WHAT TO DO WITH AN MRU

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UNOLS East Coast Winch Pool

MRU

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Mount it to a winch

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Mount it to a ship

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Active Heave Compensation

Limitations

Only one overboarding point

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Limitations

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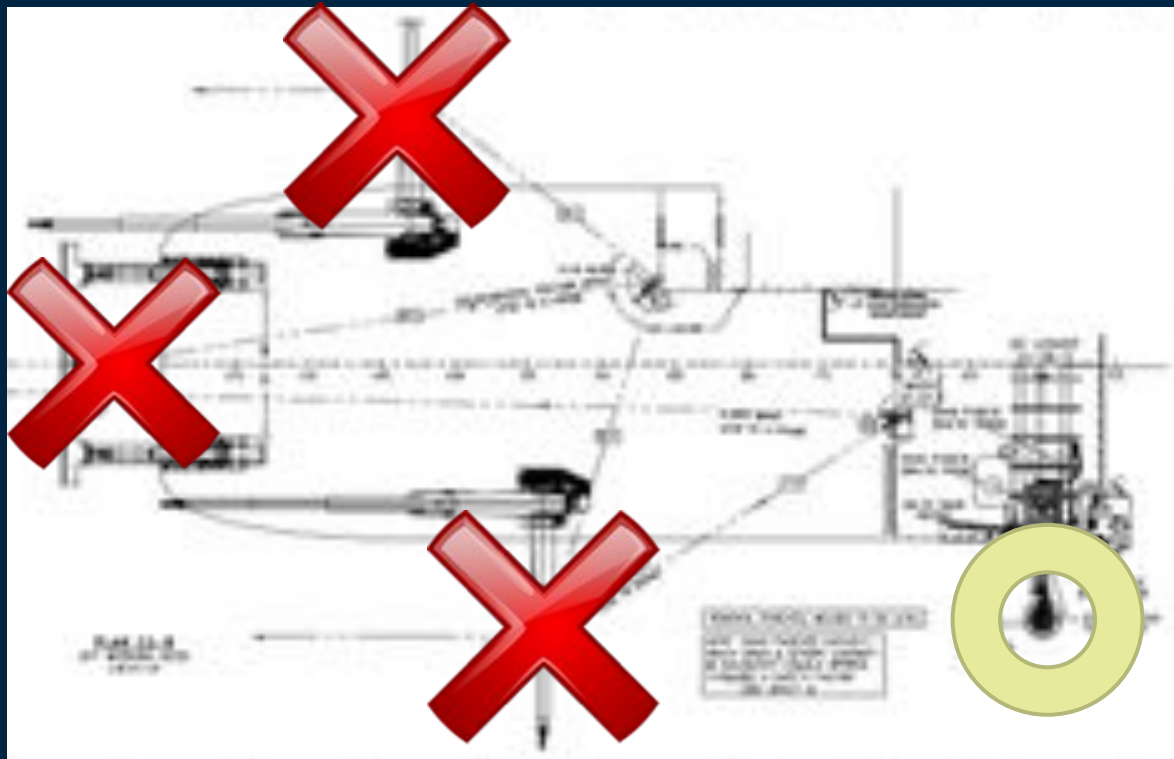
What to do?

- Add external processing
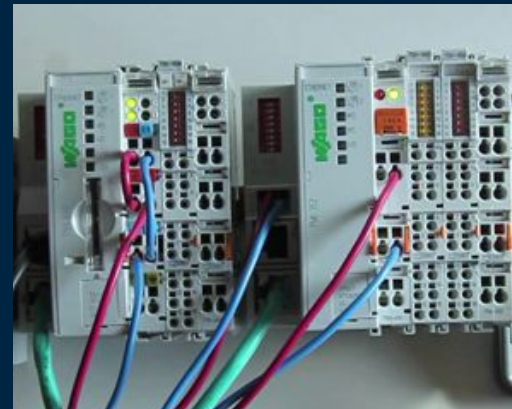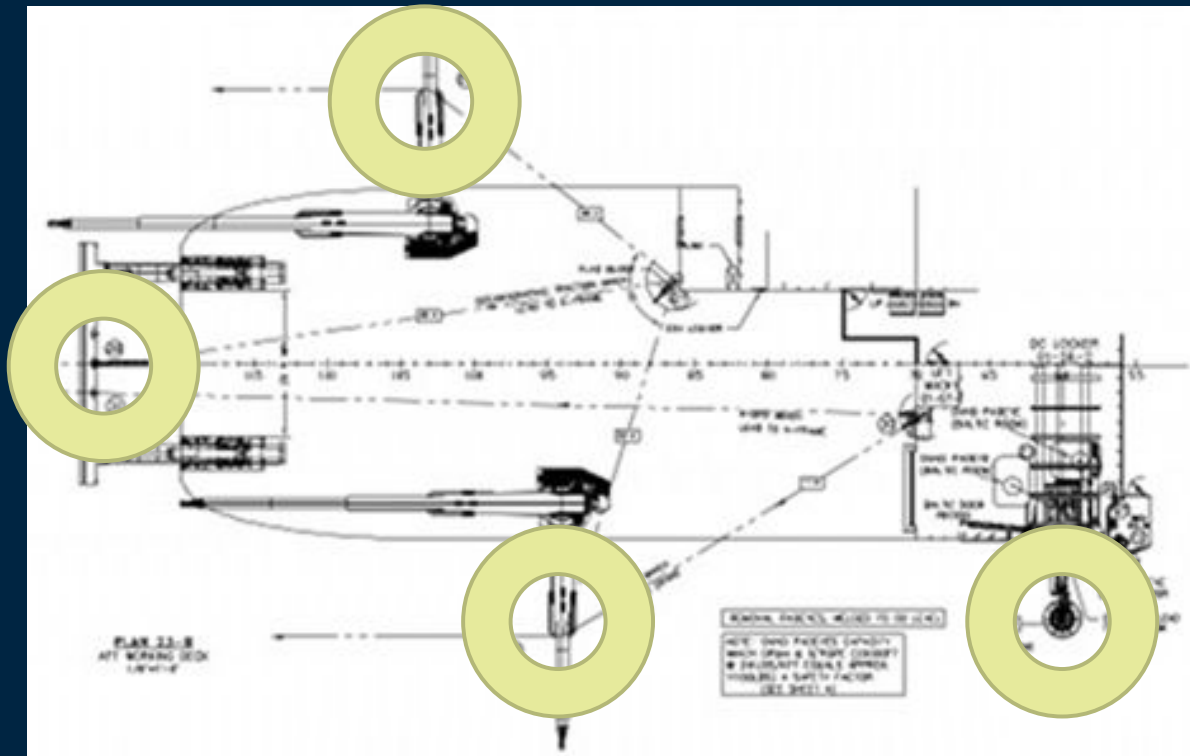
- Quaternion Math for rotations

- Analogue output for each overboarding point

- PLC or Raspberry PI with dedicated communication lines

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The Possibilities

Issues

Latency

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Discussion