Long-Range Planning Issues

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Coordination of Multi-Vehicle Operations at Observatory Sites

Four key issues for multi-vehicle operations:

- ? Safety
 - ? Alvin/RHOV
 - ? ROVs
 - ? AUVs
- ? Navigation
- ? Seafloor Compatibility
- ? Seafloor Traffic Control





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Safety

• Alvin/RHOV

- ? Standard = minimum 1 water-depth spacing
- ? Has been relaxed for "untethered" seafloor objects
- ? AUVs: ABE/Sentry OK but "torpedo" AUVs???
- ? Alvin & Nautile have worked together: 1997
- ROVs keep all vehicles separated by 1 water-depth
- AUVs
 - ? Safe launches achieved with ROVs deployed from same ship
 - ? Safe launches achieved during HOV ascent
 - ? We know how to send an AUV to sleep on seafloor
 - ? Key to avoiding trouble is good navigation







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Multi-Vehicle Navigation

- Long Baseline
 - ? Multi-frequency for multi-vehicle operations
 - ? Compatibility with USBL systems (e.g. Posidonia)
 - ? Ability to import both LBL and USBL into common space
- Experience to date
 - ? AUV ABE (LBL) & ROV Quest (Posidonia USBL)
 - ? AUV ABE (LBL) & ROV Jason (DVL, LBL turned off)
 - ? HOV Alvin (LBL) & HOV Nautile (LBL)
- Future developments
 - ? Jason/pan-NDSF acoustic controller board (Howland)
 - ? Compatible with new beacon system (Yoerger/Bradley)
 - ? Merge LBL- & USBL-space (Singh/Whitcomb/Yoerger)







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Seafloor Compatibilities

- HOV/ROV inter-operability
 - ? Common instrument & package "handles"
 - ? Install, connect, activate/deactivate, disconnect, recover
 - ? Moorings ROVs from top; HOVs from base
- AUV docking: "one size fits all"





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Seafloor Traffic Control

- High Latitude Observatories (e.g. RCO)
 - ? 12 months seafloor operations per annum
 - ? 6 months weather window (4 months to be conservative)
 - ? Requires 2-3 vehicles concerted effort each summer
 - ? (Ruggedize ROVs for longer seasons in NE Pacific?)
- Careful coordination required
 - ? Prioritization of operations
 - ? Compatibilities of vehicles safety & operations
 - ? Single coordination point needed for each observatory



