Ocean Class AGOR Acquisition Update RVOC



PEO

SHIPS



Office of Naval Research

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Ocean Class AGOR Shipyard: Dakota Creek Industries Anacortes, WA

Design Agent Guido Perla & Associates Seattle, WA





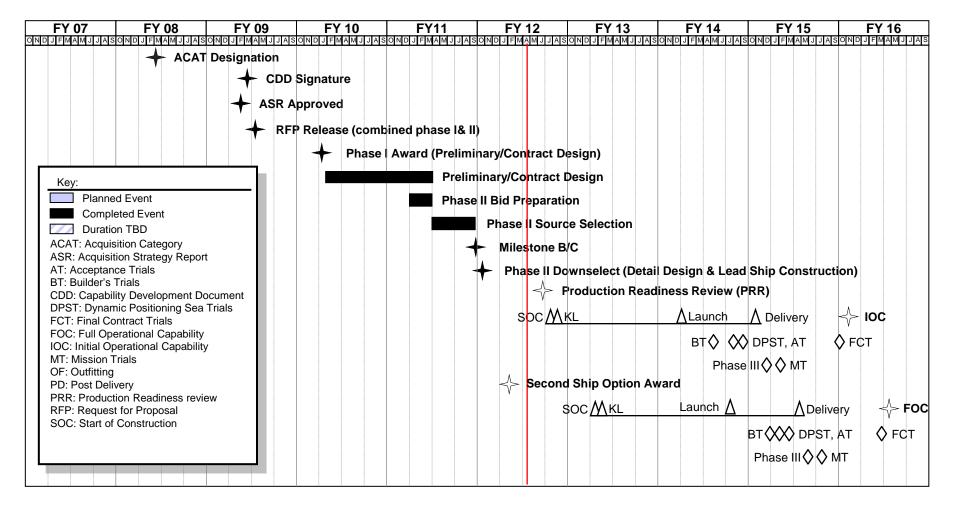
- Phase II: Detailed Design & Construction
 - Contract award (AGOR 27)
 - Option for AGOR 28
 - Start of Construction (AGOR 27)
 - Keel Laying (AGOR 27)
 - Start of Construction (AGOR 28)
 - Launch (AGOR 27)
 - Launch (AGOR 28)
- Deliveries:

~ October/November 2014 & April/May 2015

14 October 2011 February 2012 June/July 2012 ~Jul/Aug 2012 ~Nov/Dec 2012 Jan/Feb 2014 Jul/Aug 2014

Ocean Class AGOR Acquisition Schedule







General Characteristics

Length overall	238'-0"
Waterline length	230'-0"
Maximum breadth	50'-0"
(molded)	
Depth to Main Deck	22'-0"
Draft	15'-0"
Sustained speed	12 knots
Max speed (estimated)	12.8 knots
Installed brake	2,324 hp
horsepower	
Installed total power	3,952 kw



General Characteristics

Lightship weight (with 5.5%	2,058 LT
design and build margin)	
Full load displacement	2,916 LT
(without SLA)	
Range (at sustained speed)	11,500 nm
Endurance	40 days
Accommodations	20 single crew staterooms
	12 scientist double staterooms
Handling Equipment	Main Crane–22k lbs at 70ft static
	Portable crane 2k lbs at 30 ft
	Traction winch – 9/16 & .680 or .681
	A-frame, 2 hydro winches w/two stbd
	side handling devices with mo-comp.



Power Plant and Propulsion

- Integrated diesel electric drive
- Four diesel gensets
- Two AC propulsion motors and drives
- Two CPP's
- Bow thruster, azimuthing
- Stern tunnel thruster



Unique/Novel Features

- Hull form to divert bubbles from sonar area
- Controllable Pitch Propellers (CPP's) with variable speed motors for improved efficiency over varying modes of operation
- Cranes, CTD Handling and Starboard Side Handling Systems reach to waterline for improved safety and load control
- Condition based monitoring system for main propulsion, major auxiliaries and ship control equipment
- Centralized fresh water cooling system
- HVAC variable air volume and regenerative heat



• Ship has been designed with space, weight and power reservations for the following sonar systems:

Equipment	Manufacturer ¹	Model ¹
Deep Water Multibeam Survey	Kongsberg	EM-122
System		
Mid Water Multibeam Survey	Kongsberg	EM-710
System		
Subbottom Profiler	Knudsen	Chirp 3260 with 16 Massa TR-1075
		Array
Single Beam Survey System	Kongsberg	Designed for:
		EA-600 (12, 38, 120, 200 kHz)
Acoustic Doppler Current Profiler	Teledyne RD	Ocean Surveyor 38 & 75 or 150 kHz
	Instruments	Workhouse Mariner 300 kHz
Acoustic Navigation and Tracking	Kongsberg	HiPAP 500 Gantry System can be
System		used with several systems.

¹ from Mission Equipment Specification



Performance: Bubble Sweepdown and Dynamic Positioning

Bubble Sweepdown

• Model tests have demonstrated favorable results.

System Spec requirement: Flow streamlines originating at the ship's stem shall pass no closer than 2 meters, measured transversely, from the centerline of the Deep Water Multibeam Survey System sonar transducer receive array.

Dynamic Positioning

- Analytical predictions meet requirements.
 - System Spec station keeping requirement: Hold position within ± 5 meters in 35 knot wind and 2 knot beam current with ship headed into collinear wind and SS5 waves.



Performance: Seakeeping and Maneuvering

<u>Seakeeping</u>

•Analytical predictions show 100% operability in SS4 and 86%/88% operability in SS5 for arrival load/full load, with roll stabilization tank.

> System Spec defines operability as:

 \checkmark Roll < 3 degrees, pitch < 2 degrees

 ✓ Vertical acceleration < 0.15 g and lateral acceleration < 0.05 g at Main Deck amidships at deck edge

Maneuvering

- Model tests demonstrate meeting System Spec requirements.
 - Directionally stable
 - Turning diameter < 4 ship lengths</p>



Performance: Noise

- Analytical predictions meet System Spec requirements:
 - Airborne noise in all interior spaces and topside locations at sustained speed and during station keeping
 - Sonar self-noise at sustained speed
 - Radiated noise goal at 8 knots



SMR/Design Comparison

SMR Parameter	Capability or Characteristic	Design
Accommodations	 20 to 25 science berths (original SMR) 	Meets: 24 in 12 doubles
	, ,	 Meets target: 20 singles
Working deck area	 1,500 – 1,800 sq ft aft of deckhouse 	 Exceeds: 1,873 sq ft
		• Meets: 2,557 sq ft
	• 80 ft clear deck area on one side	• Meets: 80 ft
Laboratory Area	· ·	 Exceeds: 1,023 sq ft
	• Wet lab 350 - 400 sq ft	• Meets: 398 sq ft
	• Computer lab 250 - 300 sq ft	• Exceeds: 311 sq ft
	• Staging Bay 250 – 300 sq ft	• Exceeds: 303 sq ft
Science Storage	4,000 to 5,000 cu ft	Exceeds: 5,017 cu ft
Science payload	150 to 250 LT	Meets target: 250 LT



SMR/Design Comparison

SMR Parameter	Capability or Characteristic	Design
Vans	Two 8 ft by 20 ft deck vans with target of capability to carry additional vans	Meets target: 3 vans
Towing		MeetsMeets
Sustained Speed	10 to 11 knots through SS4 12 to12.5 kts at 80% MCR calm seas	Meets: 12 kts at 80% MCR in calm seas
Endurance	40 to 45 days	Meets: 40 days
Range	Up to 10,800 nm at optimal transit speeds	Exceeds: 11,500 nm at sustained speed
Seakeeping	Maximize ability to work in SS5 and higher	Meets: 86% (arrival load) and 88% (full load) in SS5



SMR/Design Comparison

SMR Parameter	Capability or Characteristic	Design
Station keeping	35 knot wind, SS5, and 2 knot current	Meets: ± 5 meters in SS5
Track line following	 ± 5 meters of intended track with a crab angle of less than 45 degrees with 30 knot wind, up to SS5 and 2 knots current 	Meets: ± 5 meters in SS5
Handling Systems	winches; stern frame; CTD handling	Meets equipment requirements and capabilities
Ice strengthening		Meets: Ice Class D0

Questions?

ocean class