Telepresence Technology and Applications on UNOLS Ships

Dwight F. Coleman

Director, URI-GSO Inner Space Center



THE UNIVERSITY OF RHODE ISLAND

GRADUATE SCHOOL OF OCEANOGRAPHY



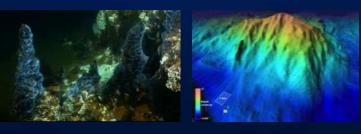
Telepresence-Enabled Ocean Research and Exploration:

Background –

Ships/ROVs - NOAA Ship Okeanos Explorer and E/V Nautilus Deep Discoverer and Hercules Shore Facilities - Inner Space Center and ECCs Education and Outreach – Exploration Now, Unknown Ocean

Pilot Project – ROV Jason (NDSF) and R/V Atlantis

Future Plans for Telepresence with UNOLS Facilities











OCEAN EXPLORATION TRUST



NOAA Ship Okeanos Explorer



E/V Nautilus





ROV *Hercules*

ROV Deep Discoverer



Ship-to-Shore Telepresence



THE UNIVERSITY OF RHODE ISLAND GRADUATE SCHOOL

OF OCEANOGRAPHY

Inner Space Center Mission Control









KEANOS EXPLORER 2012







Internet2

NOAA HQ, Silver Spring

NOAA NCDDC, Stennis







NOAA PMEL, Seattle

University of New Hampshire



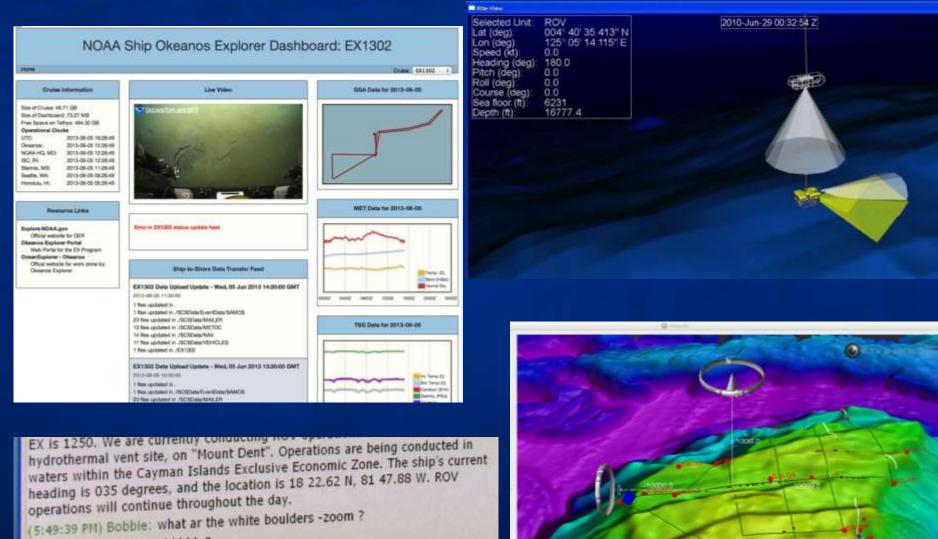






University of Haifa, Israel

Ocean Exploration Center, Mystic

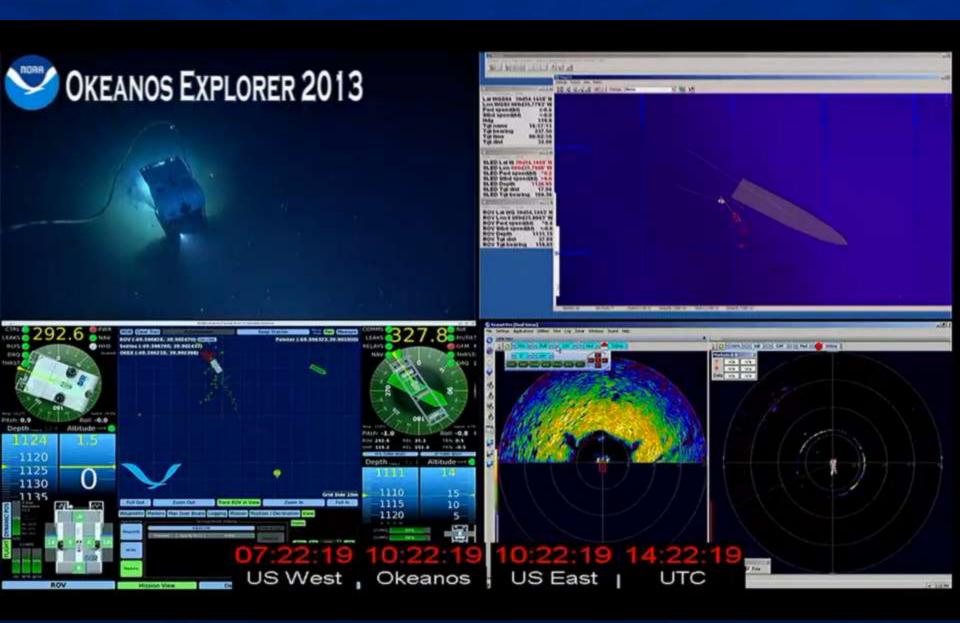


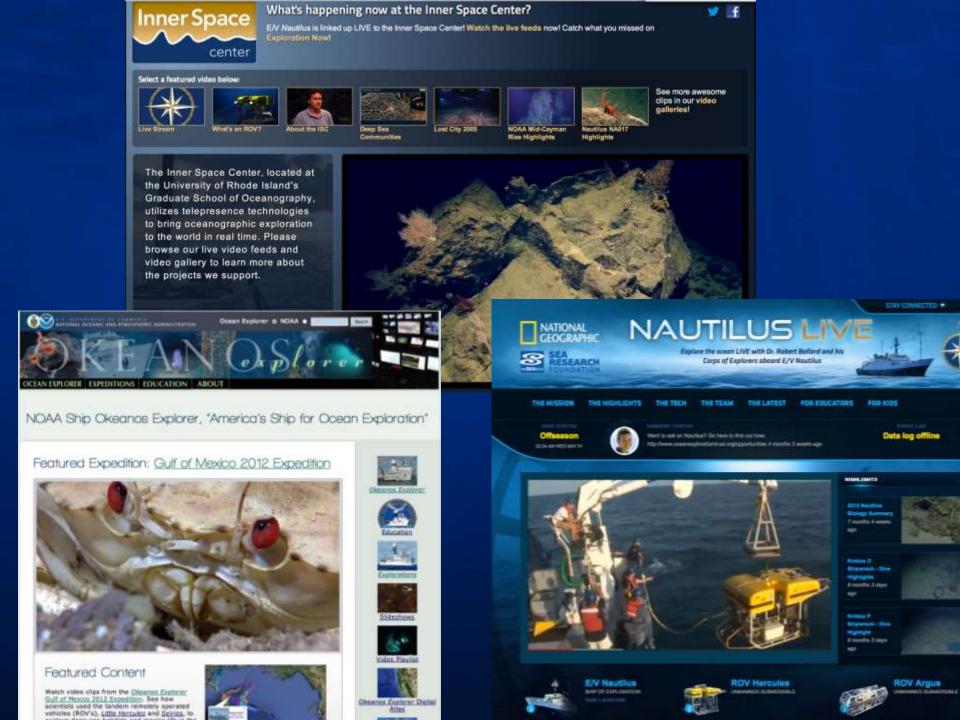
(5:50:16 PM) Bobbie: ahhhhh ?

(5:50:32 PM) jamesonclarke: limestone?

(5:50:49 PM) mikecheadle: talc?

A fort & purt @ just @









Production Control and Studio



Mystic Aquarium – Nautilus Live Theater, CT



Exploratorium, San Francisco



Cape Henry Collegiate School, VA



Scottsdale, AZ Boys & Girls Club

THE UNKNOWN OCEAN

LIVE INTERACTIVE EDUCATIONAL PROGRAMMING UTILIZING SHIP-TO-SHORE TELEPRESENCE TECHNOLOGY











Mystic Aquarium Unknown Ocean Kiosk

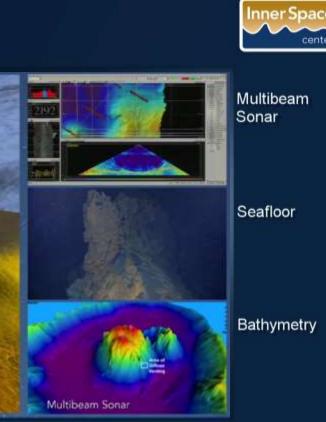
MYSTIC AQUARIUM – NAUTILUS LIVE THEATER

Exploration Command Station



The Unknown Ocean

Mapping the Seafloor







The Unknown Ocean: Exploring Inner Space



Live Feeds from the E/V Nautilus



EXPLORATION NOW

A Portal for Discovery







Mystic Aquarium – Nautilus Live Theater





LIVE

OCEAN EXPLORATION HUB

2013 ROV Shakedown and Field Thats in the U.S. Northeast Canyons: Follow along as the Okeanos Explorer team "shakes down" a new remotely operated vehicle (ROV) capable of diving to depths of 6:000 meters.



9

















<u>Telepresence – Pilot Project for UNOLS:</u>

- Project conceived after last UNOLS Council Meeting sponsored by ONR and NSF
- > Targeted funded NSF projects that planned to use the ROV Jason
- Focus was on education and outreach, not remote science
- Found willing PI's with existing outreach programs to use Jason on the R/V Atlantis – July 2013

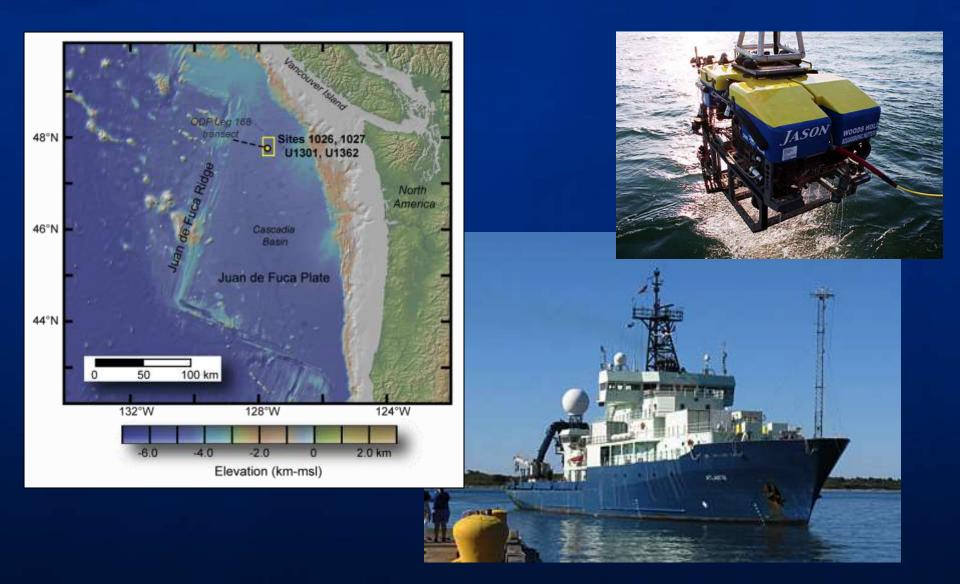
Doug Toomey, Anne Trehu, Dean Livelybrooks Cascadia Initiative – Ocean Bottom Seismometers

Andrew Fisher, Eastern Flank of Juan de Fuca Ridge – Hydrogeology, Geochemistry, Microbiology at CORK sites

Conducted science communication training for the educational teams onboard to support live ship-to-shore interactions and video broadcasts about the research

National Deep Submergence Facility





National Deep Submergence Facility



















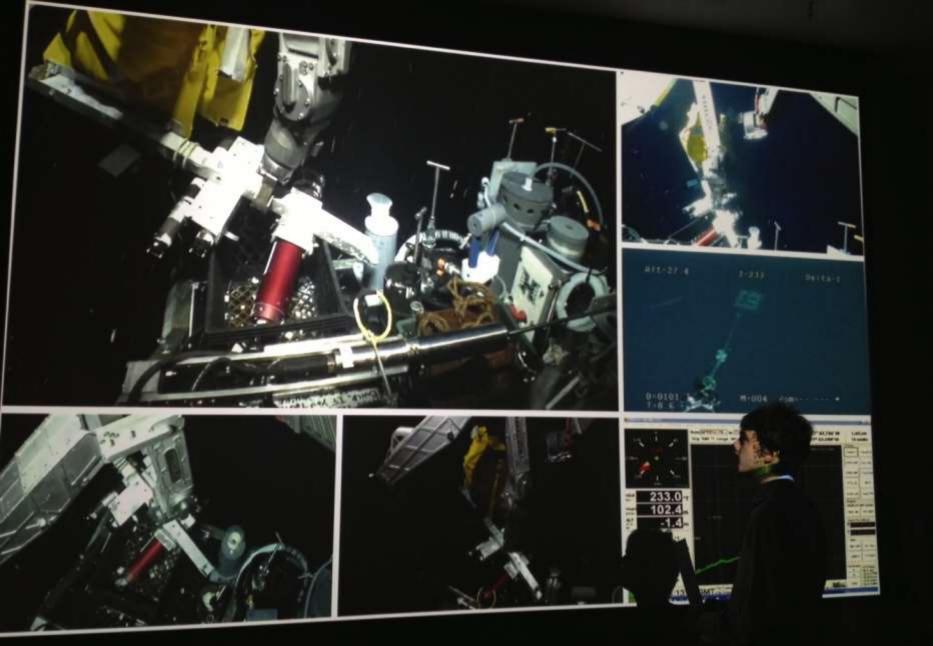
Mobile Telepresence Unit (MTU)













Oceanography

VOL.27, NO.1, SUPPLEMENT | MARCH 2014

New **Frontiers** in Ocean Exploration

The E/V Nautilus 2013 Gulf of Mexico and Caribbean Field Season

GUEST EDITORS | KATHERINE L.C. BELL, MICHAEL L. BRENNAN, AND NICOLE A. RAINEAULT

EXPANDING THE TELEPRESENCE PARADIGM

Live Interactive Programming from R/V Atlantis and ROV Jason

By Dwight F. Caleman, Dean Livelybrooks, Sharon Katz Cooper, Gregory Mulder, Andrew T. Fisher, Anne M. Tréhu, and Douglas R. Toomny

Since 1981, Robert Ballard has envisioned a concept of ocean exploration with multiple ships collecting video and data from the depths of the world ocean and broadcasting discoveries in real time through ship-to-shore satellite technology. In 1989, the telepresence vision was realized when the first Jason Project broadcasta employed ROV technology developed by the Deep Submergence Laboratory at Woods Hele Oceanographic Institution (WHOI). Those early telepresence-enabled broadcasta delivered live educational programming to vast audiences who could participate in the exploration as it was happening.

The vision expanded in 2003 when the Institute for Exploration developed a new suite of ROV and telepresence technologies as part of a portable system that was installed on ships of opportunity. In 2007, those expeditions began to feature live broadcasts 24 hours a day to audiences on the Internet and at venues such as Mystic Aquarium, all made possible through a prototype version of the Inner Space Center (ISC) at URI GSO. Since 2009, the telepresence paradigm has grown substantially with the development of E/V Nantilus, introduction of the NOAA Ship Okeanos Explorer, and construction of the permanent ISC. Live broadcasting can now originate from two ships of





Figure 1 (above), BOV Jeson, part of the UNOLS National Deep Sebmergence Facility operated by Woods Hole Oceanographic Institution. Photo credit: Tore Below, Houds Hole Oceanographic Institution

exploration that have dedicated ROV and telepresence systems installed on board and that conduct field work up to six months each year.

Beginning in 2013, the telepresence-enabled exploration paradigm expanded yet again to involve more ships, including the Schmidt Ocean Institute's R/V Falkov, the University of Washington operated R/V Thomas G. Thempaos, and the WHOI operated R/V Allamis (the latter two ships are part

of the University-National Oceanographic Laboratory System [UNOLS]). Many more live feeds could now be received and distributed through the ISC and used for live video production associated with the Exploration Now program (see page 22). We report here on two specific telepresence -enabled projects conducted during the summer of 2013 on board R/V Arlantis that used the Jaum ROV system (Figure 1). This project represents a millestone in the development and use of telepresence technology for UNOLS platforms, leading to even greater expansion of the telepresence vision for the academic research fleet, with several new ships clated to come on line in the new future.

Challenges

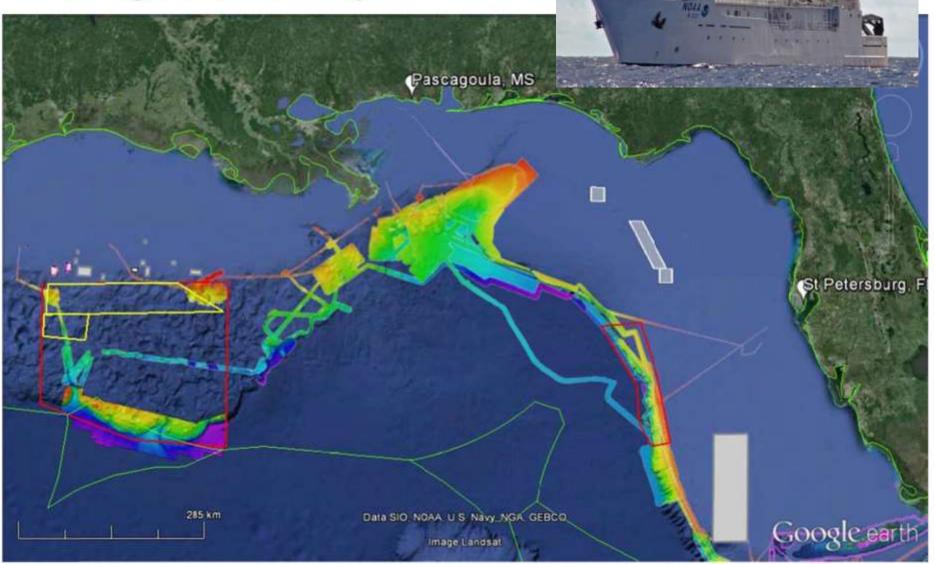
- Need for more technical support satellite operations, network engineering, telepresence systems, production logistics, shore
- Funding can't rely on supplemental funding need to plan for and budget for telepresence activities through the proposal process

<u>Successes</u>

- Outreach lots of interest in the scientific activities, conducted more than 100 live interactions with various audiences
- Data transfers to shore for remote science collaboration
- Bonus supported Chris Reddy's shore-based participation during Dave Valentine's cruise in October
- Leading to more telepresence-enabled cruise opportunities

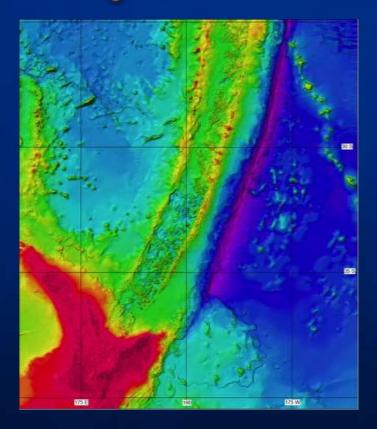


EX1402 Leg 3 Overview Map



Tim Shank's project:





Kermadec Trench, April 10 to May 20, 2014



R/V Thompson



NAUTILUS EXPLORATION PROGRAM



NSF INSPIRE OCE1344250

TREET: Transforming Remotely-conducted Research through Ethnography, Education, & Rapidly-evolving Technologies



TREET Participants:

Interdisciplinary Principal Investigators: Chris German, WHOI Katy Croff Bell, OET Zara Mirmalek, Harvard University Amy Pallant, Concord Consortium Kanna Rajan, MBARI Early Career Scientists & Undergraduates Anna Michel, WHOI Scott Wankel, WHOI

Masako Tominaga, Michigan State University + students Eric Mittelstaedt, University of Idaho+ students Pete Girguis, Harvard University + students Chris Roman, University of Rhode Island <u>Expert Mentors</u> Steve Carey, University of Rhode Island Cindy Van Dover, Duke University



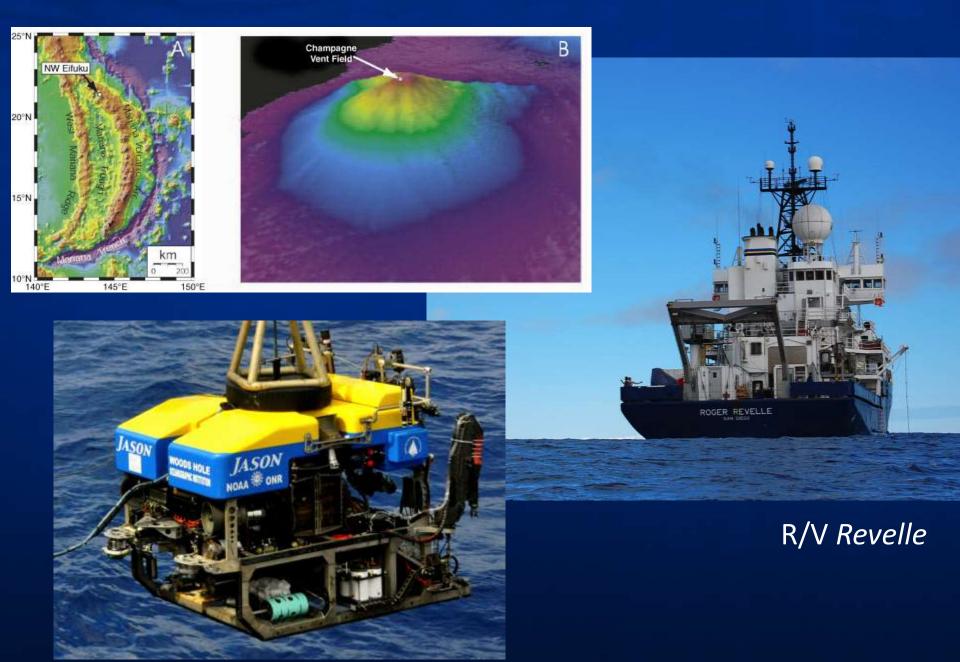
TREET Co-Pls, Early Career Scientists, Expert Mentors, + 8 Undergraduates (not pictured, pending permission to use their images)

a Phone in

TREET Focus & Goals

- To understand and capture the ways in which telepresenceenabled cruises
 - further ocean science and exploration
 - can be advanced with new technologies and social practices
 - allow more access to research environments
- To develop education tools for undergraduate training
- To produce an ethnographically informed study to feed forward in developing new technologies and social process for telepresence communities

Craig Moyer and Bill Chadwick's project, Nov-Dec, 2014:



Smithsonian National Museum of Natural History





C

17





*

Silver Spring



R/V Sikuliaq

Future RCRV(s)



R/V Neil Armstrong and R/V Sally Ride

THE UNIVERSITY OF RHODE ISLAND

GRADUATE SCHOOL OF OCEANOGRAPHY

R/V Endeavor





JOIDES Resolution



