- Brief Overview/Functionality of the Systems
- Current Status
- Recent Updates
- Plans/Status





DESSC May 2007

Brief Overview – Virtual Van

- Developed and built by Steven Lerner, Andrew Maffei, Danielle Fino in Sep 2000; funded by Keck Foundation
- Goal is to snapshot all the information happening in the control van in real-time and give easy web browser access to the integrated information on ship and on shore (for postcruise work)
- System consists of an acquisition system, video capture system, 4dGeoBrowser server, web-based user-interface, and web-based event logger
- Runs on Linux; software: Perl, cgi-scripts, Apache
- Shore server runs on a Linux computer
- NB: Not completely stand-alone requires Internet connection







Jason Virtual Van

DESSC May 2007

Functionality & User Interface



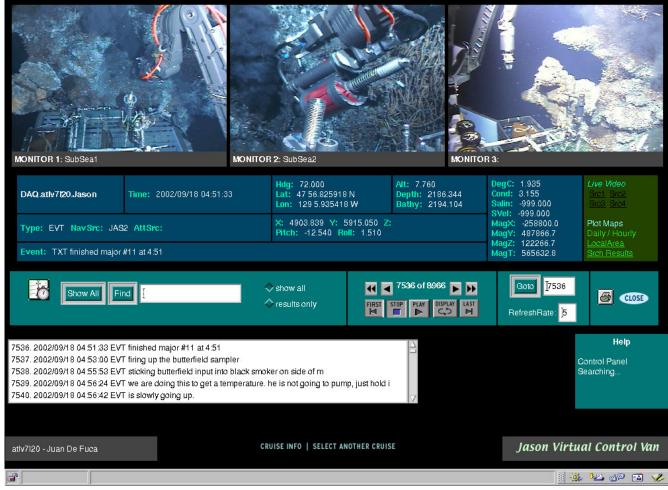
Control Van

Snapshot

Video Displays Navigation Vehicle Telemetry Science Instruments

CEANOGR.

User Events



Virtual Van Web-browser Interface





Brief Overview – FrameGrabber

- Developed by Steven Lerner, Barrie Walden, Dan Fornari; prototype Linux laptop built May 2002 (NSF funded) and Windows' production system built and installed April 2003 (NDSF funded)
- Goal is to snapshot all the information in the submarine in real-time and give easy web browser access to the integrated information on ship for pre- and post-dive synopsis and for onshore post-cruise work
- System consists of an acquisition system, video capture system, web-based user-interface and capability to process historical cruises
- Runs on Windows; software: Internet Explorer, Perl, cgiscripts, Apache; shore server is Linux-based





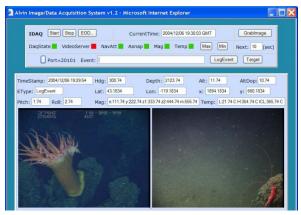


Alvin FrameGrabber

Functionality & User Interface

DSV Alvin





Acquisition System





User Interface (web browser)



Features Include: Scrolling/clickable map, image highlight/annotation, interactive time-bar, summary icons (proof-sheets, time-series plots), VCR-style navigation buttons



Current Status

Jason Virtual Van

- Operational since September 2000
- 33 cruises
- 2,369,738 images

Alvin FrameGrabber

- Operational since April 2003
- 51 cruises
- 518 dives
- 647, 486 images







Recent Updates

Jason Virtual Van

- Renav capability (operational)
- Four *Jason* cruises (39 lowerings) of renavigated data in database, 2 cruises worth of lowerings in VVan, three further cruises worth of data ready to be processed

Alvin FrameGrabber

- Renav capability (in testing phase)
- Ten Alvin cruises (136 dives) of renav processed & ready...

Shore web server updated

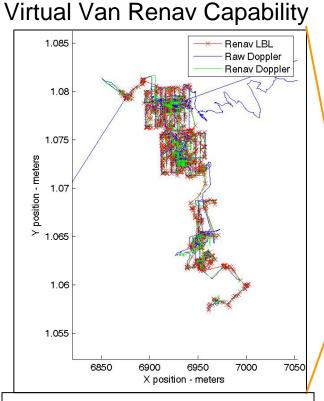
- http://4dgeo.whoi.edu/jason
- http://4dgeo.whoi.edu/alvin





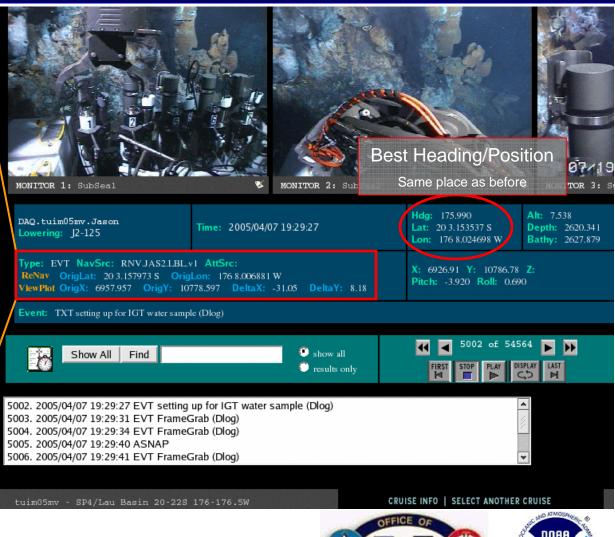


Recent Updates



With renav capability, original realtime lat/lon is displayed along with calculated delta x/y. Clicking on 'View Plot' shows track differences.

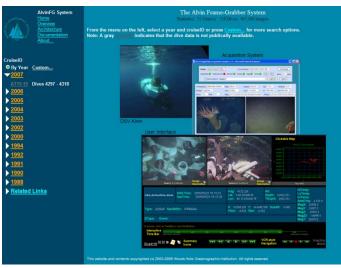




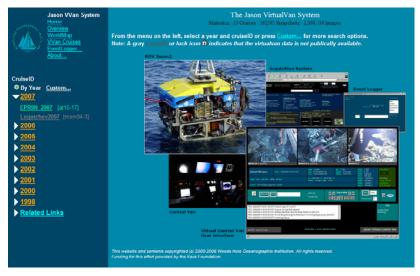


Recent Updates

Shore Server Web Sites Updated



http://4dgeo.whoi.edu/alvin



http://4dgeo.whoi.edu/jason







Where Next?

Jason Virtual Van

• Update event viewing/export capability (design complete)

Alvin FrameGrabber

• Complete renav capability (testing phase)

ABE/Sentry

• Build FrameGrabber system (design phase)

But - what is the *really* smart way forward? & How to make data accessible through multiple interfaces?





