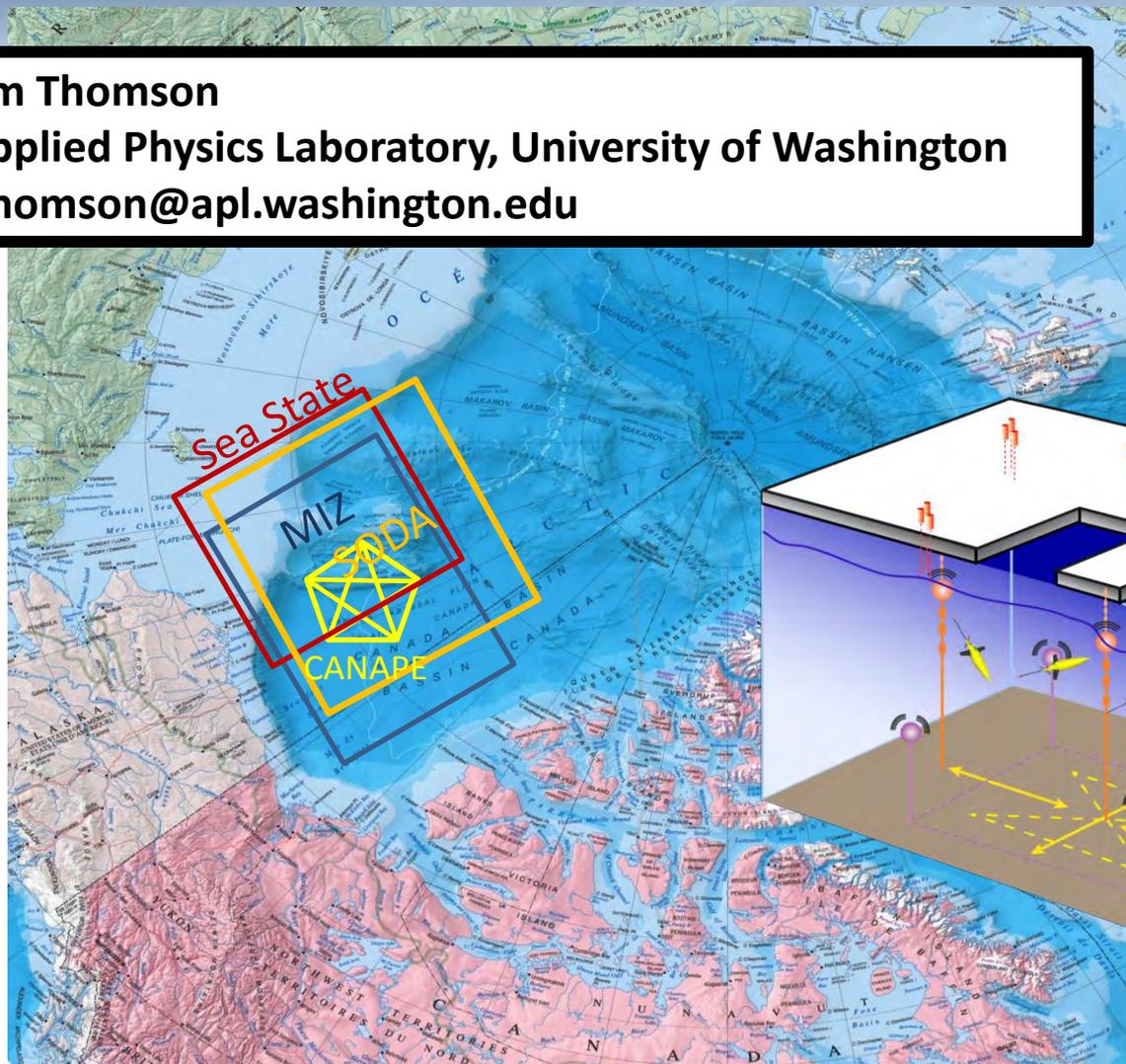
- **Marginal Ice Zone (MIZ) Initiative**
 - 2014 Field Program
- **Waves and Sea State Initiative**
 - 2015 Field Program
- **Canada Basin Acoustic Propagation Experiment (CANAPE)**
 - 2015, 2016-2017 Field Programs
- **Stratified Ocean Dynamics in the Arctic (SODA)**
 - 2017-2019 Field Programs
- **Sea Ice Dynamics Experiment (SIDEx)**
 - 2019-2020 Field Programs
- **Arctic Mobile Observing System (AMOS)**
 - 2020-2023 Field demonstrations



Stratified Ocean Dynamics in the Arctic (SODA)

Jim Thomson
Applied Physics Laboratory, University of Washington
jthomson@apl.washington.edu

- 2018-2019.
- Central Beaufort Sea.
- One year of autonomous sampling (moorings, gliders, ice-tethered sensors).
- Autumn service cruises, ship-based measurements.





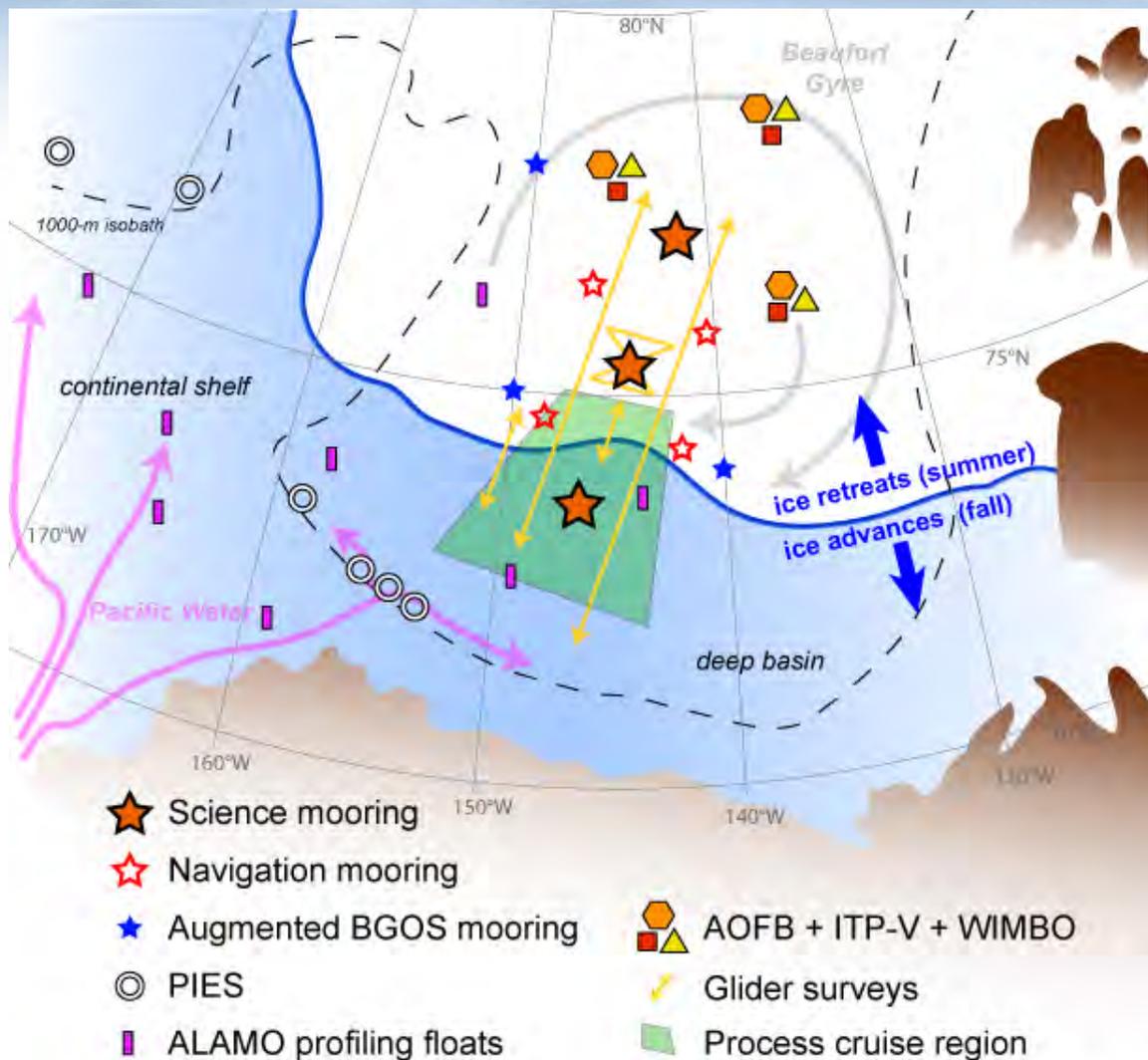
Stratified Ocean Dynamics in the Arctic

2018 – 2019 Field Efforts

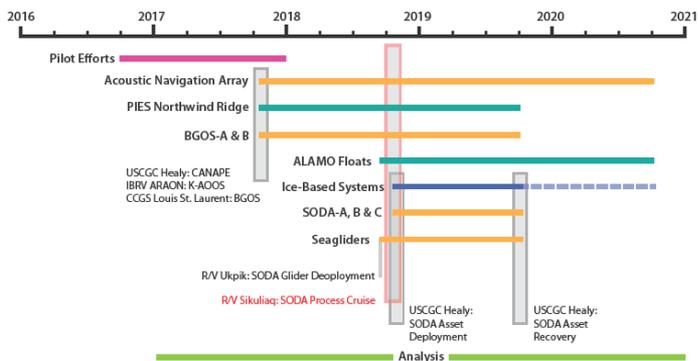
SODA Objective

SODA is a process study to better understand the response of the upper Arctic Ocean to changes in oceanic inflow and surface forcing over ice-free waters or areas of reduced sea ice cover.

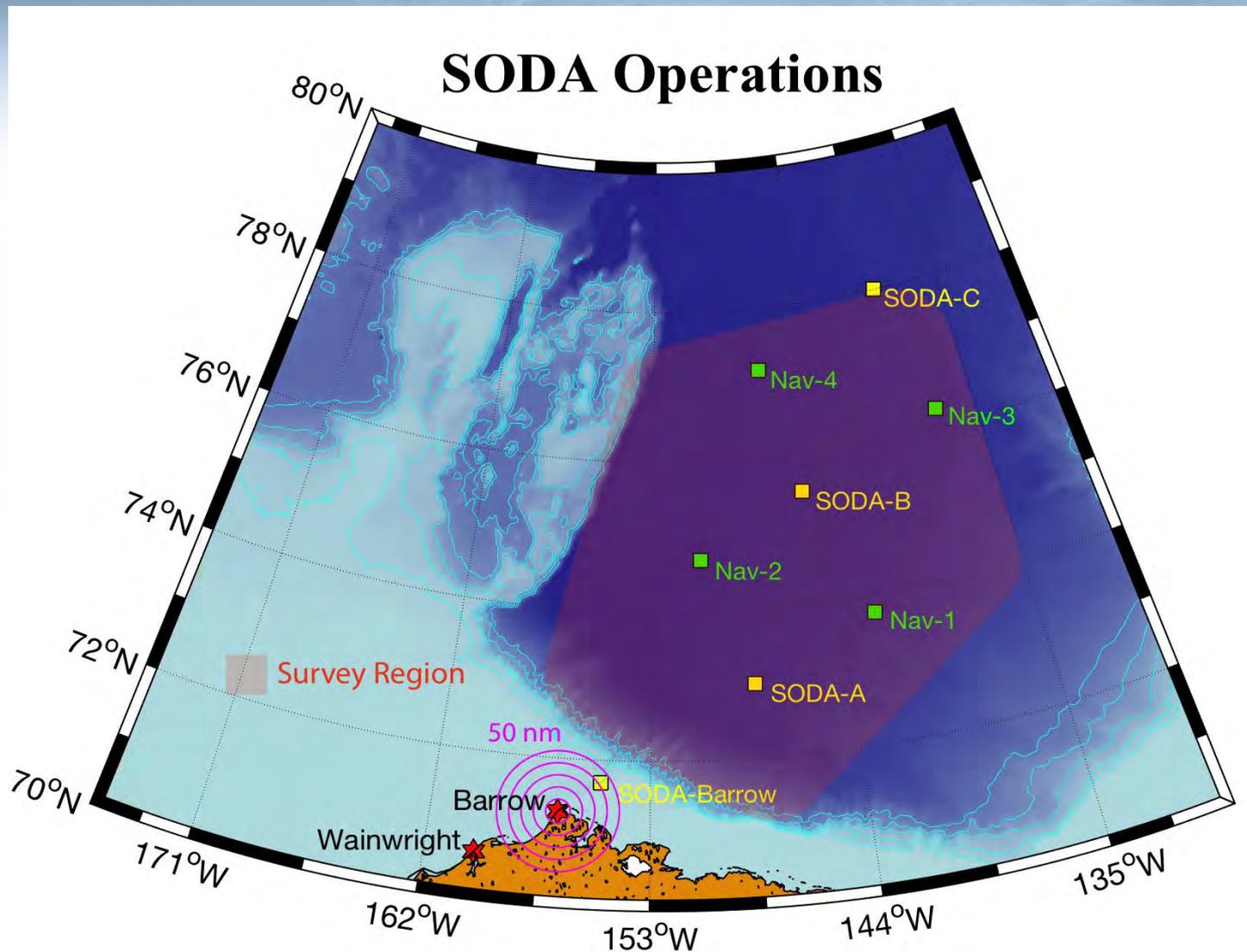
The program will include extended autonomous observations as well as intensive ship-based data collection during several cruises.



SODA Program Timeline

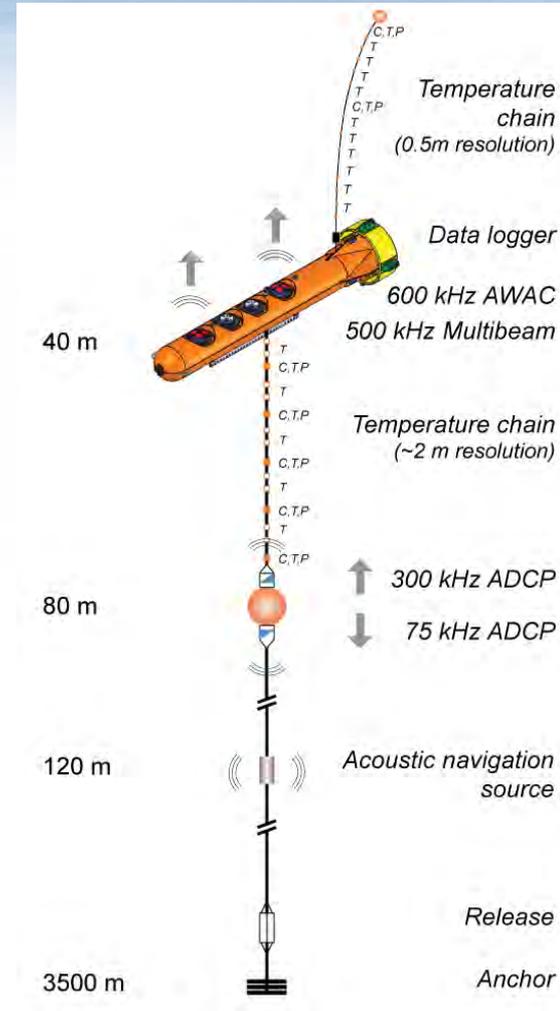
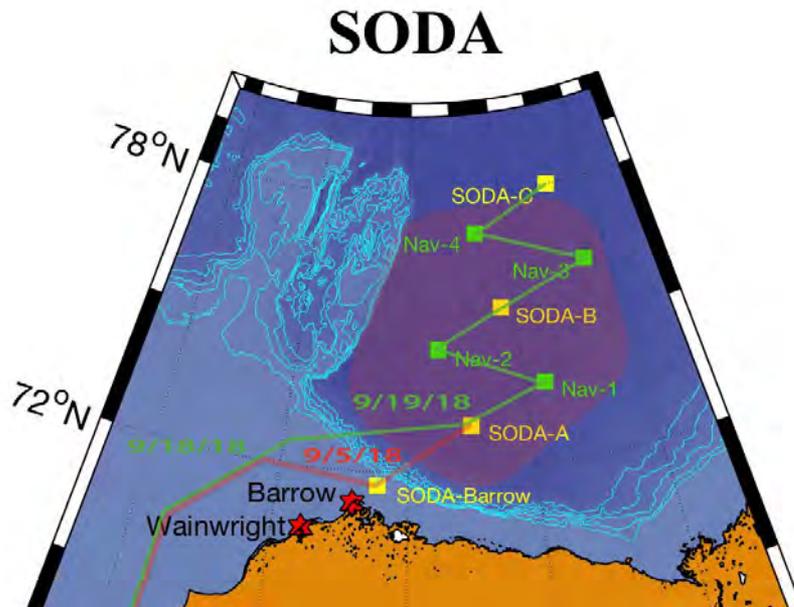


SODA region



Focus on mooring deployments:

- SODA A, B, C
- Navigation moorings
- Ice-based platforms



Focus on process, in three modules:

1. Eddy survey
2. Mooring survey
3. Ice edge survey

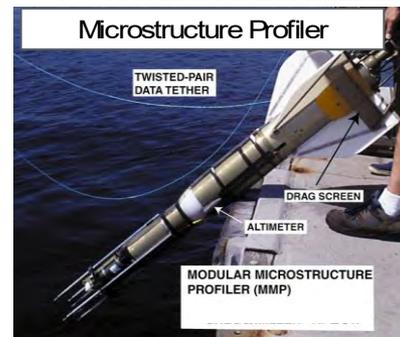


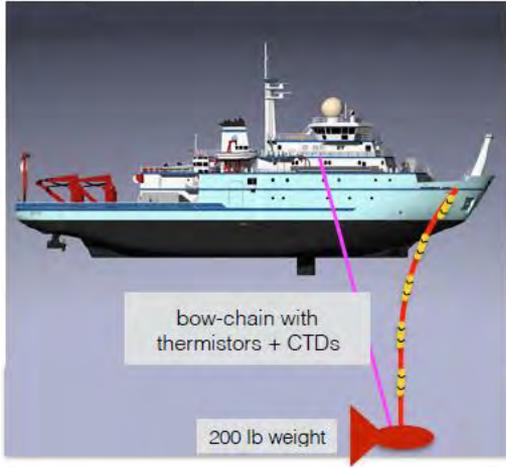
Figure 10. Proposed tools to be used during the process cruise. Clockwise from upper left: the Modular Microstructure Profiler (rapid tethered profiling down to 300 m), SWIFT drifters for short deployments from the ship (new versions have ADCPs and C-T chains), meteorological instrumentation on the mast, and the SWIMS towed body.

Process cruise tools: ship-based

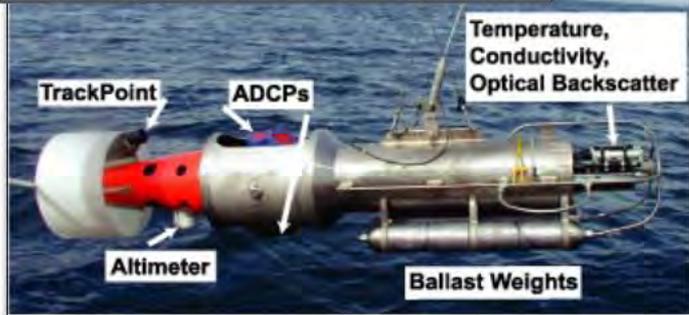
Microstructure profiler on outboard boom



Bow Chain



Shallow Water Integrated Mapping System (SWIMS)



3D sonic anemometer+IMU

Process cruise tools: near-ship

Gill Windmaster Microstrain GPS + IMU Airmar weather station Datawell MOSE-G



Wave Glider

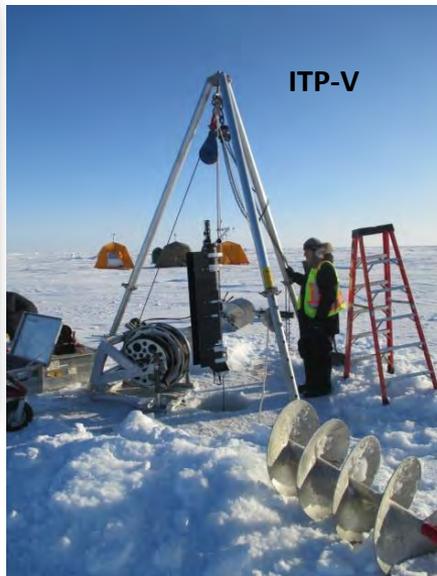
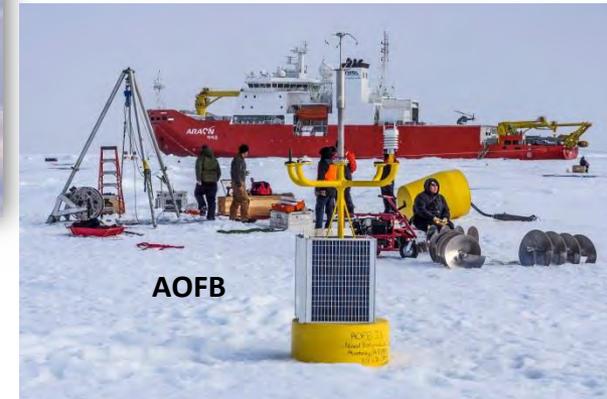
RDI ADCP

Seabird CTD

SWIFT drifters



Autonomous Instrumentation

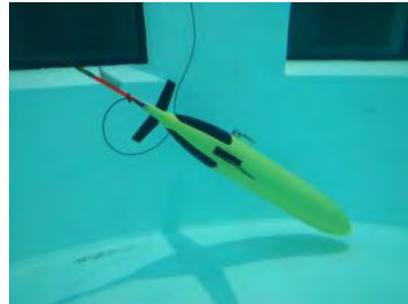
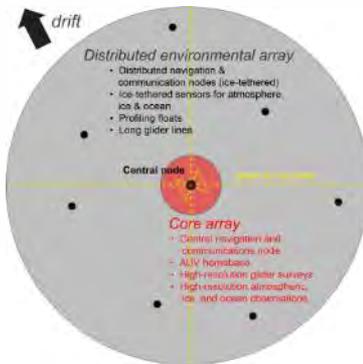




Sea Ice Dynamics Experiment (SIDEx) 2019 Field Effort

Objective

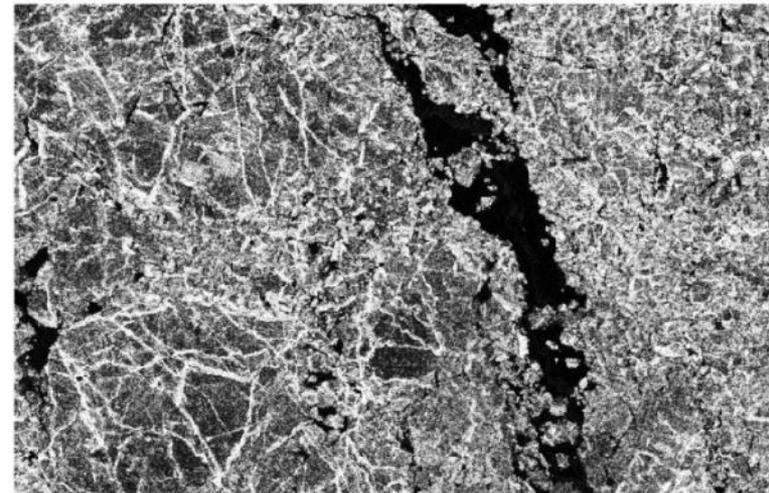
Using a distributed array of unattended sensors and platforms, understand the fine scale behavior of different sea ice types under a variety of stress and strain conditions to enable the development of high-resolution numerical sea ice models that can accurately simulate and forecast the formation, deformation, and break-up of Arctic sea ice due to atmospheric, wave, and ocean forcing.



SIDEx Observing Array

- Will combine in situ platforms and satellite remote sensing to track sea ice motion and forcing over several months

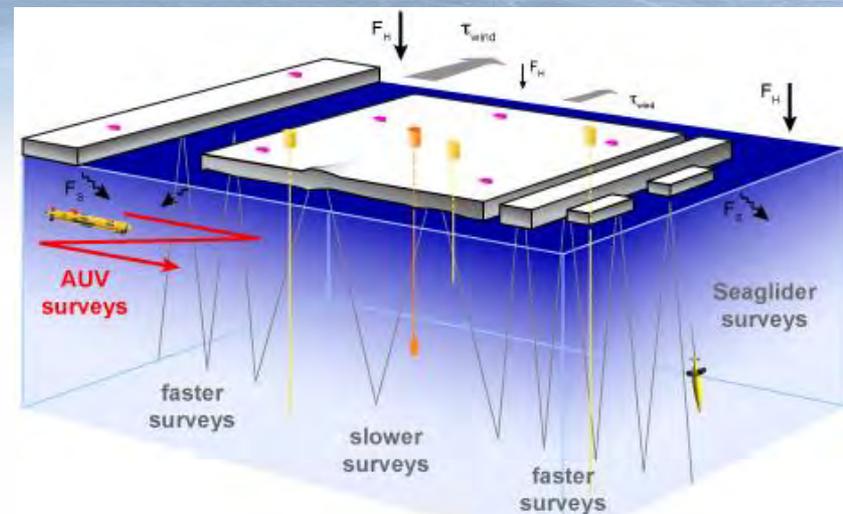
TSX 09/18/2014 01:45:45 UTC



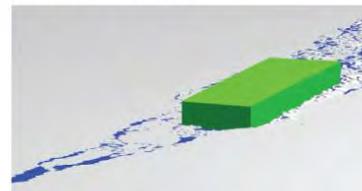


Arctic Mobile Observing System (AMOS)

- Mobile Sensing System for Arctic Observation and Prediction
- Multiple unmanned platforms with under-ice capabilities – UUVs/buoys/floats will collect data around a central buoy node drifting with the sea ice that provides power/comms
- Bi-directional data transfer and mission adaptability with autonomy improvements
- Designed to characterize the Arctic environment & prototype CONOPs for persistent robotic observing systems in the Arctic

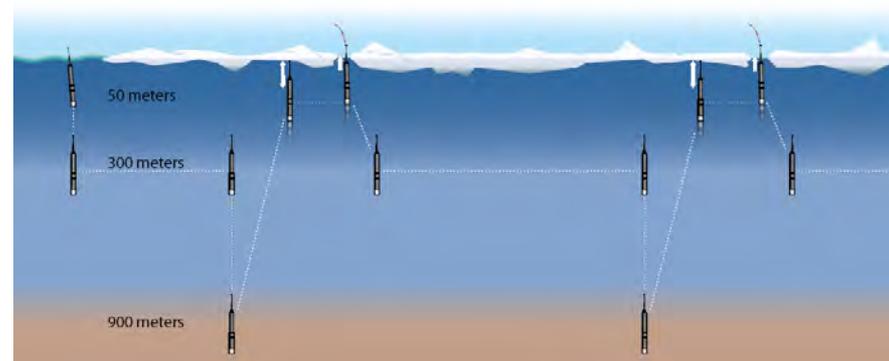
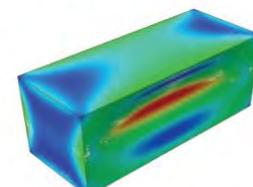


DEM
Ice-container interaction



ICE LOADS

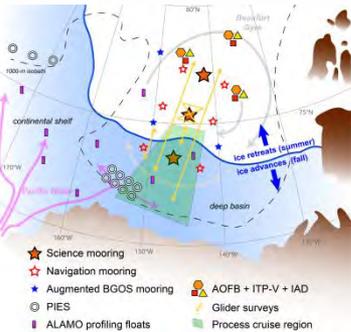
FEM
Container structural response



Key Technical Goals and Deployment Opportunities

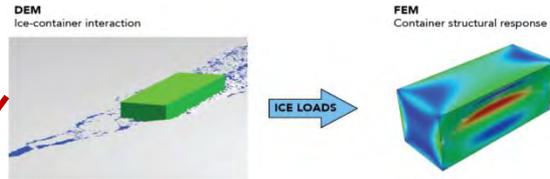
SODA DRI (6.1)

Will further develop under-ice navigation and communication with autonomous platforms



AMOS Kick-Start Funding

Supports design and testing of initial node designs in FY17 and FY18



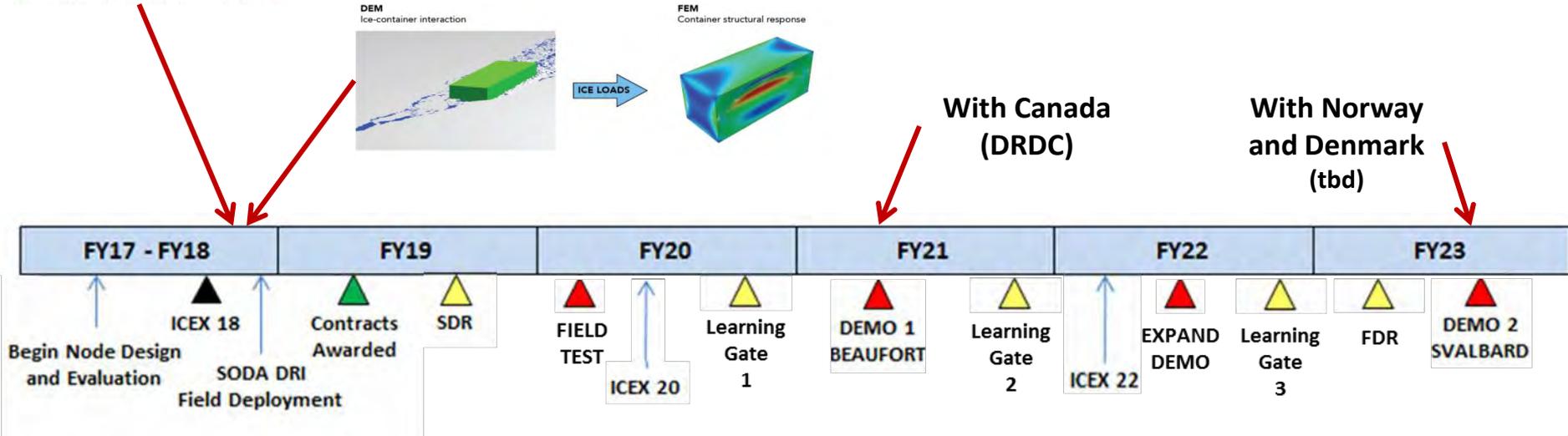
Leap Ahead Technical Goals

Domain-Specific Engineering Development

- Upgrade UUV platform designs for the Arctic environment
- Develop the power and communication buoy node for the Arctic domain
- Incorporate mature and maturing UUV sensing capabilities into vehicles and ensure suitability for Arctic operations

Develop Under-ice CONOPS for Autonomous UUV Network

- Build on capabilities developed under previous efforts for vehicle autonomy, re-charging, sensing, communication, and C4I, and develop new capabilities for operating under sea ice
- Enable an under-ice acoustic navigation system for unmanned platforms (suitable for use in any GPS-denied operational area)





ONR Arctic Access Concerns

ONR is interested in autonomous observing systems in the Arctic, and will require the ability to deploy, test, and evaluate prototype platforms, systems, and components .

In particular, ONR will need, in SODA and in follow-on programs, the ability to deploy sensors and systems on the ice. With that in mind...

- How successful have recent deployments onto ice floes been from the HEALY?
- How are decisions made regarding risk and approval to put people on the ice?
- How are the candidate floes chosen?
- Is there anything ONR can do to help ensure, or at least maximize, the opportunity to get scientists and engineers on the ice to deploy their gear?
 - Remote sensing support (high-resolution SAR)?
 - Dedicated weather forecasting for ship locale?
 - Other?



ONR Arctic Research Summary

ONR's Arctic Program is investing in research that will enable the Navy to prepare for and respond to future Arctic missions and concerns in recognition of the emerging interest in the region.

Primary thrusts:

- **Development and use of new observing tools, with an emphasis on autonomous platforms and sensors**
- **Basic understanding of the emerging physical Arctic system**
- **Development of the Arctic component of Earth system numerical prediction models to enable improved forecasts**

