

# Sentry Upgrades

## Battery Upgrade

- New 1 atm batteries
- New ceramic housing
  - Old one had 300 dives = time to check
  - Old one inspected, serviced, and ready to use again in the future
- 2x the total power
  - Upgraded charging means similar turn around times
  - ~25-28 hour multibeam missions with 90-100km of track line
  - ~50+ hour photo missions with ~125km track line



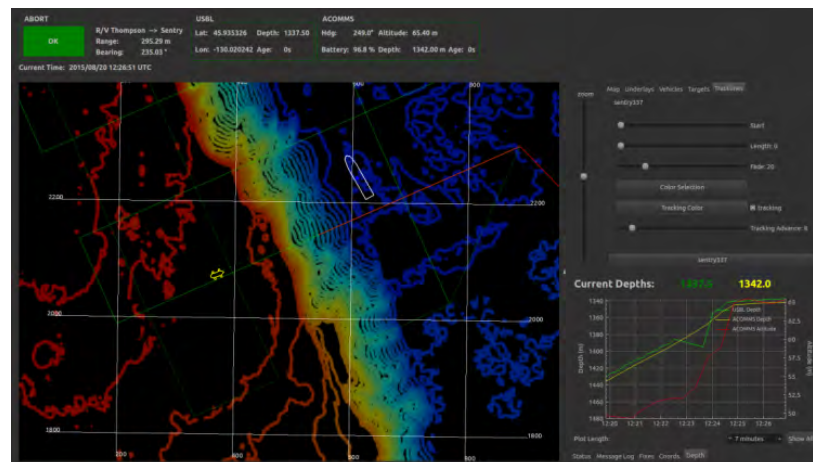
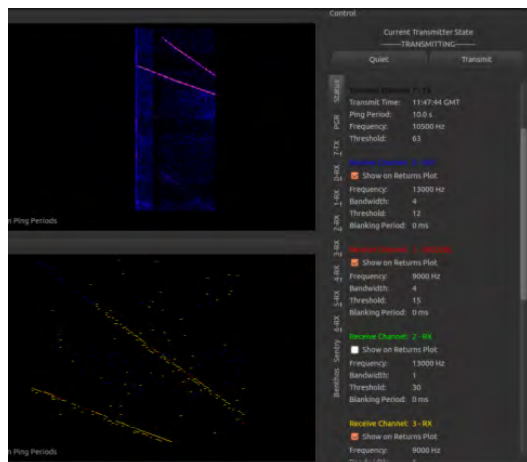


# Sentry Upgrades

## User Interfaces



- NavG interface
  - Substantial additions to situational awareness
  - Now decent science, bridge, and watchstander interface
- PGR
  - Significant improvement to non-USBL tracking of *Sentry*
  - Removes last of topside legacy software no longer supportable
  - Adds logging and other features
- *Sentry* Sitter
  - Integrated seamless acoustic comms for Micromodem and Sonardyne
- Pre/post dive – many new scripts. Predive has shortened by ~30min over the last 2 years, postdive by similar

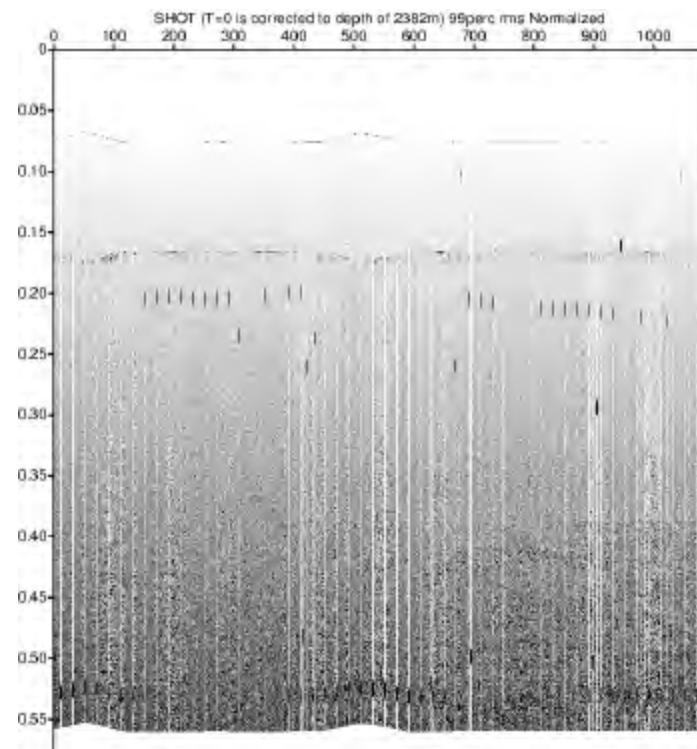




# Sentry Upgrades Data Pipelines



- MB system sidescan and sub-bottom pipelines fully online and highly automated
  - Navigated SEG-Y & strip plots for SBP
  - Navigated JSFs and strip plots for Sidescan
- New Multibeam tool makes process even more highly automated
  - Maps within 20 – 60 minutes of recovery now common – though not guaranteed
  - Very simple to use the basics but preserves advanced functionality



# Sentry Upgrades Photomosaics

- Mosaicing pipeline in process
- Getting results, but not automated enough to implement as standard
- Hoping to finish before end of the year, but may not have sufficient engineering resources – new position posting open







# Sentry Upgrades Metadata



- New scripts configure and read all possible data from instruments (e.g., serial num, cal constants, etc.)
- All responses logged
- Logs parsed by post processing
- Table created for dive report
- Should be in every dive report by end of year for some sensors
- Remaining sensors to be implemented next year

## 1.1 sentry338 Devices

Instrument	Model	Serial Num.	Comments
USBL	Sonardyne AvTrak2	U001A91	
DVL	RDI Navigator (300kHz)		
Magnetometer	APS 1540	APS 0689 Ver: 3.85BD7716F	
	APS 1540	APS 0688 Ver: 3.85BD7716F	
	APS 1540	APS 0690 Ver: 3.85BD7716F	
CTD	SBE 49	S/N: 222	



# Normal *Jason* Upgrades



- **New recovery line technique**
  - Line direct to *Medea*, faster and safer
- **Syntactic elevator flotation**
- **Upgraded elevator frames**
- **New 'Minivator'**
- **New LARS HPU**
  - Faster crane motion, safer, quieter, deck testing of manip
- **New navigation & dynamic positioning system**
- **DVDs eliminated**
- **New 'K' tube .681 cable**
- **Improved framegrabber**
- **Data delivered on hard drive**



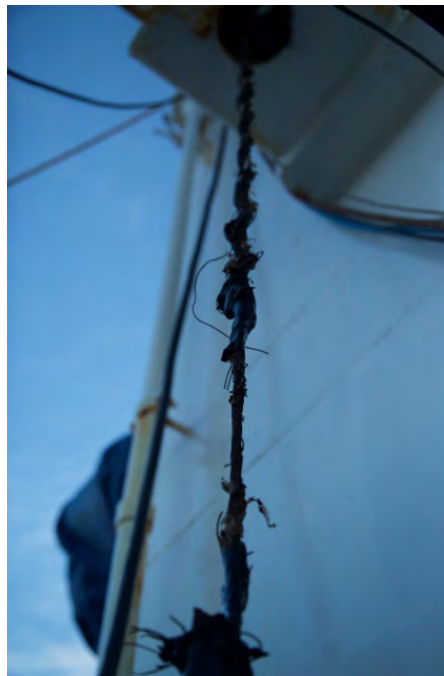
# Revelle EOM Cable Failure



- Deployed onboard the *Roger Revelle* PI Craig Moyer December 2014
- During a dive the weather deteriorated with a worsening forecast and the decision was made to recover early however the recovery was delayed in order to accomplish the maximum science
- Recovery was attempted but abandoned with ROV redeployed to 750 meters to await more favorable conditions
- Upon recovery, at a location 470 meters from the surface, an area of severe damage to the main cable was discovered
- Recovery of *Jason* was completed after 48 hours in gale conditions
- Nearly 6,000 meters of wire was jettisoned after inspection revealed periodic corrosion of the armor to this point.
- The cruise was completed with no further difficulty



# Revelle Cable Damage







# Suggestions for Further Consideration



## Users (NDSF)

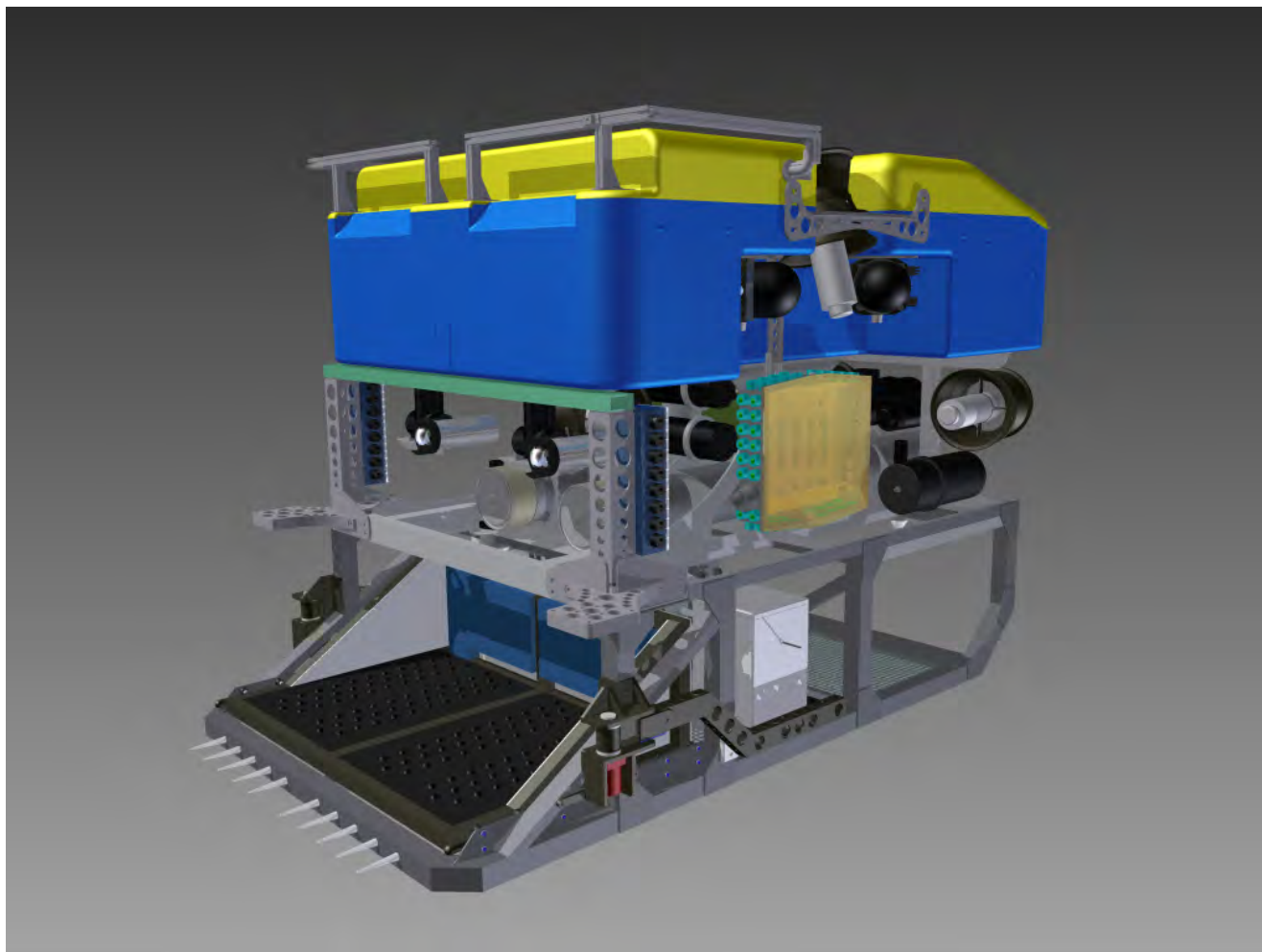
- Make prudent choices of risk/reward and communicate this to the stakeholders
- Ensure planning for deck operations and communications reviewed and understood for every activity
- Do not deploy payload to a fixed depth for extended periods of time without consideration/inspection for fatigue or wear

## Facility Operator (Wire Pool)

Ensure a 360 degree process to incorporate lessons learned become practice:

- Cleaning, lubrication and storage standards
- Periodic inspection with appropriate and detailed guidance to the operators/users
- Representative testing
- Review criteria and readiness of cables for service
- Ensure all operators are aware and informed

# Jason OOI Upgrade



## OBJECTIVE:

Modifications to the *Jason* system to enable routine operation and maintenance of OOI/RSN components

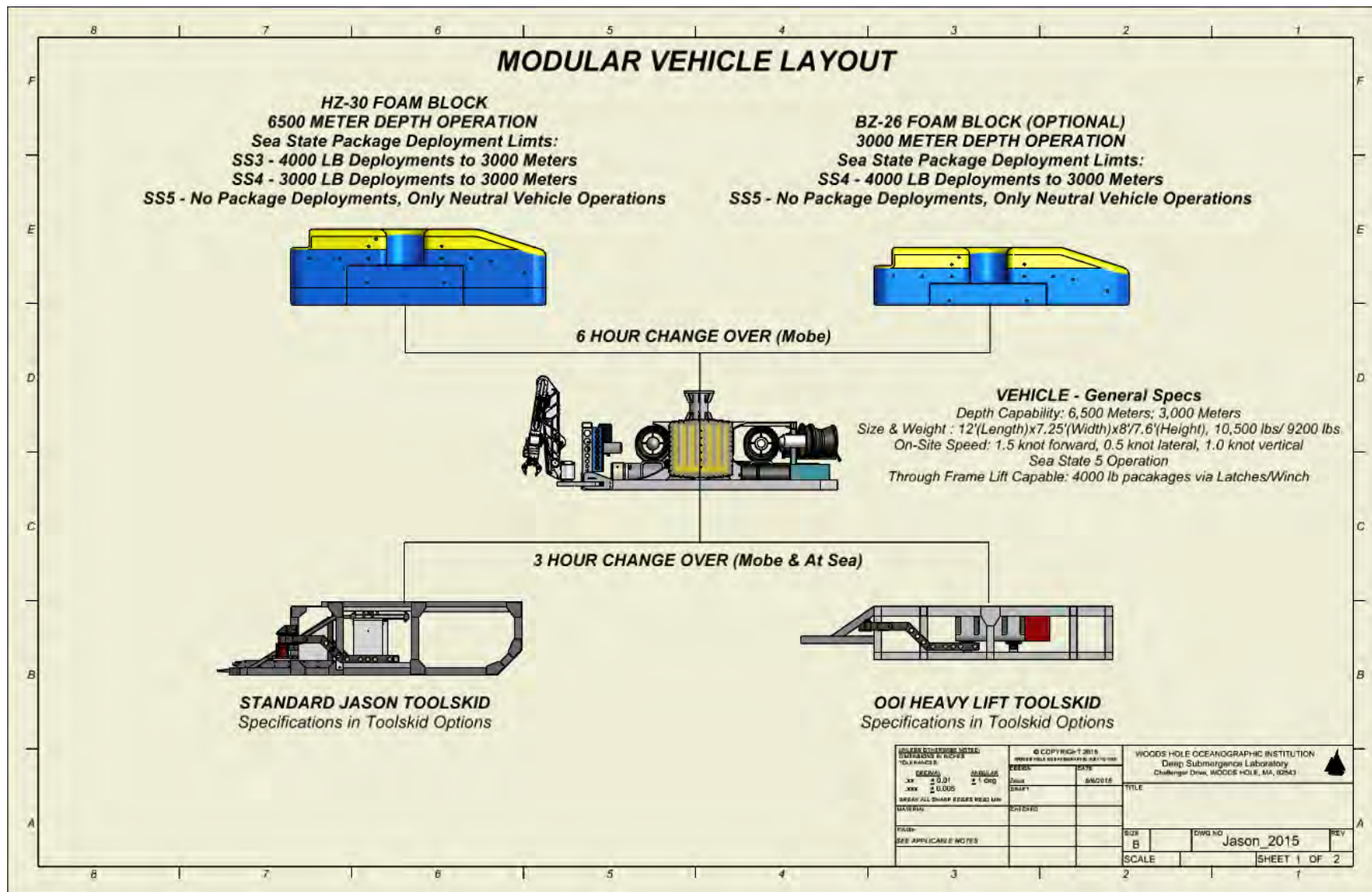


# Upgrade Details



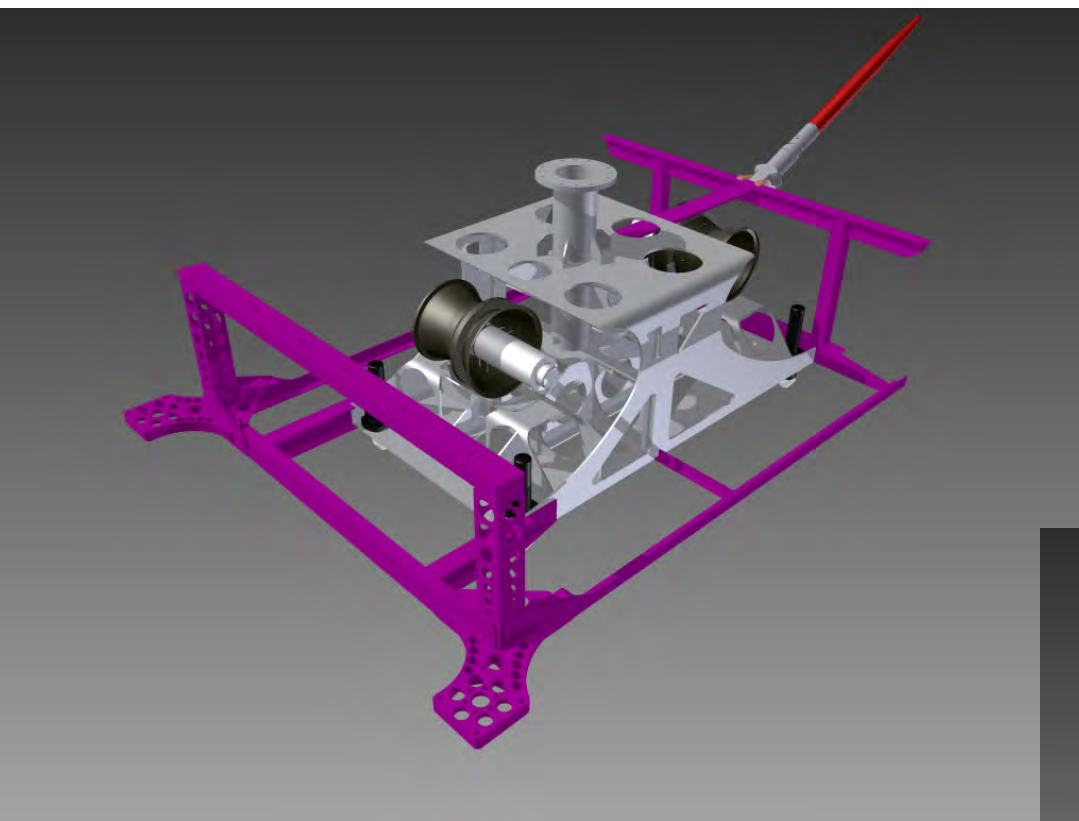
- New *Jason* frame for thru-frame lifts up to 4,000 lbs
- Single body ops, umbilical direct to *Jason*
- New higher strength umbilical 5,000 m
- New LARS crane
- Reduces deck space requirements
- Short turnaround tool skid swap
- Improves serviceability of vehicle components
- Increases free space in science bay

# Modular Vehicle Layout

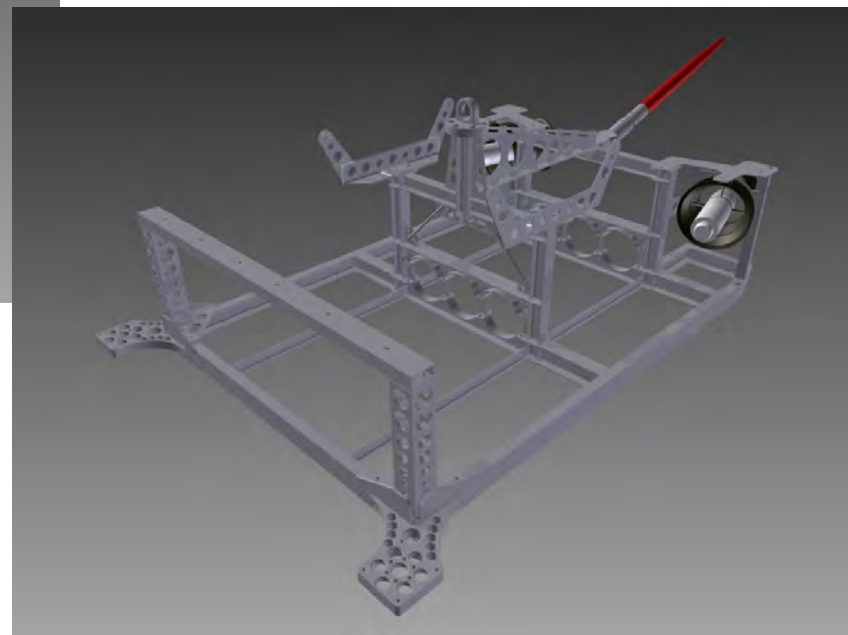




# New Frame vs. Existing



New frame load path



Old frame not  
capable of withstanding  
additional loads

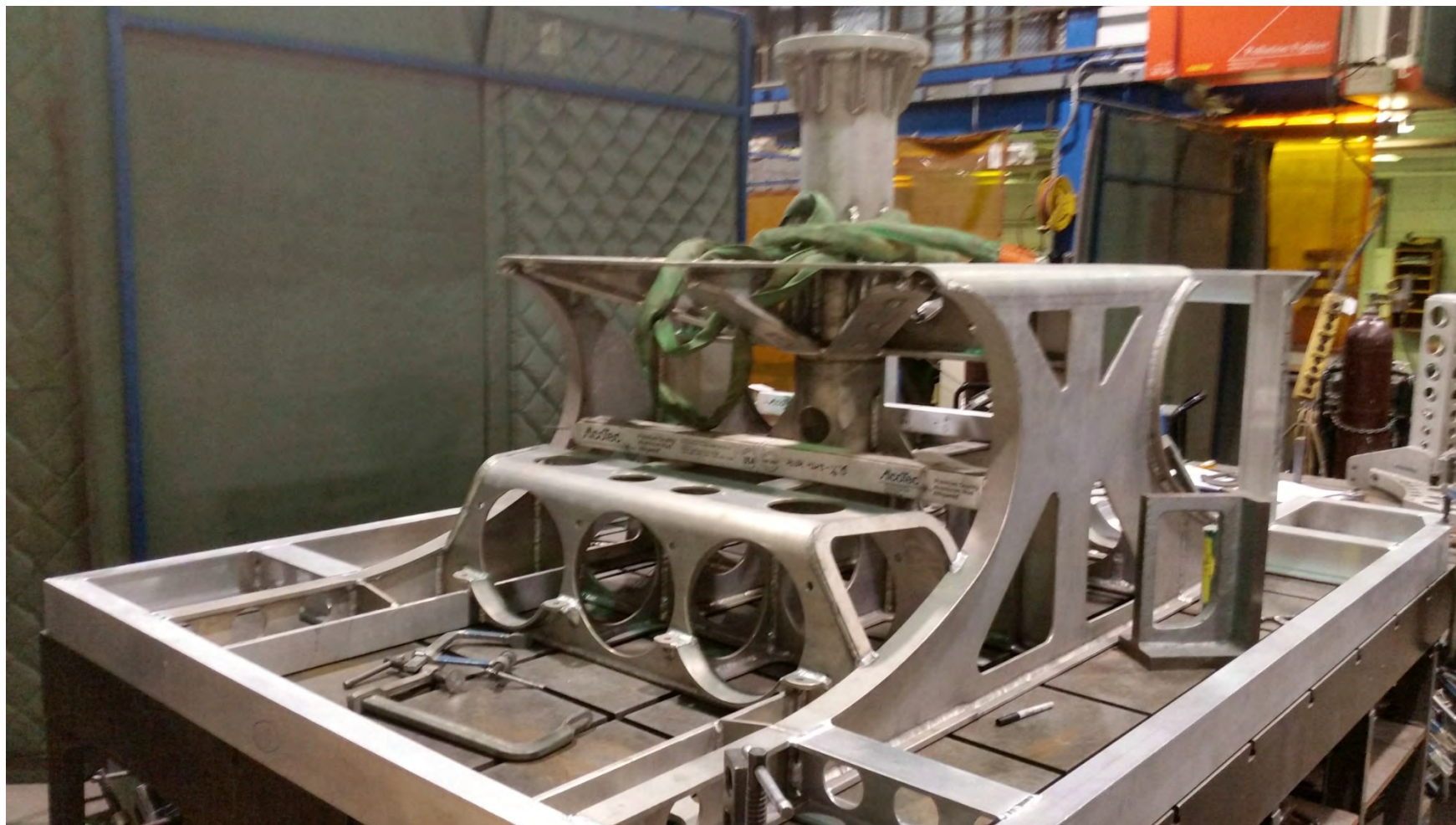


# Load Path Heat Treat

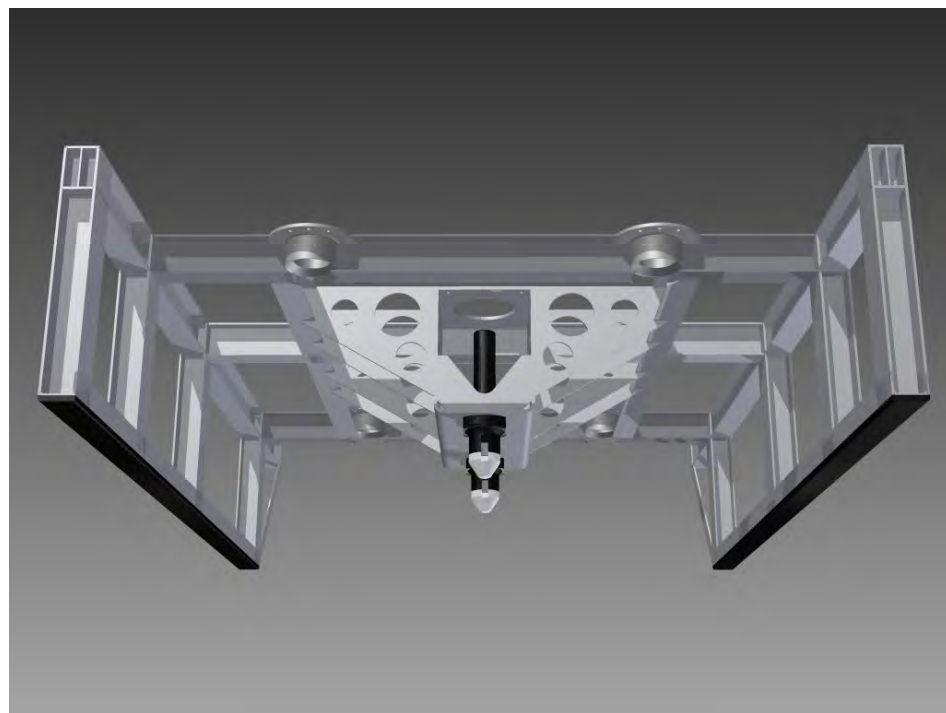




# Frame Welding

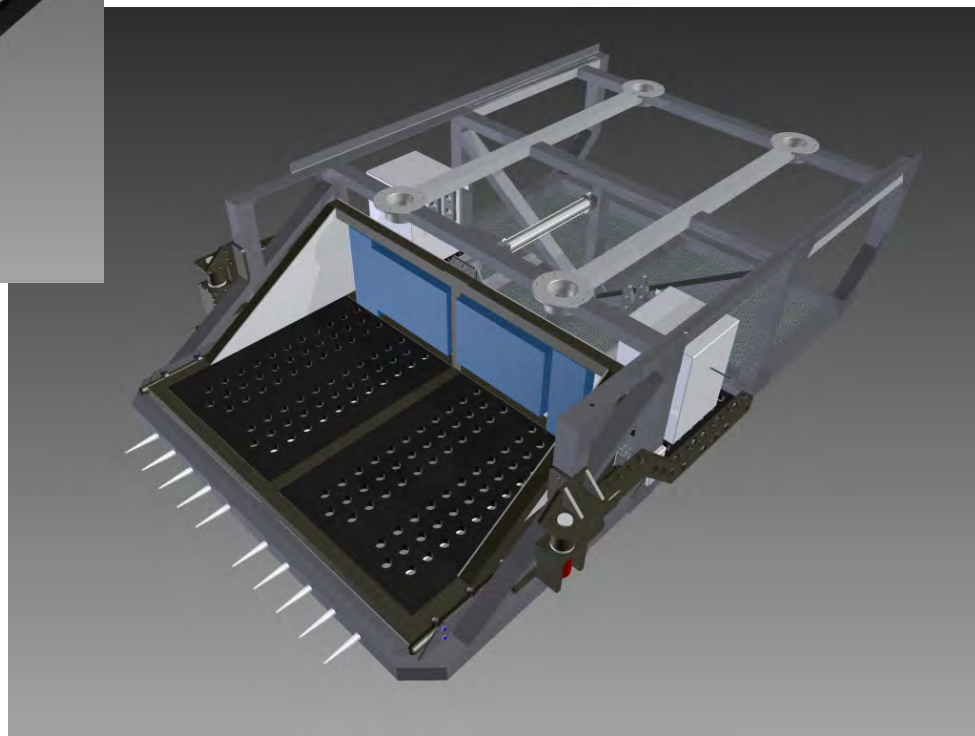


# Swappable Tool Skid



*Jason* skid – similar to existing design, additional aft bay space

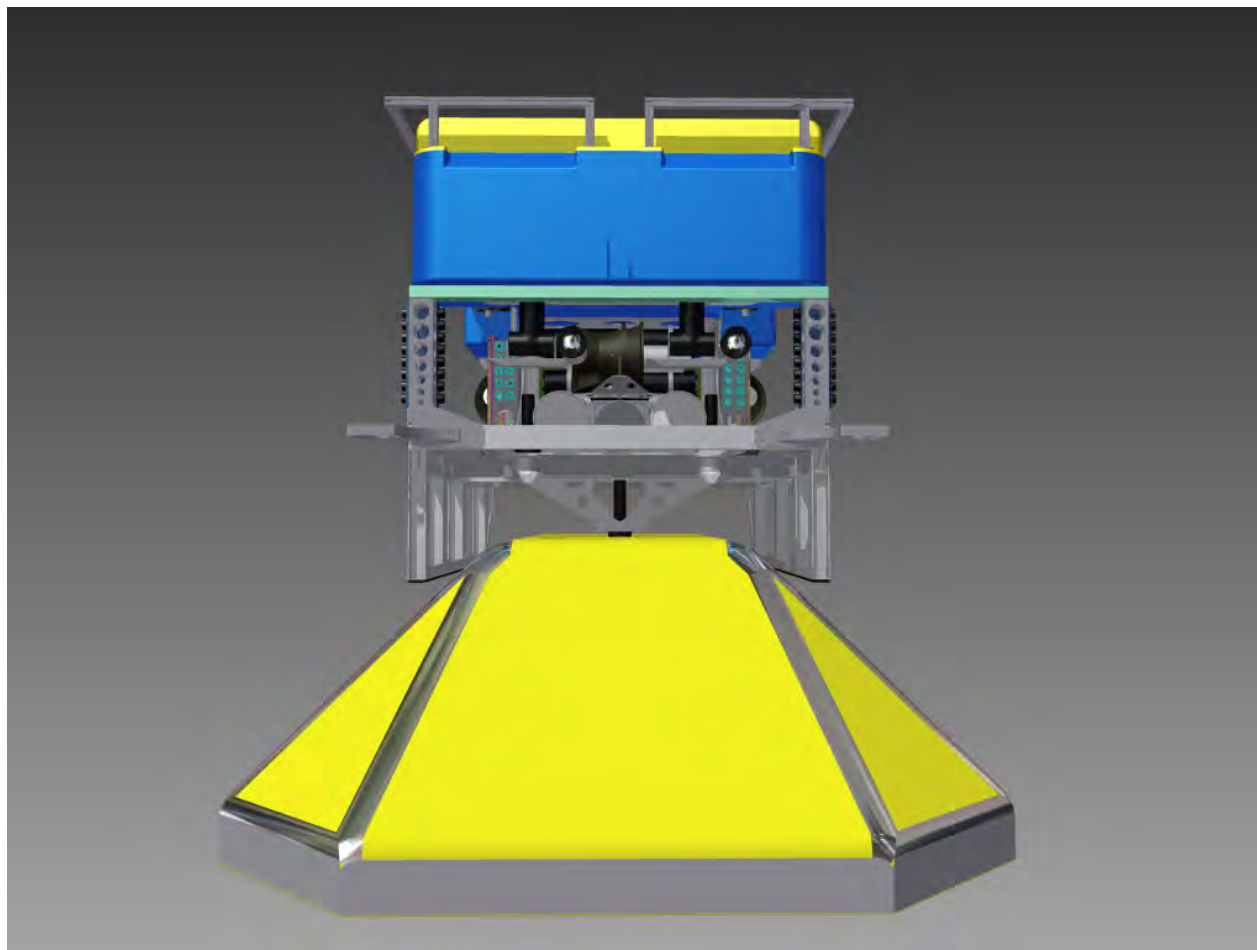
OOI skid  
Releases for packages  
No aft science bay  
Smaller basket







# Package Attachment



RSN Benthic Node

# Overboard Handling System: Layout

Existing Rapp Winch power van. Mounted on top of winch to use less deck space.

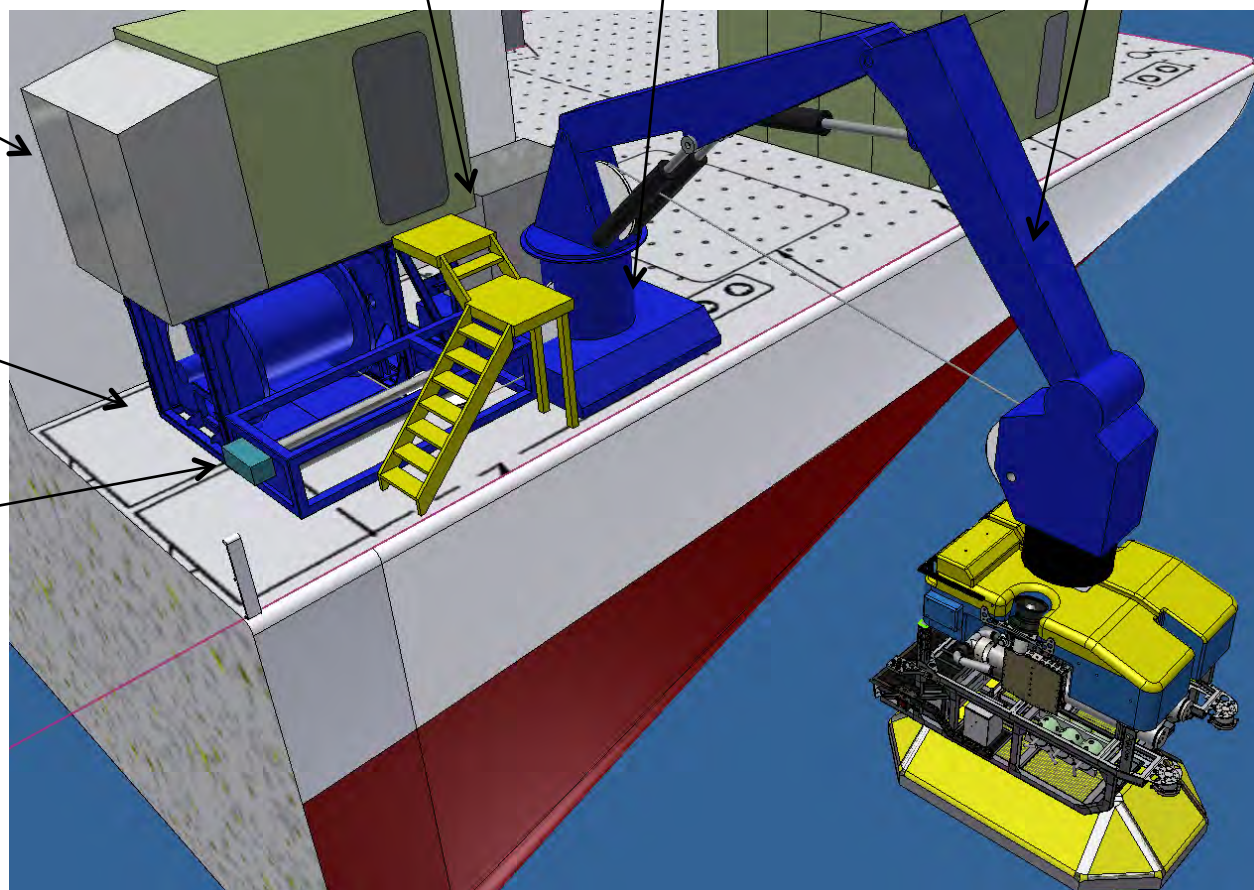
Recently purchased Airline Hydraulic HPU. Mounted on top of LARS Base to use less deck space.

In-house LARS Base. Allows winch to mount to either forward or inboard edge depending on ship.

North Pacific Crane Co. LARS Includes latching docking head.

Existing Rapp Winch with new drum and Lebus for 0.842" cable

New Rapp Level Wind for 0.842" cable in new side-mount position. Braced against LARS base for reduced winch deck loads.





# Overboard Handling System: Specs



## LARS Crane

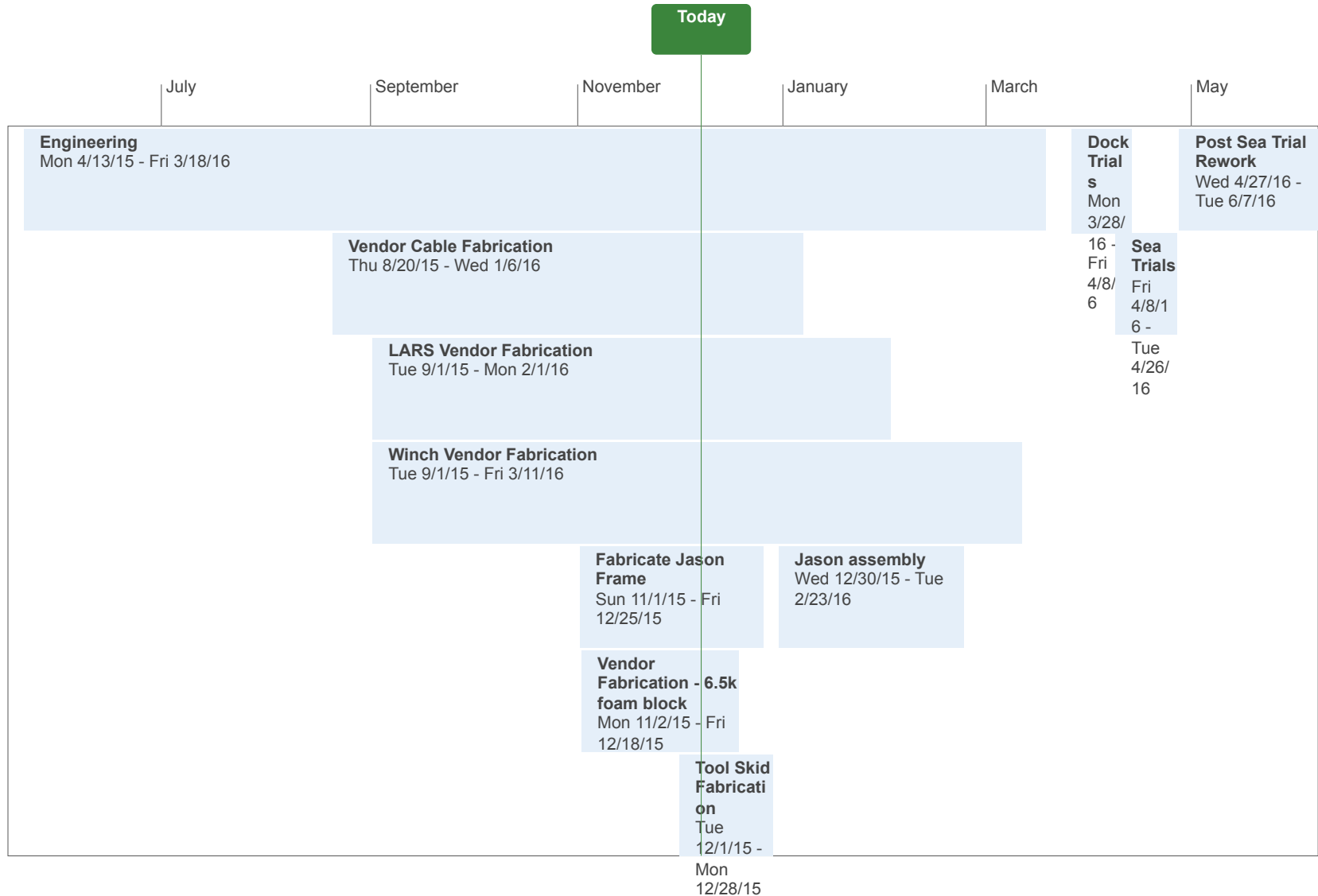
- 20 ft reach in Sea State 4 (package deployment)
- 14,000 lb capacity includes 4,000 lb packages
- Features snap load attenuation via gas accumulator springs
- Latching docking head with powered sheave to prevent cable slack in sheave train
- Can ship knuckled as one piece with base and HPU

## Winch

- Carries 5,000 m of 0.842" cable
- Active heave compensation reduces motion during deployment
- Can be converted back to original 0.681" cable use using original drum and level wind

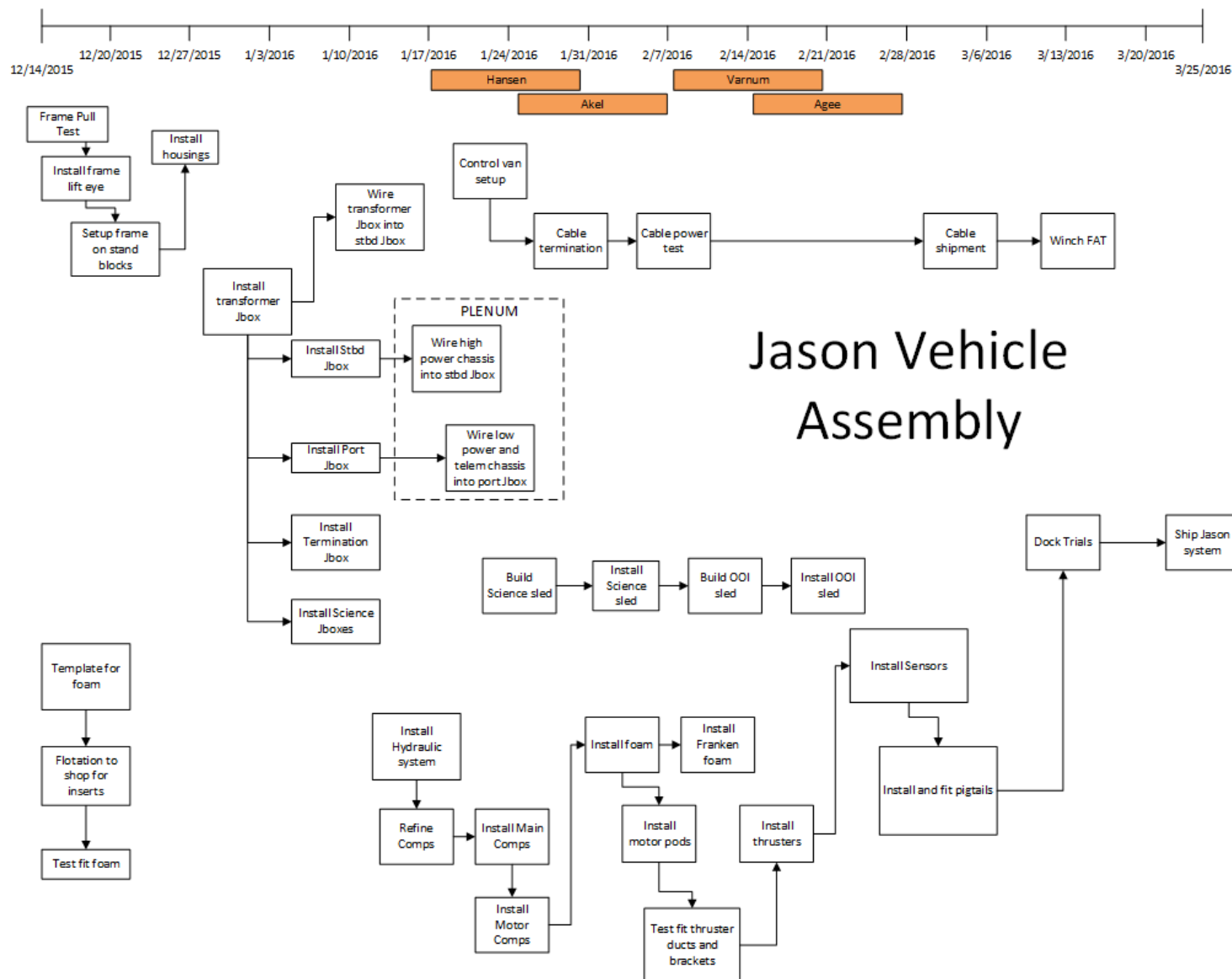


# Schedule

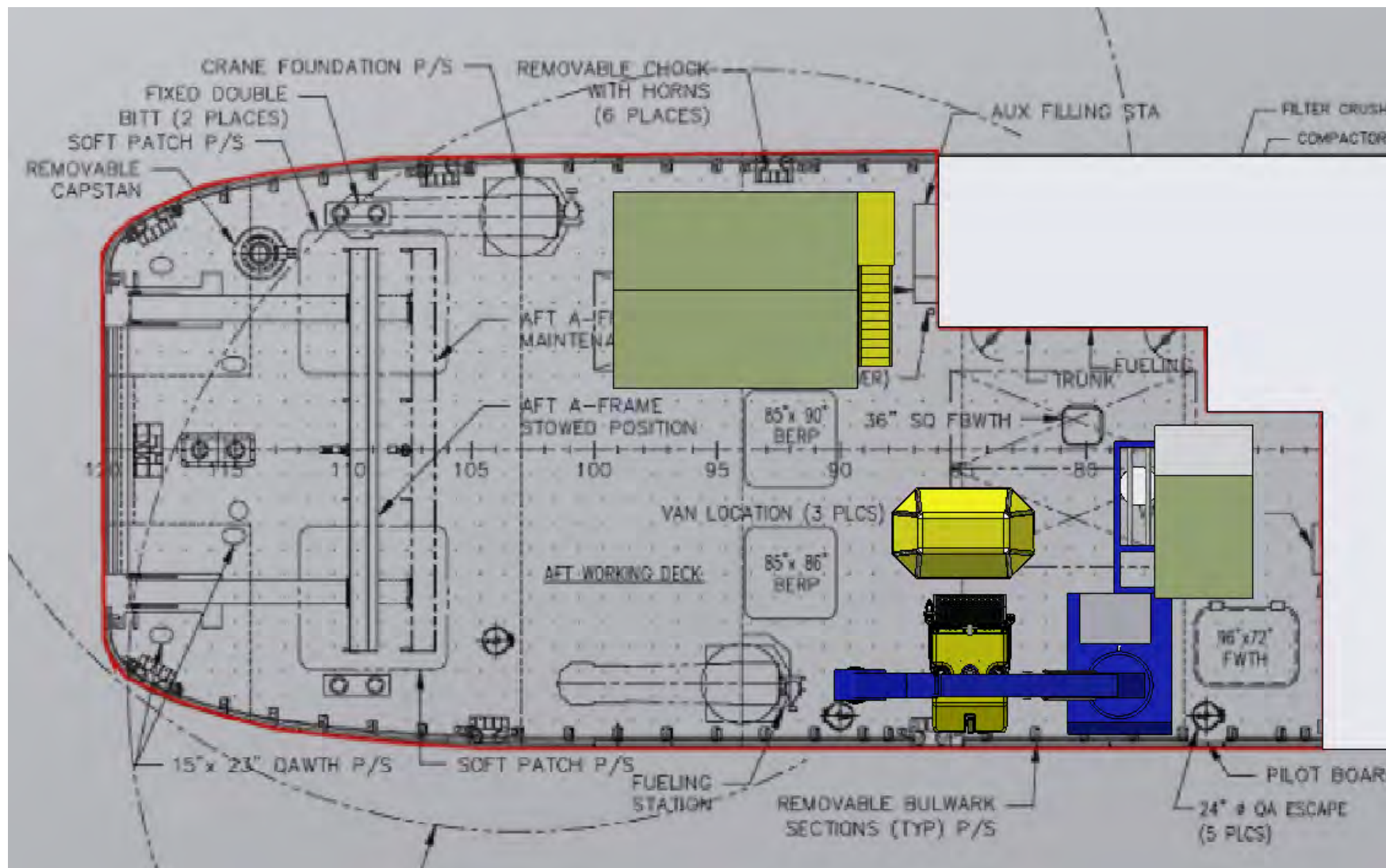




# Schedule

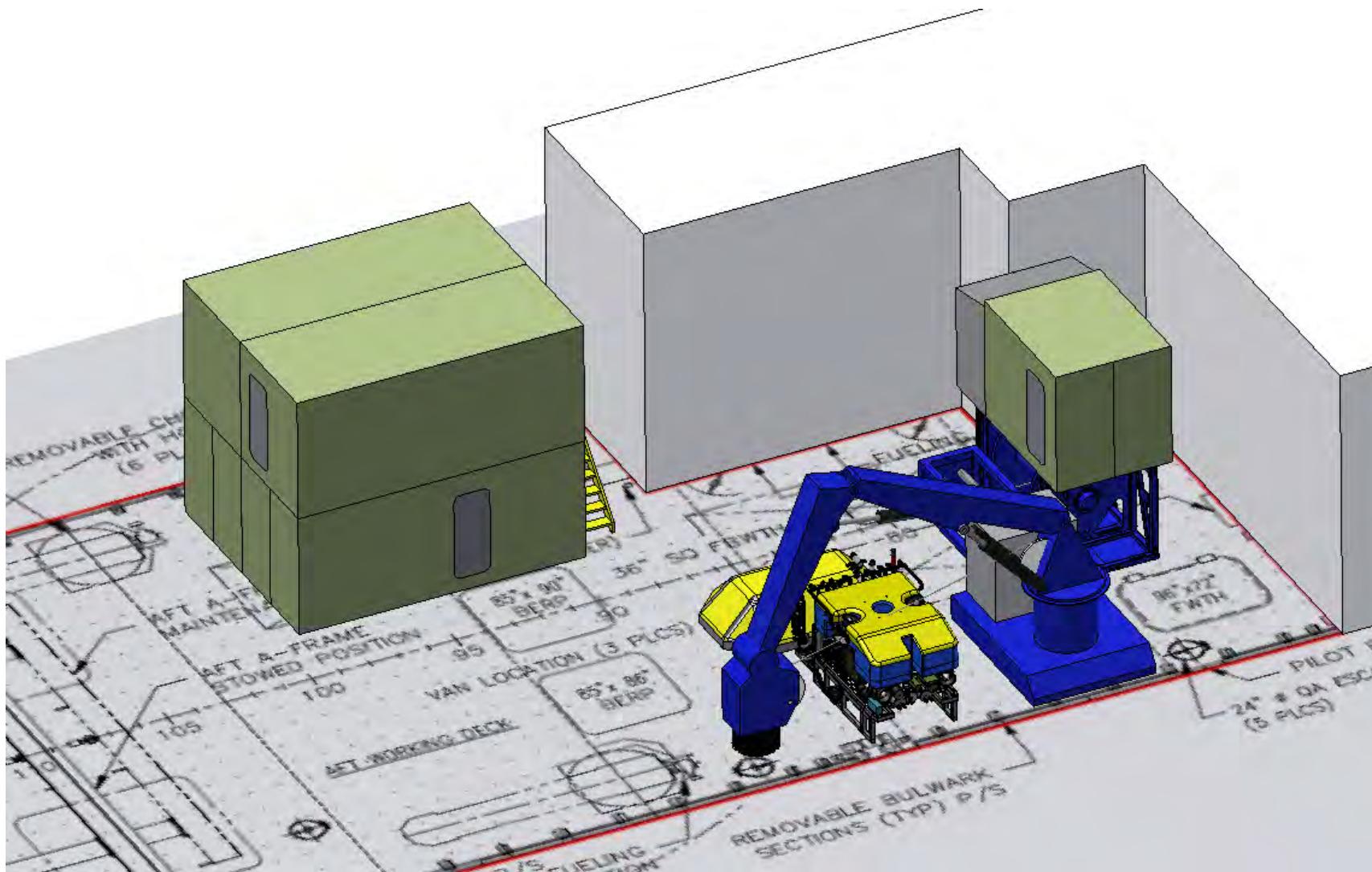


# Sikuliaq



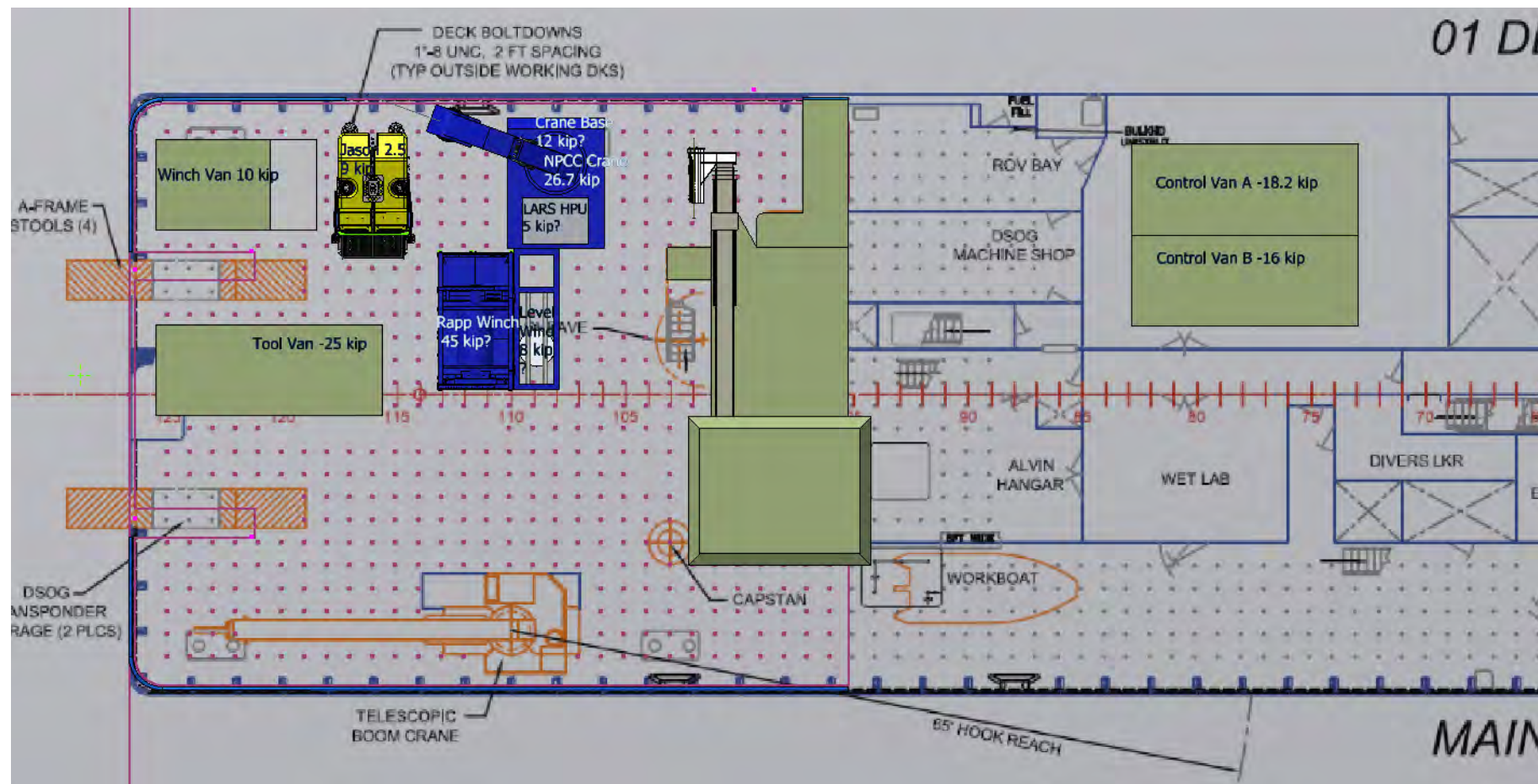


# Sikuliaq





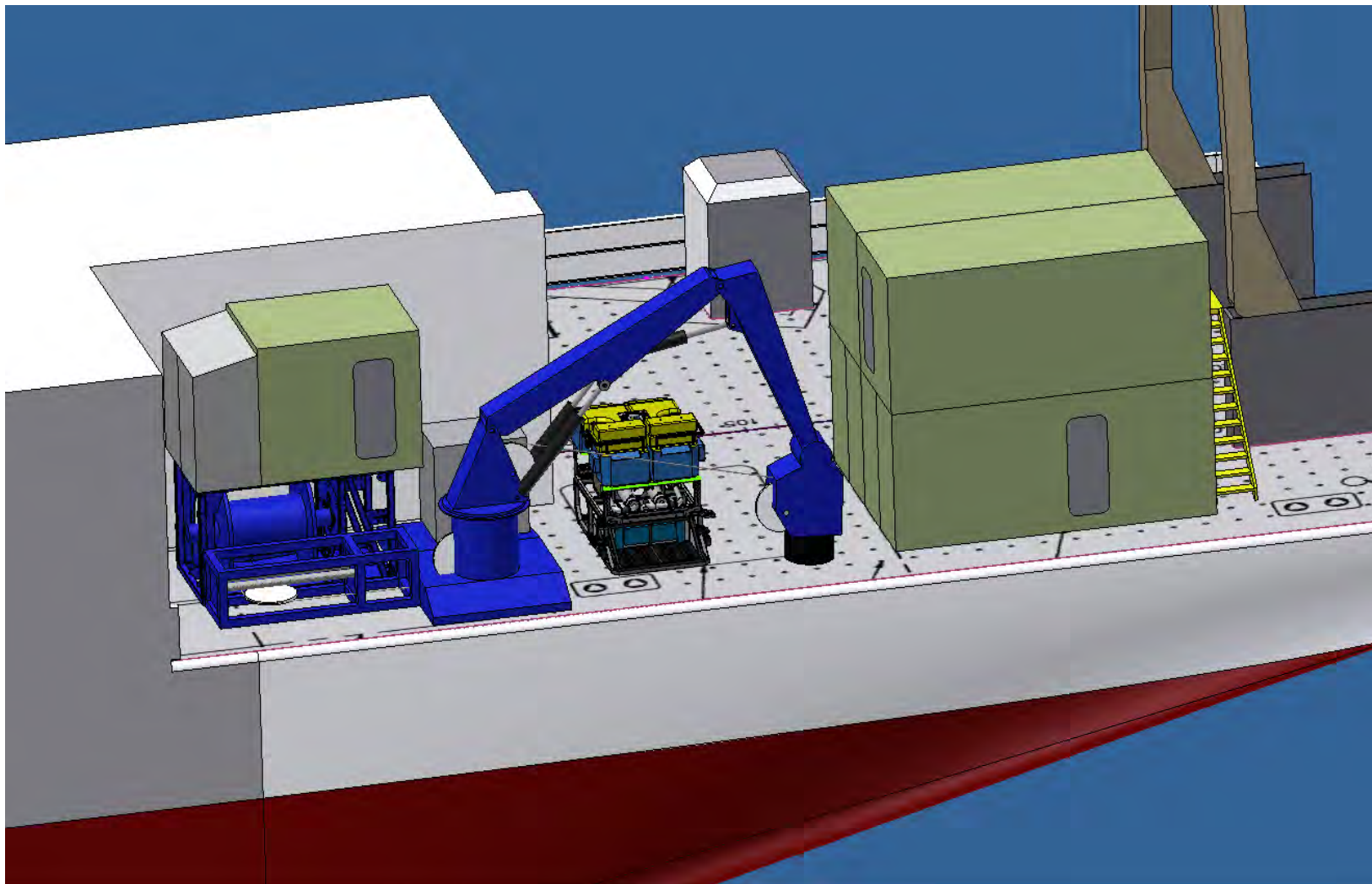
# Atlantis







# Thompson





# *Alvin* Upgrades



## Navigation

- Top Lab now using updated navigation software (Nav-g/Navest); DVLNav officially retired. Progressive development and implementation of *Alvin* navigation post-processing software (developed by *Sentry* team). End goal: produce daily semi-automated, first-cut navigational maps and data for science use.

## Reson Sonar

- Reinstalled and test operated during AT29-04. Some follow-on evaluation required to complete installation.

## BlueView Sonar

- Installed for AT29-02 and AT29-04, initial evaluation for regular use on *Alvin*. Overall sonar is excellent but likely will install dedicated computer in-hull to improve usability.



# *Alvin* Upgrades



## **In-Hull Toxicity/Flammability Testing**

- First opportunity to utilize new Navy-approved testing vendor. Testing expense is approximately half previous cost.

## **Kongsberg PATZ Cameras**

- Cameras returned from dome repair and are working well