NSF Acoustics Brief

08 March 2011 Timothy Gates

Sonar Requirements

- Three main issues are required for optimum sonar performance
 - Installation orientation
 - Background ship noise
 - Bubble free environment

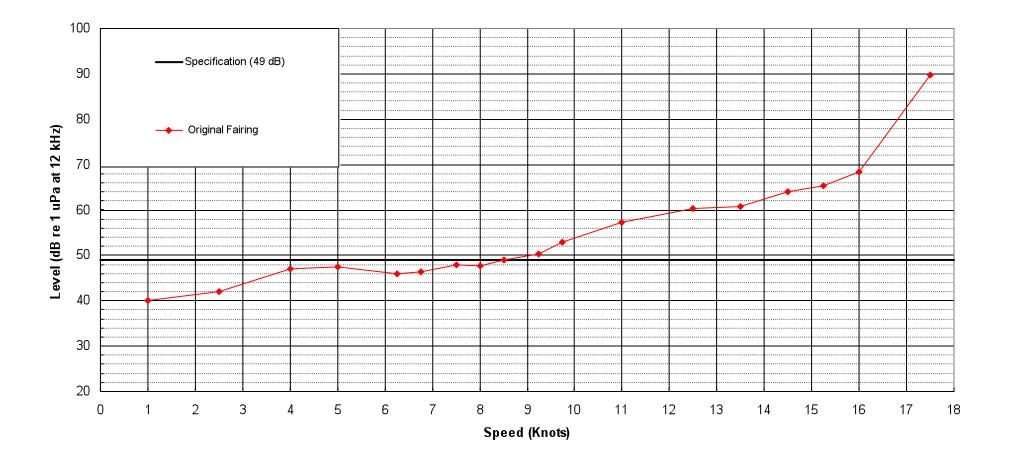
Typical Problems that can impact sonar performance

- Machinery Noise
- Hydrodynamic Flow Noise
- Propeller Cavitation
- Appendage Cavitation
- Sonar Interference
- Bubble Sweepdown

TAGS 60 Class Pre-Gondola

- Hydrodynamic Flow Noise
 - Fairing shape
 - Acoustic window roughness
- Appendage Cavitation
 - "Football" transducer fairing
 - Bilge keels
- Bubble Sweepdown

Original PATHFINDER Levels





New Sonar Fairing



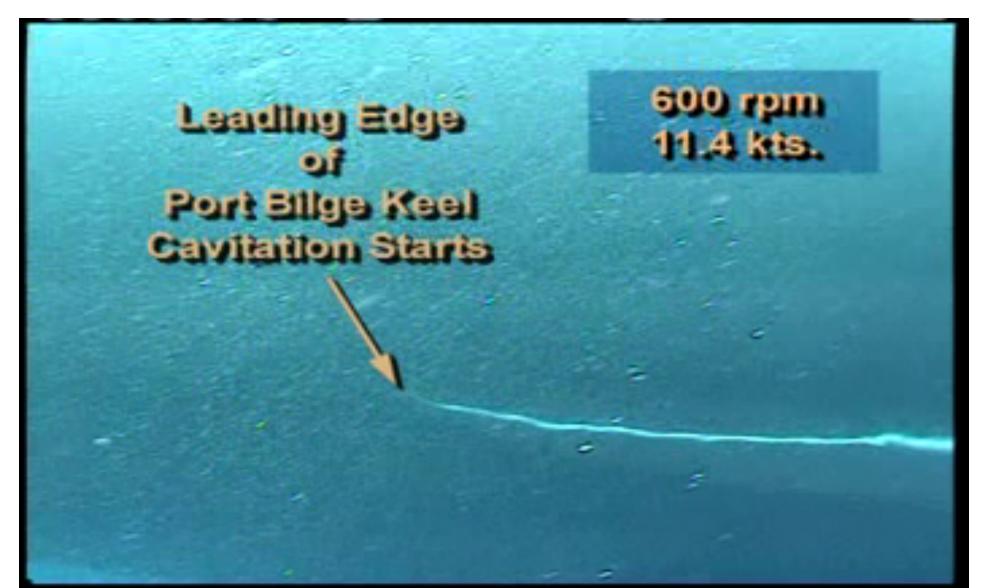
Original Transducer Pod



Re-designed Transducer Pod



Bilge Keel transient



Bilge keel pictures



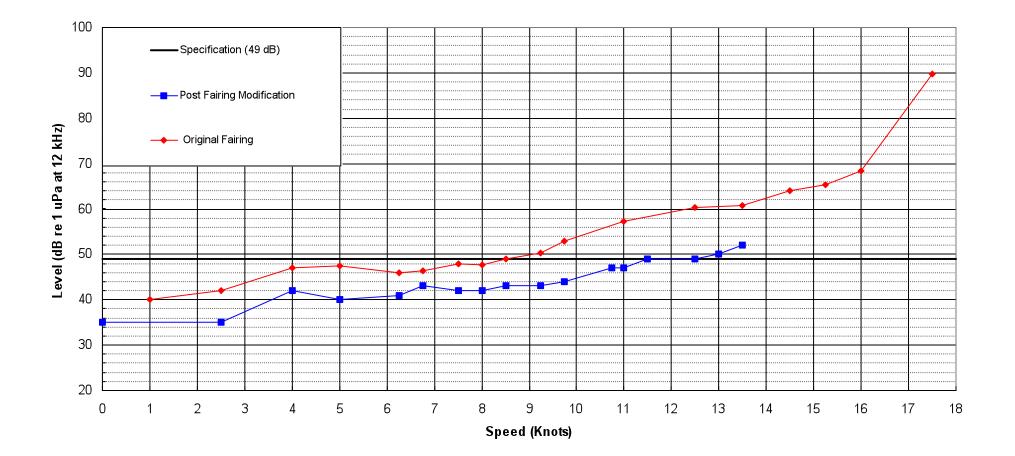
Bilge Keel pictures

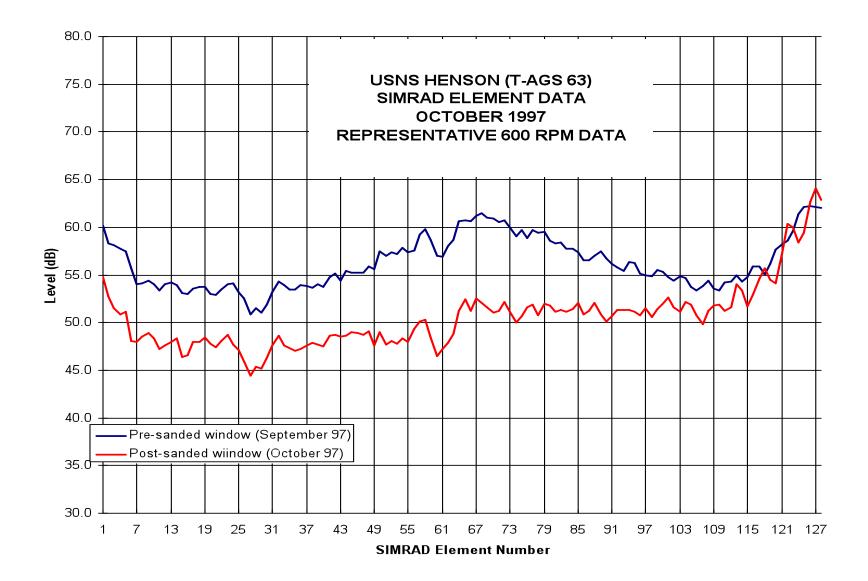


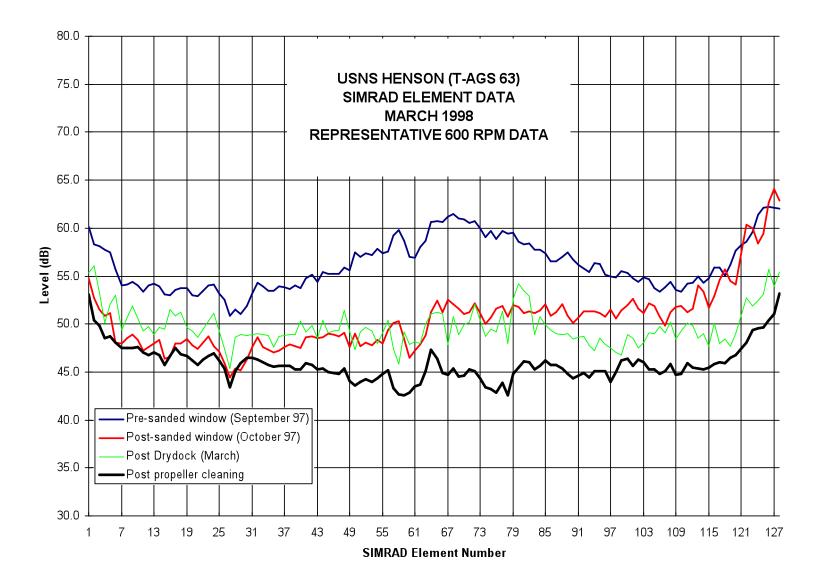
T-AGS 60 Class Current Configuration Bubble Diverter



Photo courtesy of Mike Carver NAVO

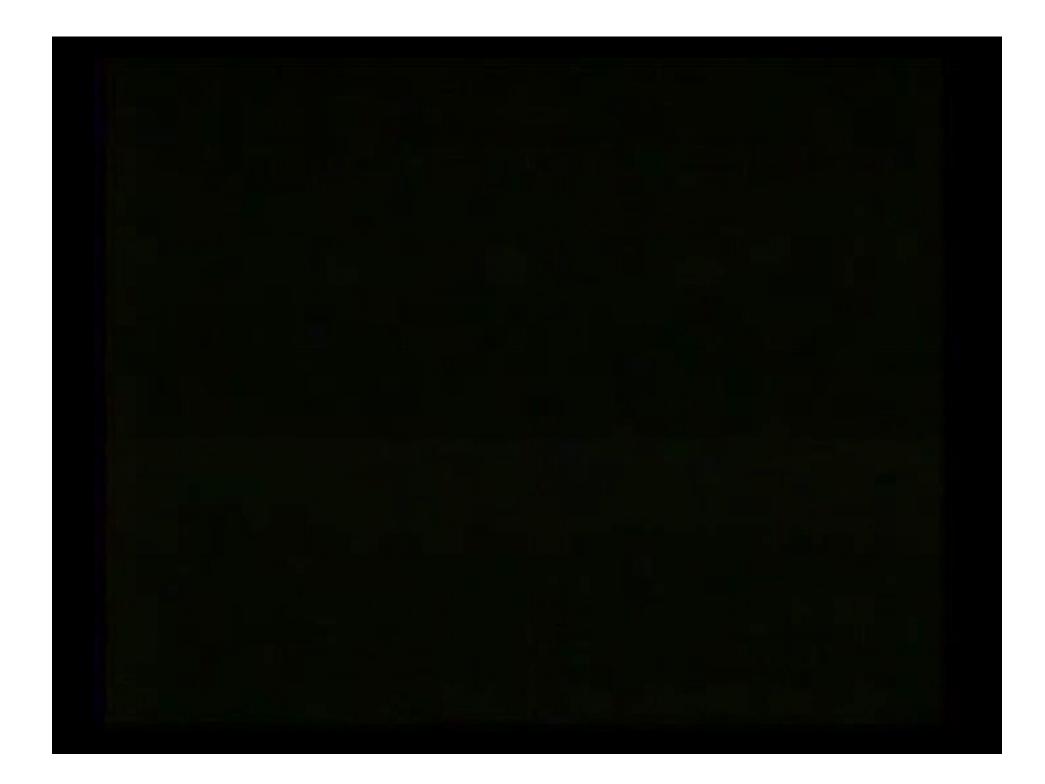






AGOR 23 Class

- Sewage Pump
- Propeller hub vortex cavitation
- Bubble Sweepdown (REVELLE only)

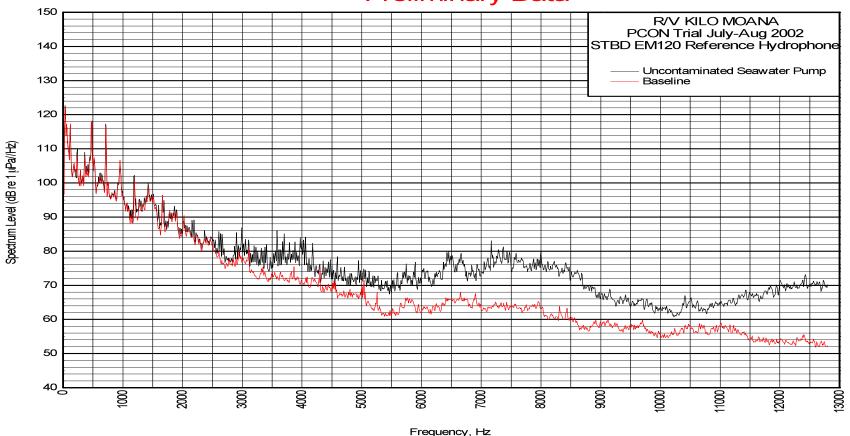


KILO MOANA (AGOR 26)

- Propeller Cavitation
- Scientific Seawater pump
- Main Diesel Noise

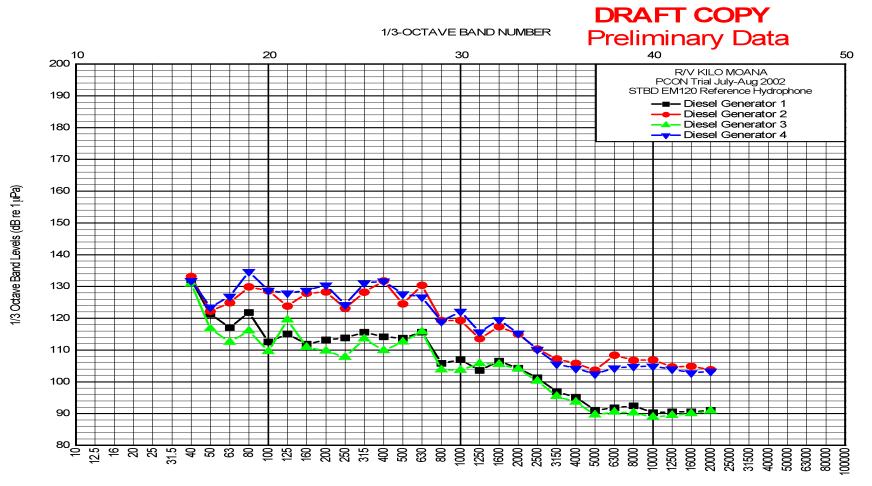
Kilo Moana Scientific Seawater Pump

DRAFT COPY Preliminary Data



Note: Data converted to Spectrum Level (1 Hz resolution) from 8 Hz resolution data.

Kilo Moana Diesel Noise

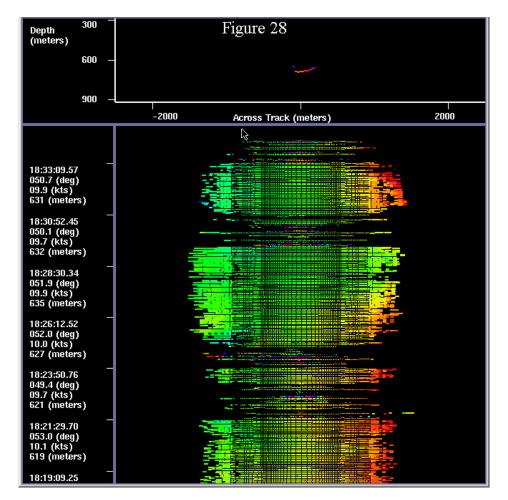


Frequency, Hz

NOAA T-AGOS Conversions

- Hi'Alakai
 - Bubble Sweepdown
 - Machinery
- Oscar Elton Sette
 - Bubble Sweepdown
 - Machinery

EM 300 Sonar Display on HI'IALAKAI

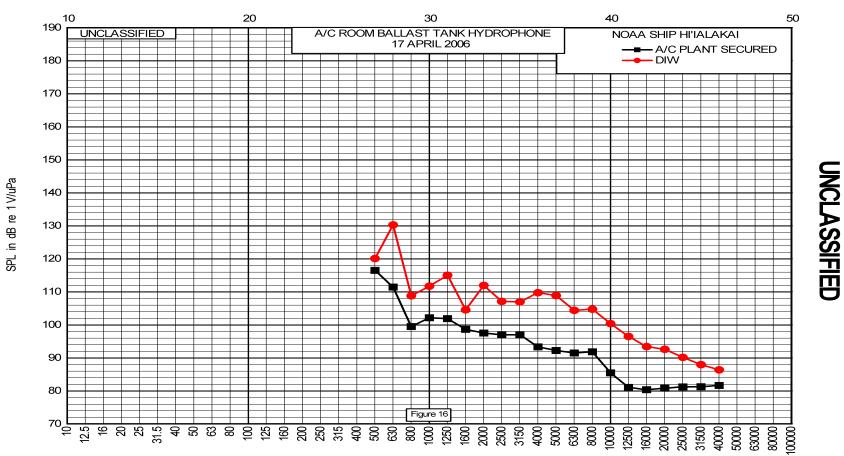


EK 60 Sonar Display on OSCAR ELTON SETTE

SIMRAD ER60 - Local - [Normal]	
Operation View Options Install Output Window	Help A E Channel: GPT 38 kHz 009072018179 1 ES388 Mode: Passive
GPT 38 kHz 009072018179 1 E538B	
	4.02m
Sv 201 -35dB -35dB 100 200 200 360 200 360 21:30:11	Transducer ES38E Frequency: 3800Hz Beamtype: Split. Depth: 0.00m Gain: 25.41dB, Sa Corr: 0.67C 2.1.942:07 Transcucer ES38E Frequency: 3800Hz Beamtype: Split. Depth: 0.00m Gain: 25.41dB, Sa Corr: 0.67C Angle Sensitivity, Along: 2.19C Angle Sensitivity, Along: 7.20° Transceiver Passiv Pulse duration: 1024 us. Samp Power: 2000W. Receiver Banc Environment Sound speed: 1525 m/s, Absor Noise Estimate: -122dB Depth: 0.00m Max ping range: 1000m Max ping range: 1000m
📓 GPT 120 kHz 00907203393a 2 E5120-7	
Sv 20Lc -35dB 100 0 Detections -80dB 21:27:22	Transducer ES120- Frequency: 12000Hz Beamtype: Split. Depth: 0.03m Gain: 25.67dB, Sa Corr: 0.34d 2.vwy beam angle: -20.30dB Angle Sensitivity, Along:0.020, Ath 3-dB Beam width, Along:6.30°, Transceiver Paasiv Power: 500W. Receiver Bandh Dower: 500W. Receiver Bandh Dower: 500W. Receiver Bandh Depth: 0.00m Max ping range: 100m
🏦 Start 🗍 🛃 🥔 🔕 🕑 🗍 🚰 SIMRAD ER60 - L	9.9 kts 4251.915 nmi 21° 11.320 N 158° 13.067 W RECORD ON: 5211432 [21:42:07.59] 0 Warning Local Screenshot1.bmp - Paint V ↔ @ ① ② ↔ @ ② ◇ ② ◇ ◇ ◇ ◇ ◇ ◇ ◇ ◇ ◇ ◇ ◇ ◇ ◇ ◇ ◇ ◇

HI'IALAKAI air conditioning problem

1/3-OCTAVE BAND NUMBER



UNCLASSIFIED

Frequency, Hz

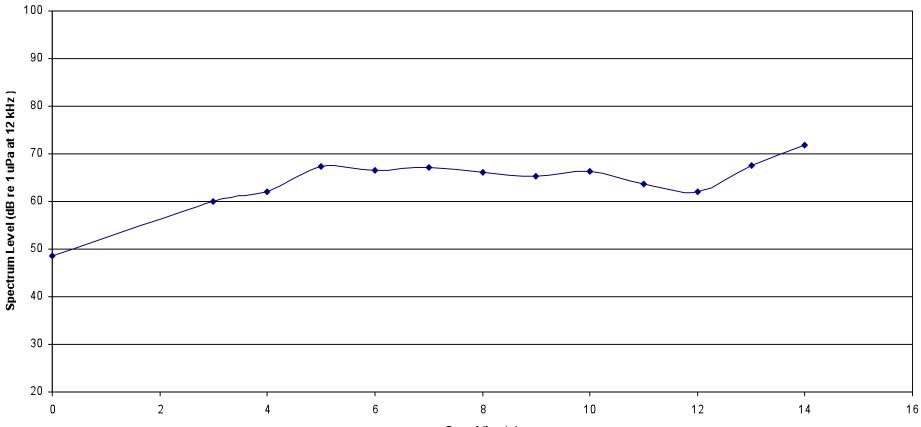


R/V MITCHELL

- Propeller Cavitation (CPP prop)
- Machinery Chill Water Pump

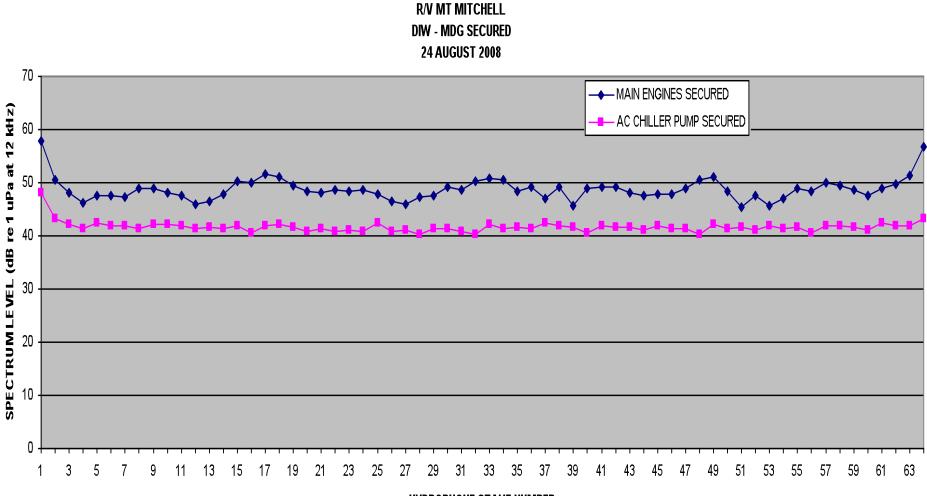
EM120 RX Noise Levels

R/V MT MITCHELL August 2008 EM 120 Noise Levels



Speed (knots)

AC Chiller Pump Secured



HYDROPHONE STAVE NUMBER

COOK

- Bubble Sweepdown problem significant limits sonar performance
- Bulbous bow is cause of bubble ingestation



ACOUSTIC MONITORING

ACOUSTIC MONITORING SYSTEM



Sonar Performance Requirements

- High performing (expensive) sonars require a quiet background noise to ensure optimal operation
- Quiet ships don't stay quiet
- If acoustic housekeeping isn't conducted, a research vessel's overall noise level will degrade over time

Potential Acoustic Degradations that can occur over time

- Machinery Noise
 - Failed vibration isolation mounts
 - Clogged/restricted piping
 - Pump/machinery mechanical failure
- Propeller Cavitation degradation
- Fairing damage
- Hull Fouling

Acoustic Monitoring

- Monitoring the overall vessel acoustic signature can predict and determine degraded sonar performance
- An acoustic baseline can be used to compare current acoustic levels to assess current sonar performance
- While this is a simple procedure, the current trend has been to ignore the acoustic signature of a research vessel and just "take what you get"

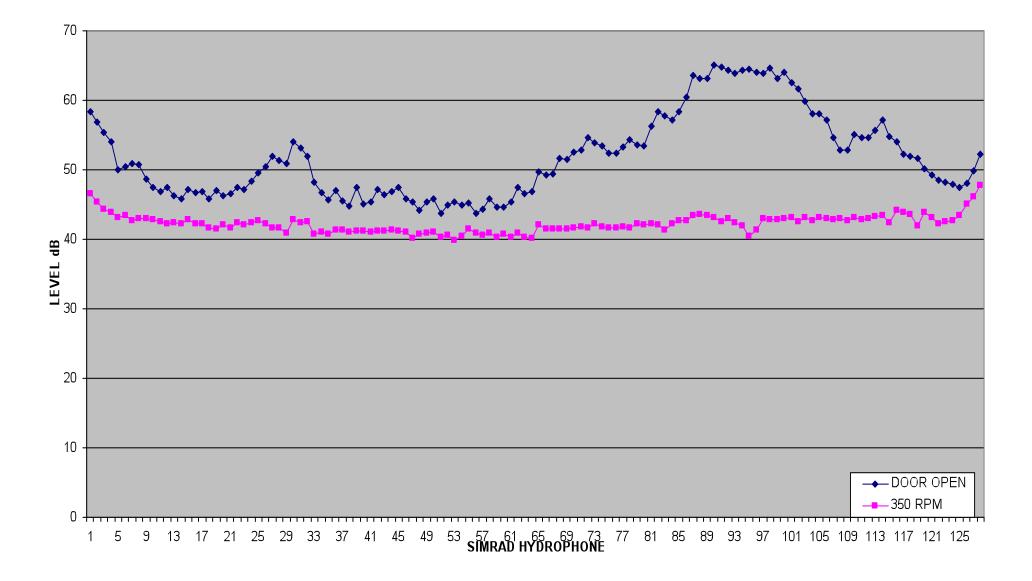
The NSF Initiative

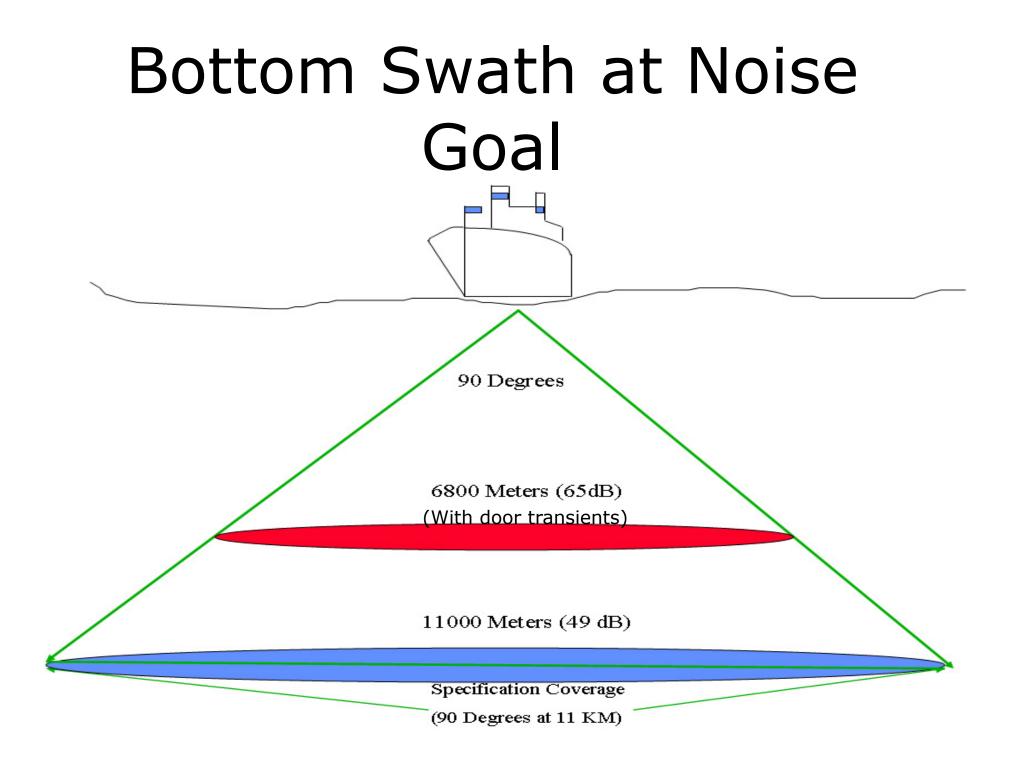
- NSF has recognized the value and importance of maintaining research vessel acoustics
- Based on recent sonar upgrades in the UNOL fleet that have had poor sonar performance, all UNOL/NSF funded sonar upgrades will attempt to understand and control acoustic signatures of research vessels

ACOUSTIC MONITORING SYSTEM

- During most first acoustic evaluation with new system onboard background noise levels were significantly higher than expected
- Acoustic monitoring system was utilized to identify high level squealing transients present in data
- Transients were isolated to unsecured squeaking door

USNS MARY SEARS (T-AGS 65) 10 APRIL 350 VS UNSECURED DOOR





Fairing damage



Bio-fouling



Conclusions

- Every vessel has a different noise source/ problem that could limit sonar performance
- Acoustic preparation for high performing sonars must be considered
- Acoustic levels should be monitored over the life of a research vessel to ensure optimal performance for EVERY mission