

DeSSC report

December 1, 2016

UNOLS Council Meeting

- DeSSC membership update
- NDSF vehicle updates
 - HOV Alvin
 - Chief Sci training
 - ROV Jason
 - Jason on the RV Sally Ride
 - AUV Sentry
- Other activities
 - DESCEND2 report
 - Telepresence working group initiated
 - Education and outreach activities



DeSSC membership

Current members

Craig Dawe (*MBARI*)***

Amanda Demopoulos (*USGS*)

Dave Emerson (*Bigelow*)

Brian Glazer (*Univ. Hawaii*)***

Nick Hayman (*UTIG*)

Laura Lapham (*Univ. Maryland*)

Anna-Louise Reysenbach, Chair
(*Portland State U*)

Cindy Van Dover (*Duke*)

Scott White (*Univ, SC*)***

Peter Girguis, (*ex-officio, Harvard*)

Rob Munier (*ex-officio, WHOI*)

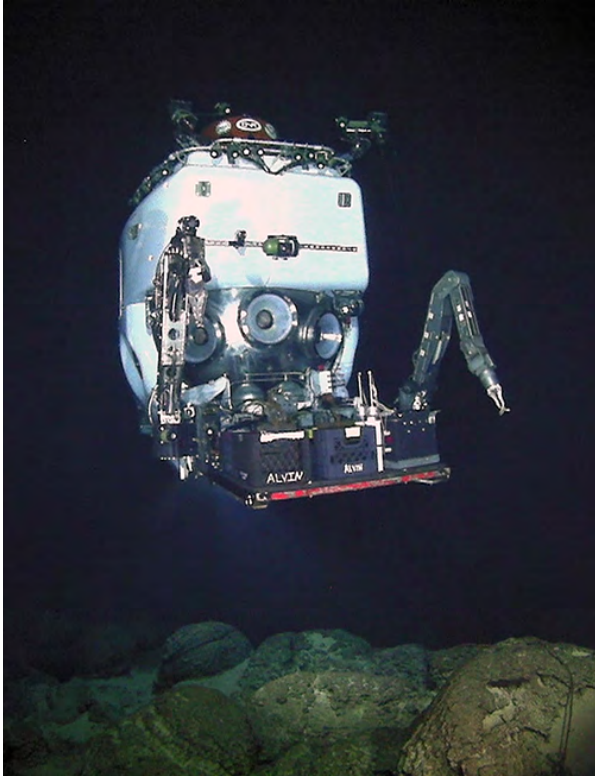
Tim Shank (*ex-officio, WHOI*)

Adam Soule (*ex-officio, WHOI*)

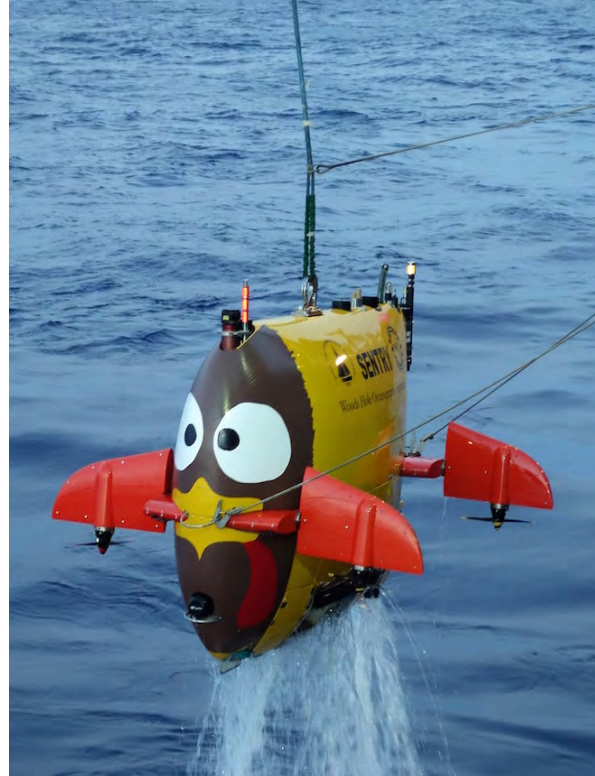
Changes to Terms of Reference- Vice Chair



NDSF Vehicle Updates



HOV *Alvin* on the seafloor at the 8°20'N seamount chain on the EPR. Image courtesy of P. Gregg & D. Fornari.



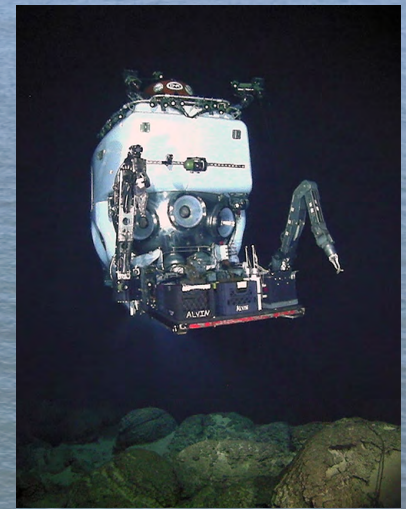
AUV *Sentry* in a holiday mood with a turkey face by J. Fujii. Image courtesy of D. Yoerger.



ROV *Jason*

HOV *Alvin*

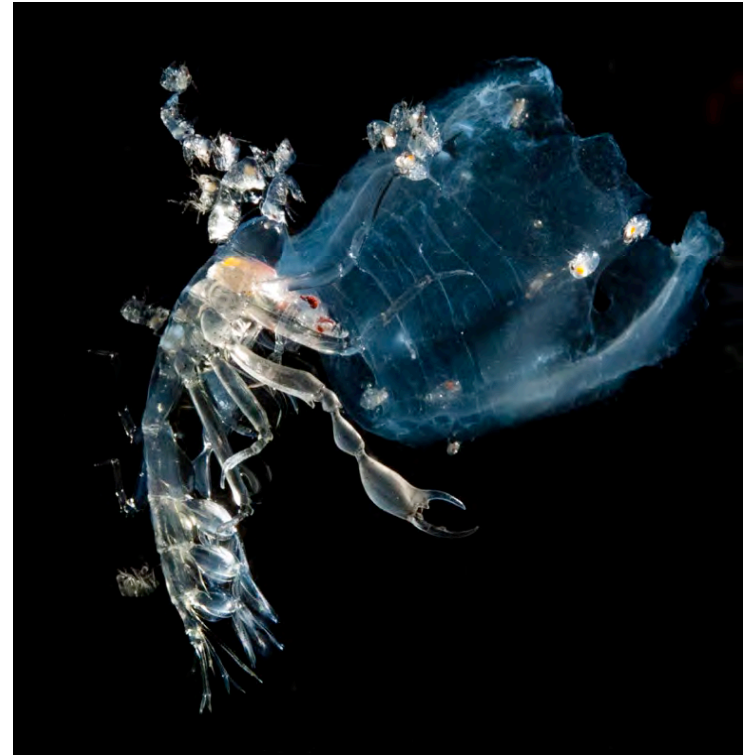
- Usage: 127 days (46 days in 2015)
- Running really well
- integration of acoustic communications package for enhanced sub-to-ship comms (text messages, images).
- Transitions between downtime can be a bit of a challenge- additional engineering dives helps smooth out the wrinkles
- Featured vehicle in UNOLS Chief-Sci Training cruise sponsored by NSF (along with AUV *Sentry*).



Chief Sci training cruise included 24 young scientists with ship and shore parties supported by telepresence.

Deep submergence chief scientist training program

- 24 asst. professors, senior postdocs and grad students with ~56 remotely signed up! (July-Aug 2016)
- planning and executing collaborative, interdisciplinary research
- leadership in cruise and dive/mission planning and execution
- integration of instrumentation with *Alvin*/*Sentry*/other deep-submergence assets
- telepresence-enabled data acquisition and seafloor-to-ship-to-shore communications data management, sharing, reporting
- science communication and outreach to broader audience(s)
- Cindy Van Dover, Donna Blackman, Adam Soule, Dan Fornari and Karl Bates



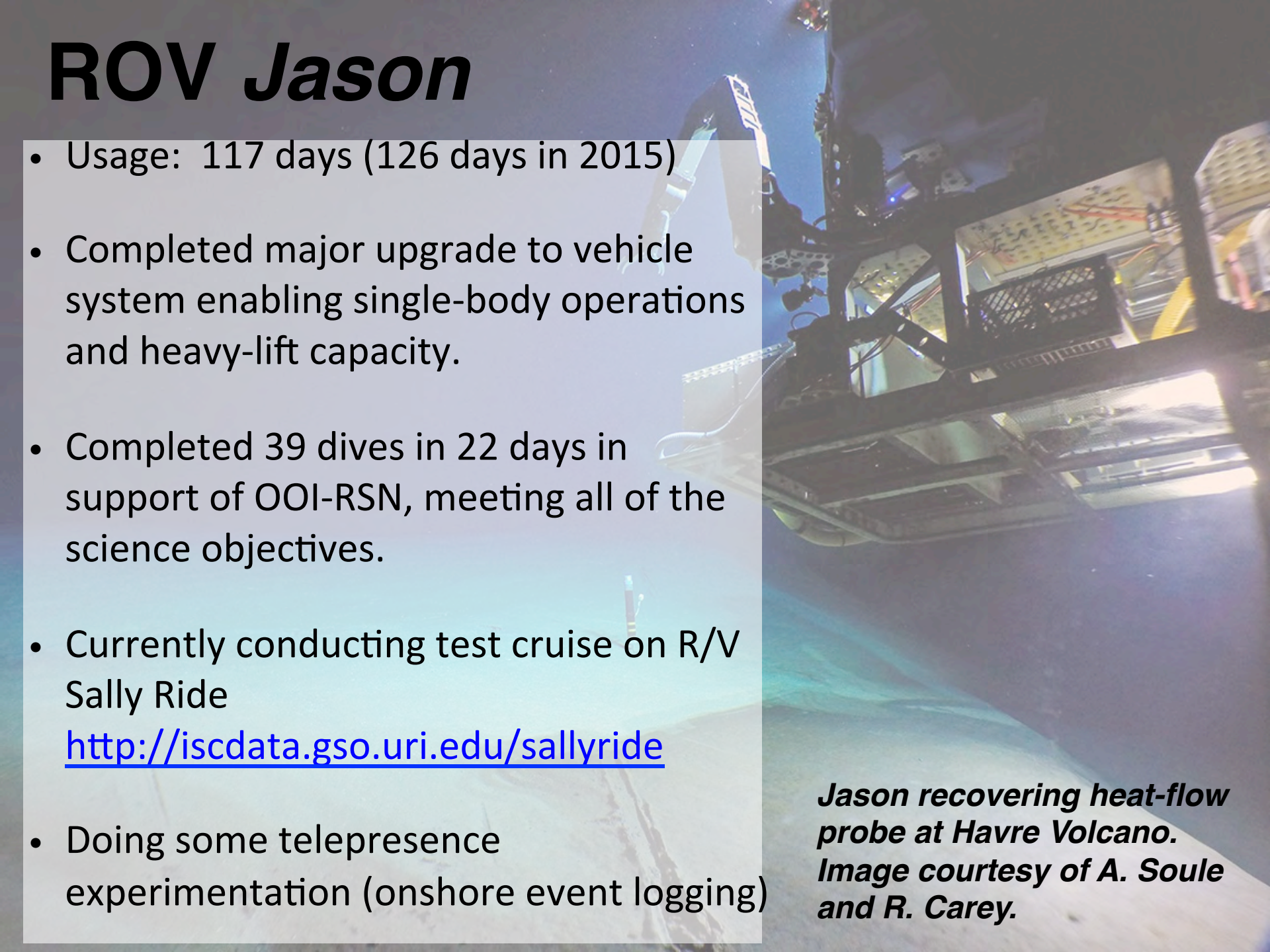
Phronima sp. (hyperiid amphipod) and its salp house from mid-water *Alvin* sampling. Photo by ECS Laura Bagge.

Outcomes: Highlights

- Overall very successful and well received
- Report on DeSSC site
- Although 75% of participants had seagoing experience, 42% had no previous experience with NDSF. Most first time with Alvin
- 67% likely to submit proposals to use NDSF in next 2 years, all but 2 would in next 5 years
- 88% expect to continue these collaborations
- Numerous recommendations in the report such as: “Chief sci shadowing” opportunities
- “What is fun to see is that they continue to work together - a network is in place”.. Cindy Lee Van Dover –Chief Sci
- Clearly building capacity- user base, an endeavor I hope we can continue to support

ROV Jason

- Usage: 117 days (126 days in 2015)
- Completed major upgrade to vehicle system enabling single-body operations and heavy-lift capacity.
- Completed 39 dives in 22 days in support of OOI-RSN, meeting all of the science objectives.
- Currently conducting test cruise on R/V Sally Ride
<http://iscdata.gso.uri.edu/sallyride>
- Doing some telepresence experimentation (onshore event logging)

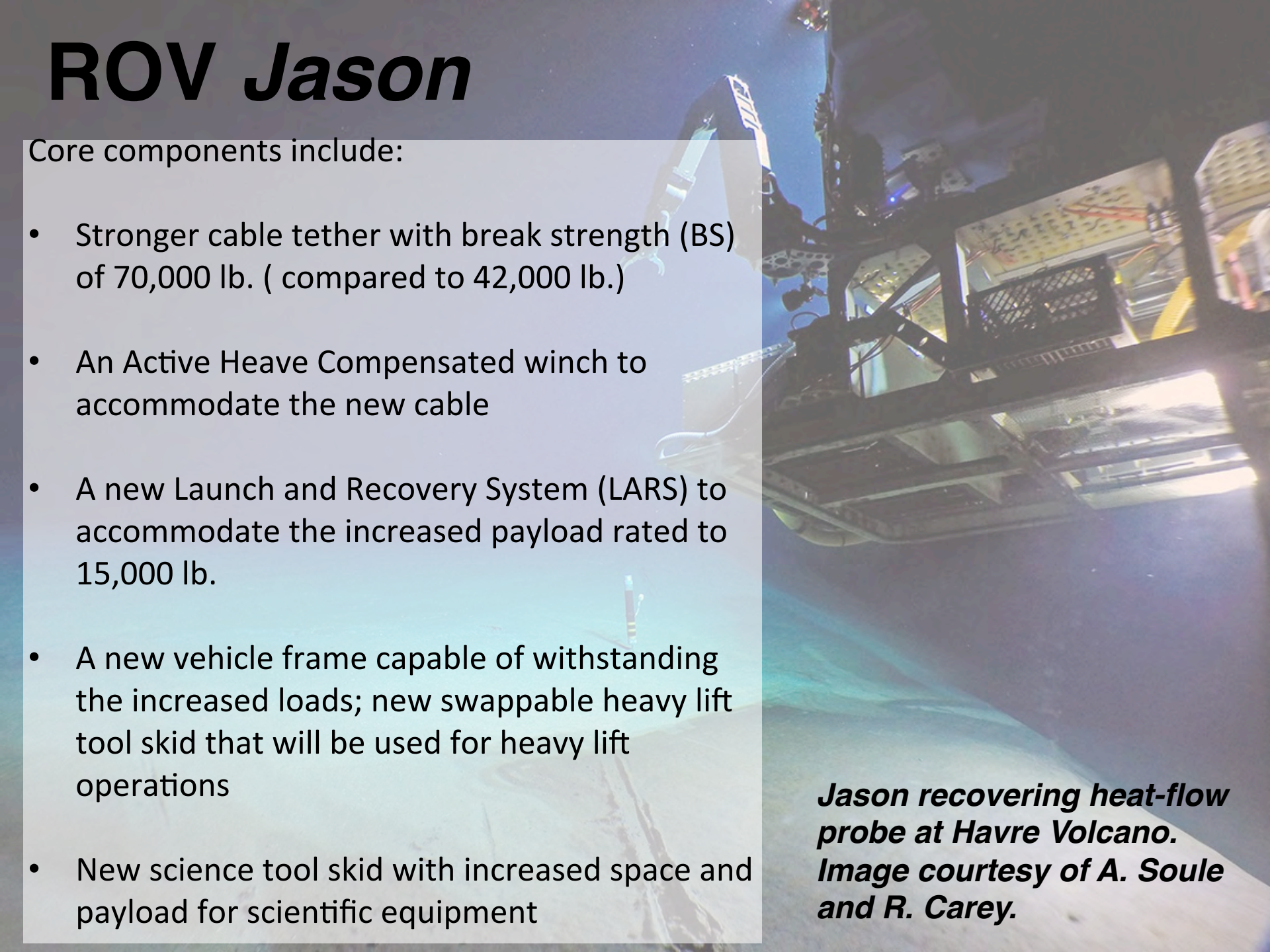
The image shows the ROV Jason in a deep-sea environment, illuminated by its own lights. The vehicle is a complex, multi-tiered structure with various instruments and sensors. It is positioned above a dark, rocky seafloor. The background is a deep blue, slightly hazy water column.

Jason recovering heat-flow probe at Havre Volcano. Image courtesy of A. Soule and R. Carey.

ROV Jason

Core components include:

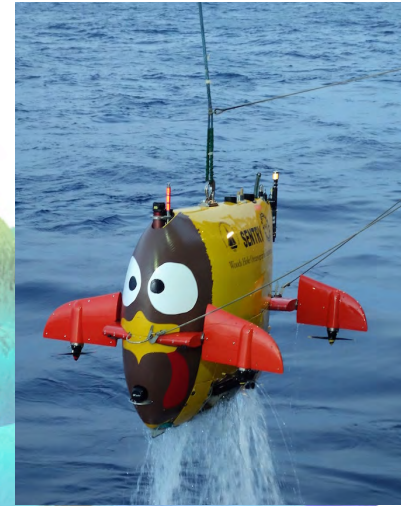
- Stronger cable tether with break strength (BS) of 70,000 lb. (compared to 42,000 lb.)
- An Active Heave Compensated winch to accommodate the new cable
- A new Launch and Recovery System (LARS) to accommodate the increased payload rated to 15,000 lb.
- A new vehicle frame capable of withstanding the increased loads; new swappable heavy lift tool skid that will be used for heavy lift operations
- New science tool skid with increased space and payload for scientific equipment

The background image shows the ROV Jason in operation. It is a large, complex piece of machinery with various instruments, lights, and a crane-like structure. The ROV is positioned in a deep-sea environment, with a dark, blueish water column and a rocky seabed visible in the lower part of the frame. The ROV's lights are on, illuminating the surrounding water and the seabed. The overall scene is a technical and scientific operation in a deep-sea environment.

Jason recovering heat-flow probe at Havre Volcano. Image courtesy of A. Soule and R. Carey.

AUV *Sentry*

- Usage: 139 days (197 days in 2015)
- Battery upgrade significantly increased endurance (24h mapping, 36h photos) without increasing turnaround time.
- Upgrades have made it lighter, forward looking sonar= significant improvement
- Completed cruise in support of NTSB survey of El Faro wreckage and search for VDR. (broader impacts of the NDSF)
- Five of seven *Sentry* cruises were two-vehicle, supporting *Alvin* or *Jason* ops.

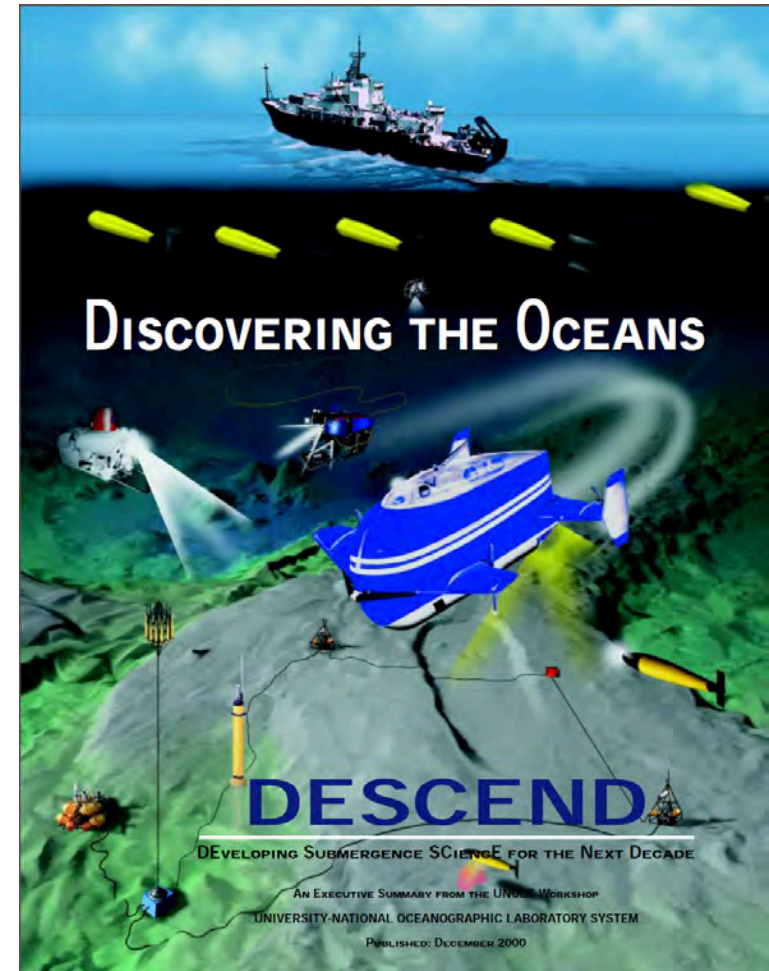


1-m resolution Sentry bathymetry of the axial valley of the Mid-Atlantic Ridge (14°N), courtesy of M. Kurz - WHOI

OTHER activities:

DESCEND2 workshop (Jan 14-15, 2016)

- 74 participants
- To direct future strategies for upgrades to vehicles, sensors, sampling techniques, imaging capabilities
- critical questions and the technologies necessary to address them.
- Coastal, open ocean (benthic and pelagic), polar, physical oceanographic, ecological, biogeochemical summary reports
- website is live at the UNOLS DeSSC webpage and at [https://
descend2blog.wordpress.com/](https://descend2blog.wordpress.com/)
- Pete Girguis is finalizing report



1999 DESCEND workshop report

Telepresence working group

- DeSSC has initiated a working group to:
 - draft a paper on Telepresence-enabled science missions
 - Will include
 - a review of ongoing activities (including those of the ECS)
 - Logistical limitations/considerations
 - Recommendations for usefulness of new technologies
 - Etc.

Education and Outreach

- AGU Fall -DeSSC meeting Dec 10-11
- With support from NSF, we've hosted 5 early career science programs, all of which were very well attended and received
 - ~28 attendees this Fall
 - Agenda

<https://www.unols.org/event/meeting/2016-dessc-winter-meeting>
- We continue to develop and implement new activities (with the approval of DeSSC/UNOLS), and to assist UNOLS with E&O assessment activities
- As new DeSSC chair, I would like to explore additional ways to broaden our outreach activities.

Thank-you

