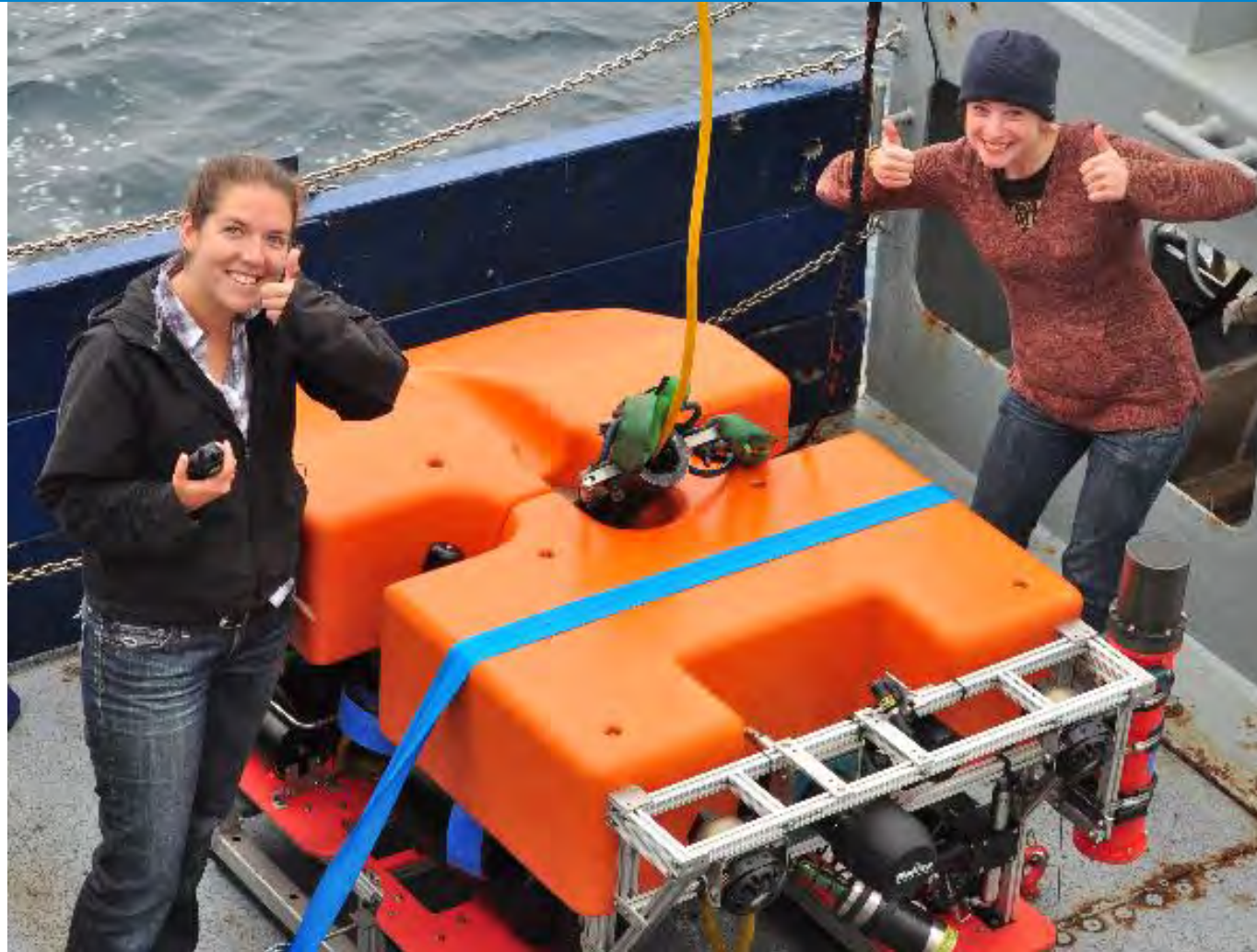


ROV *Trident*

A 2,000 meter portable Remotely-Operated Vehicle



Scripps Institution of Oceanography

Associate Director; Bruce Appelgate, December 2017



ROV Trident

General Specifications

Depth: 2,000 meters

Payload: 74.5 kilograms

Crew: 3 persons per 12-hour shift

Power Requirements:

Control Van: 480v/3ph/60Hz/60A

Winch: 480v/3ph/60Hz/60A

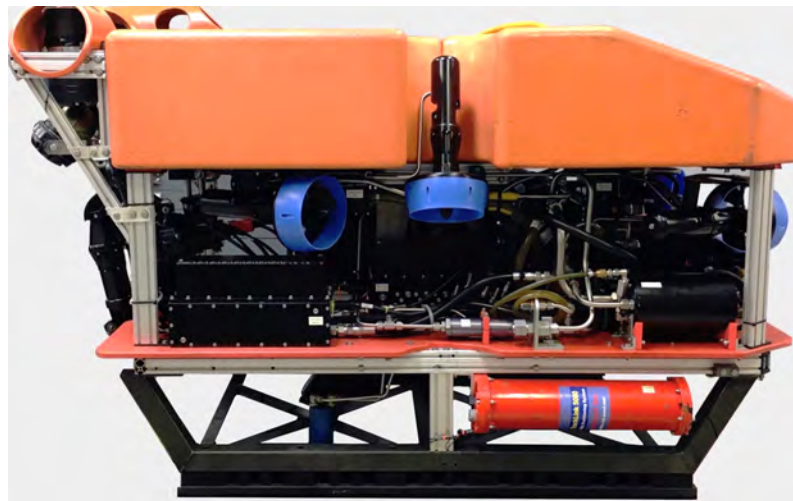
Deck Space:

Control Van	9000 lbs	8' x 20'
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Winch	3000 lbs	6' x 8'
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ROV	895 lbs	60" x 39" x 48"
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Navigation: USBL (portable, pole mount)



Sonar (BlueView)

Camera (basket)

Lights (upper)

Lights (lower)

Manipulator
DOER SeaMantis
five-function



Camera (aft)

CTD (SeaBird)

Navigation transponder

Color Camera (Pegasus)

Compass / Depth Sensor
& thermometer ISD4000

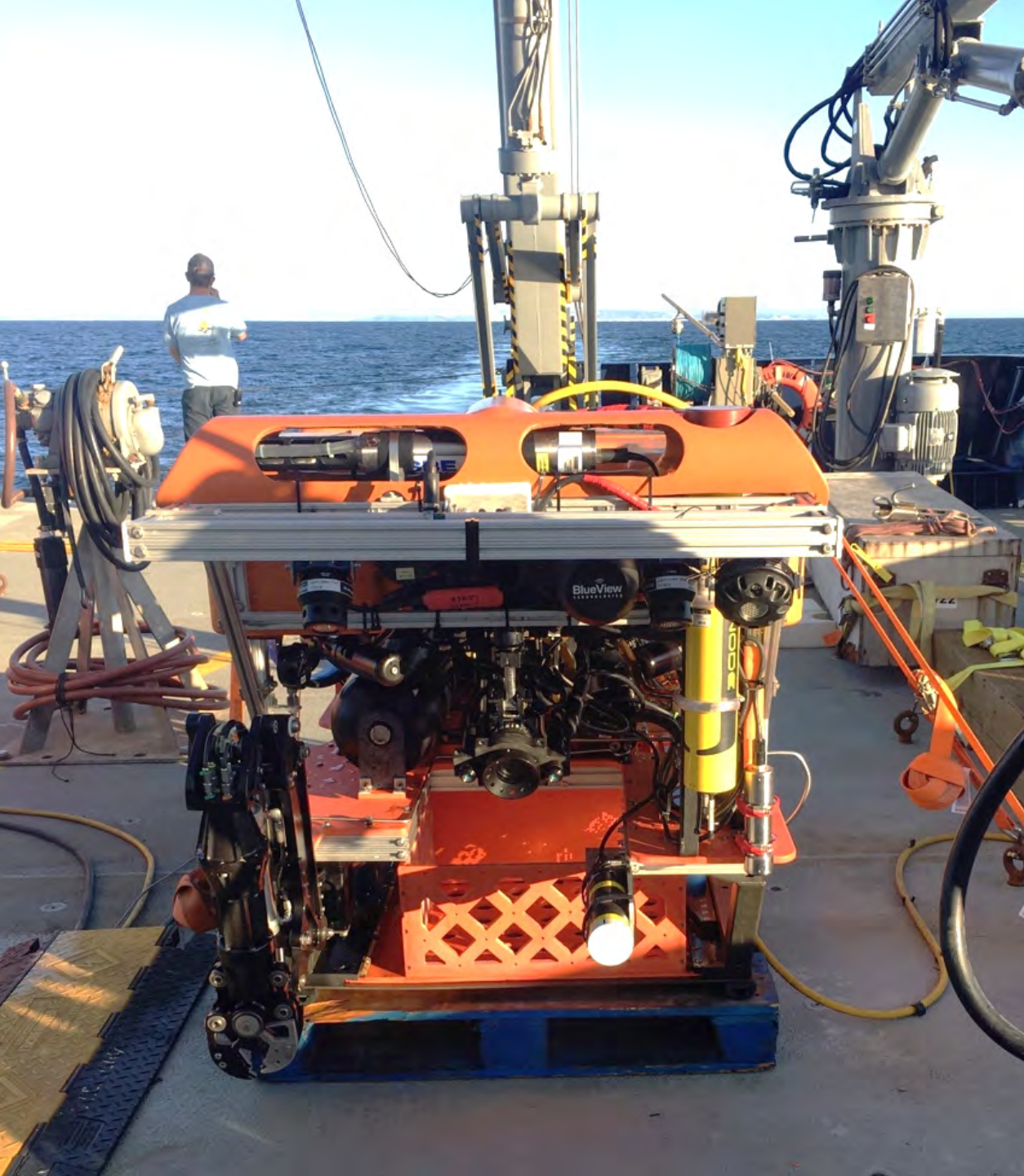
HD Camera (SIDUS)

Altimeter (Valeport)

Lasers (15 cm)

Sample Basket
(Retractable)





2017 Activities

- Hardware and software integration of Greensea Inc. *Balefire* topside control system in January 2017
- Commissioned control system on *R/V Sally Ride*, February 18-25, 2017

Improvements, Changes, Modifications

- Additional tuning of control software
- Integration of Impact Subsea ISD400 AHRS (motion sensor)
- Reconfiguration of control van to fit operational features of Greensea system
- Replacement of control van networking components
- Preparations for 2018 cruise



ROV *Trident*

A 2,000 meter capable portable Remotely-Operated Vehicle

Available for use worldwide now.

Costs charged by usage day rate plus shipping.

How to use *Trident*

Contact the ROV group at Scripps:

rov-trident@ucsd.edu

Contact the SIO Tech Services Manager (Lee Ellett)

lellett@ucsd.edu



UC San Diego

