

Long Distance Disruption-Tolerant Wireless Networking

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Intel **Research**
Berkeley

Who am I?

- Intel Research (Berkeley)
 - Part of Intel Corporation (the chip people)
 - One of the ‘tablets’ working with universities
- Chair of the ‘Delay Tolerant Networking’ RG
 - Part of IRTF/IETF (the people who do standards)
 - Participant/PI in related NSF and DARPA programs
- I am here because...
 - Our work might help oceanography
 - I am interested in [some of] your problems

802.11 Standard

- Half-duplex radios
 - only one of: Transmit or Receive
 - designed for low-delay office environment
- Collision avoidance
 - Cannot listen to channel while transmit
 - Backoff before every transmit
 - Contention for access to broadcast channel

802.11 Packet Sequence



Features:

- Stop and go
- MAC retransmissions for reliability

Key Issues:

- Channel utilisation
- ACK timeout
- Collisions

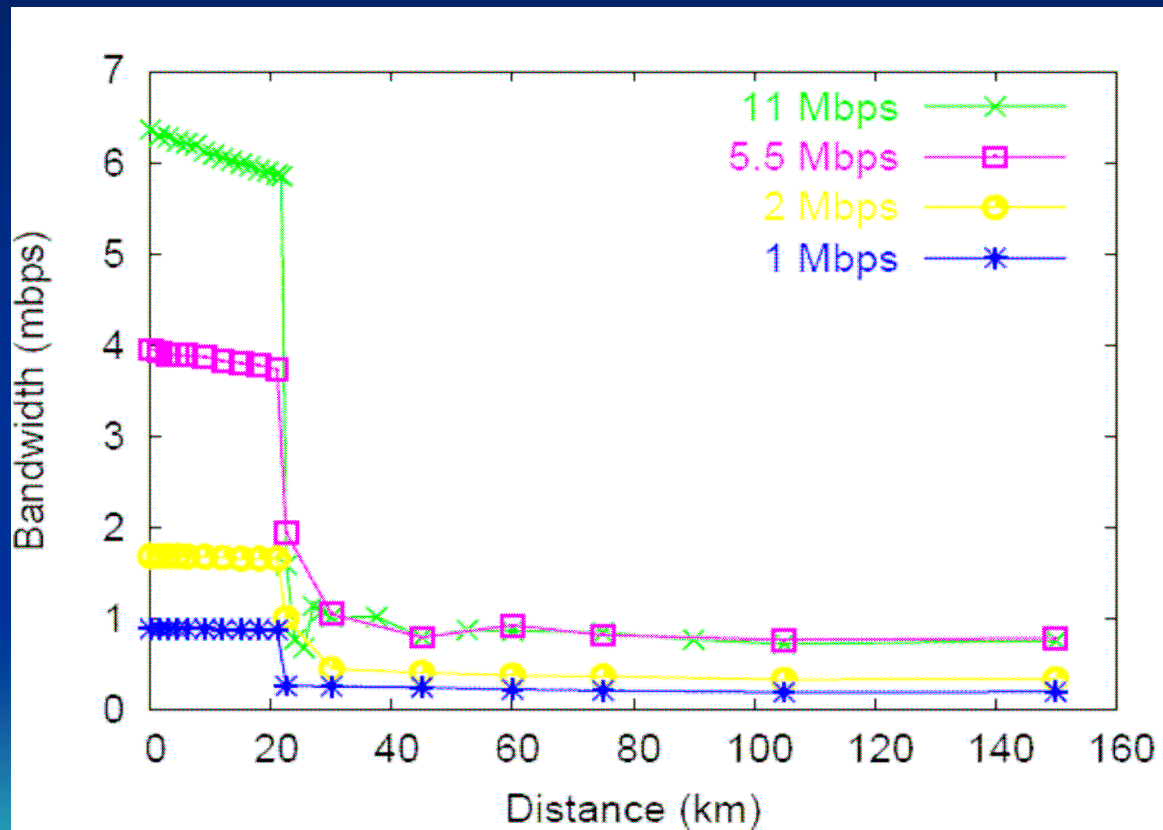
Packet transmission time : T_p

ACK transmission time: T_a

Propagation delay : T_d

ACK Timeout $> (T_p + 2 * T_d + T_a)$

Throughput vs distance



- PRISM 2.5 Radios
- UDP throughput
- With retries enabled

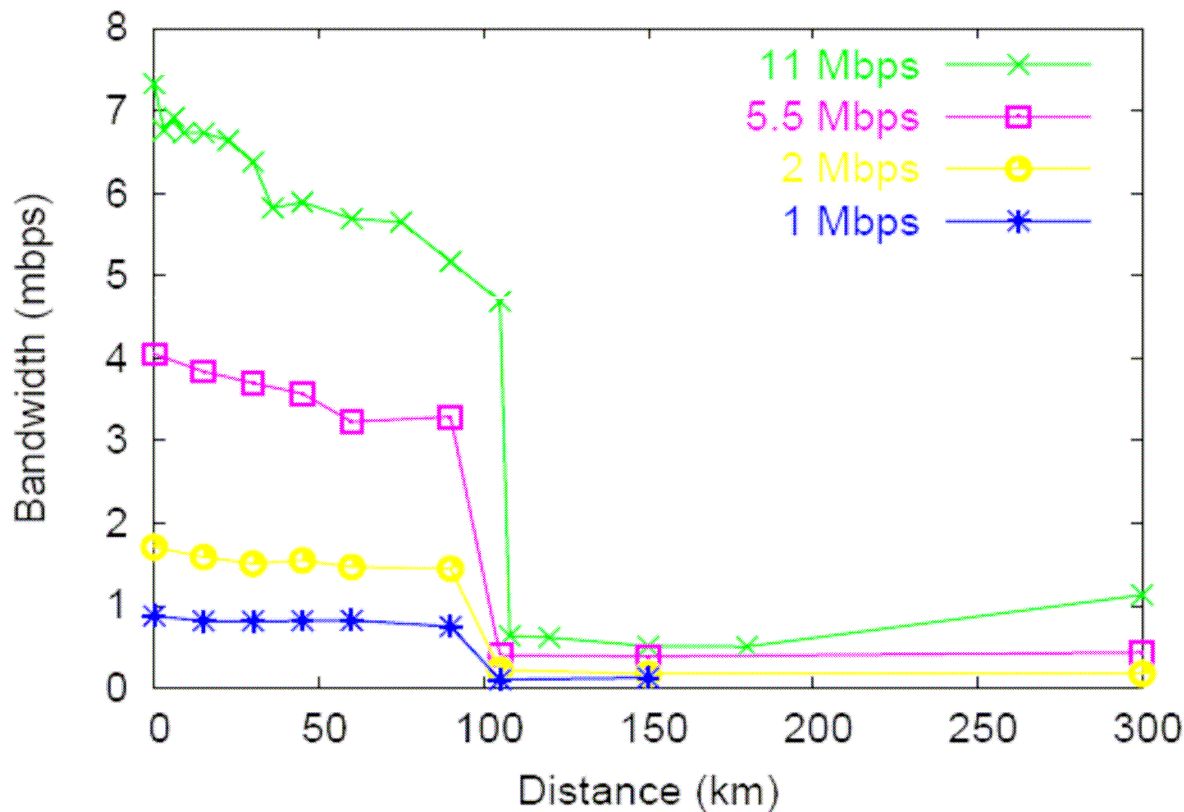
Results:

- Gradual drop as round trip time increases
- Sharp drop at 22 km

Setup:

- Channel emulator
- RF isolated experiments

Throughput vs distance again



- Atheros Radios
- UDP throughput
- With MAC retries

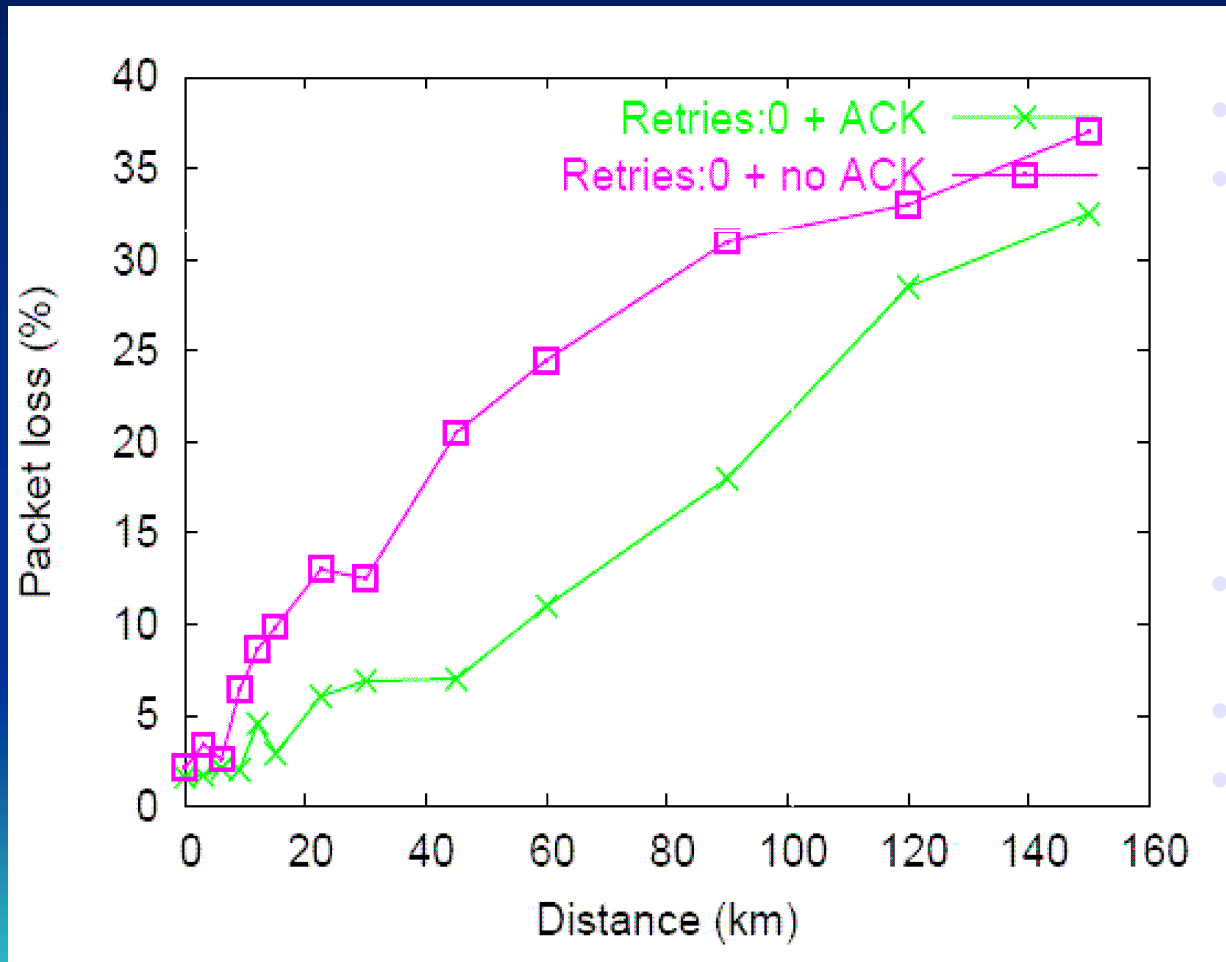
Tweak:

- Use longer ACK timeouts

Results:

- 30 % drop even before 111 km
- Sharp drop at 111 km

Bi-directional traffic vs distance

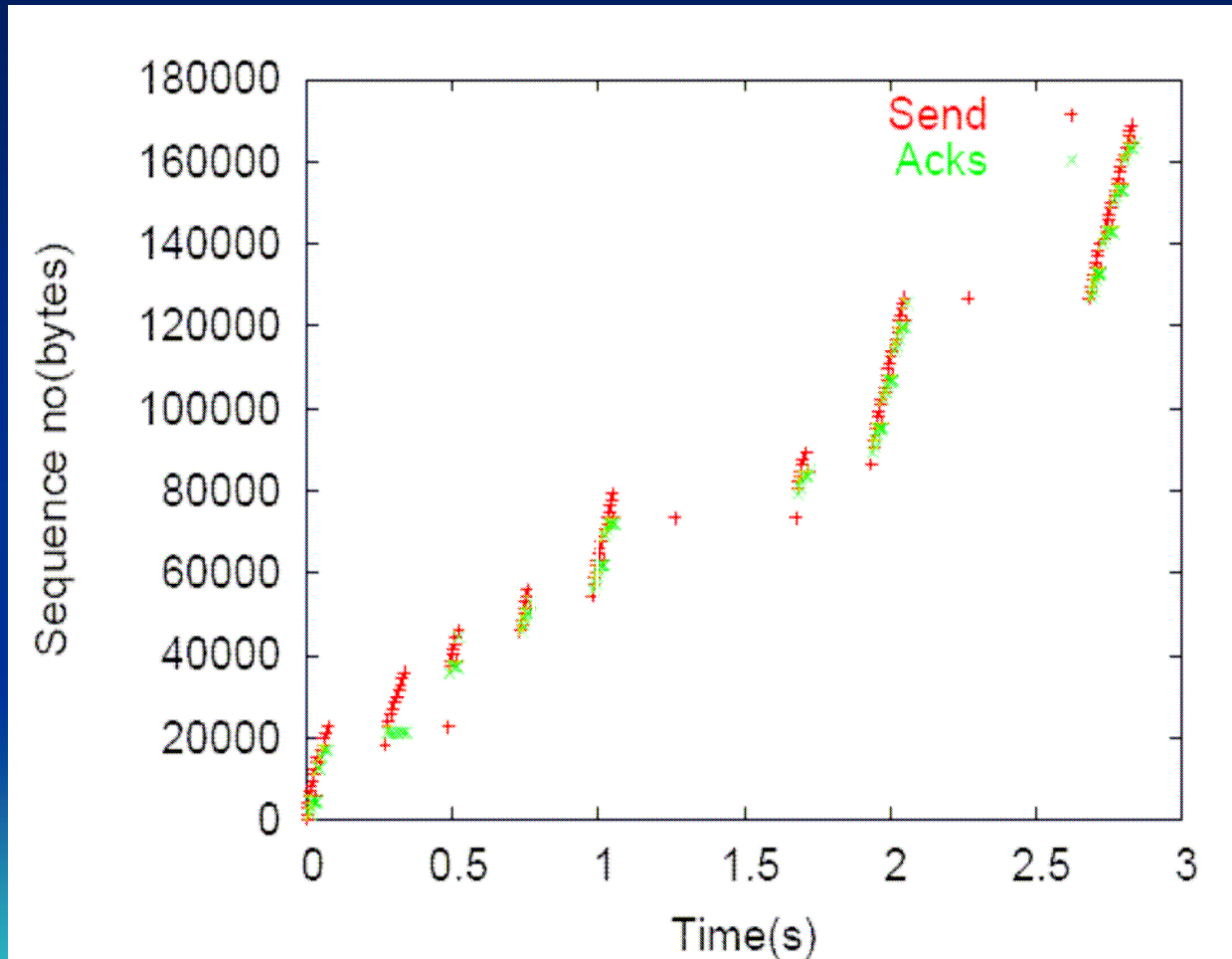


- Bi-directional UDP
- With zero MAC retries

Results:

- Collision avoidance does not work
- Too far apart
- Upto 30% at 100km

TCP on Lossy link



20 km link over the bay from Berkeley to SF (near Sutro Tower)

20 % loss

Results:

TCP : 372 kbps

UDP : 4.5 mbps

Frequent timeouts of 200 ms

Lots of ACKs are also lost

But this only works if...

- End-to-end RTT is not terribly large
 - A few seconds at the very most [typ < 500ms]
 - (TCP works)
- Some path exists between endpoints
 - Routing usually finds single “best” existing route
 - (Internet Routing works)
- Retransmission enhances reliability [TCP]
 - True for low loss rates (under 2% or so)
- Packet switching is the right abstraction
 - Internet/IP makes packet switching interoperable

Non-Internet-Like Networks

- Things that move
 - Ships, gliders, AUVs, submarines, satellites...
 - Buses, trucks, bicycles, mules, zebras, etc.
- “Exotic” links
 - NASA DSN [40min max RTT to Mars]
 - UAM’s [acoustics: low capacity, high error rates & latencies, intermittent, (power)]
 - Optical: free-space, underwater, etc.

Delay-Tolerant Networking Architecture

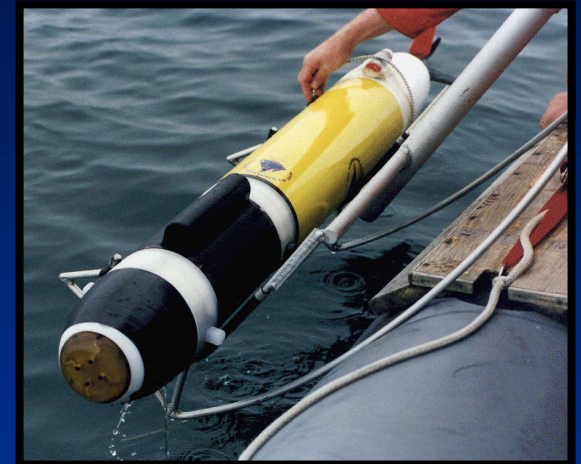
- Goals
 - Support interoperability across ‘radically heterogeneous’ networks
 - Acceptable performance in high loss/delay/error/disconnected environments
 - Decent performance for low loss/delay/errors
- Components
 - Flexible naming scheme with *late binding*
 - Message overlay abstraction and API
 - Routing and link/contact scheduling w/CoS
 - Per-(overlay)-hop reliability and authentication

Platforms

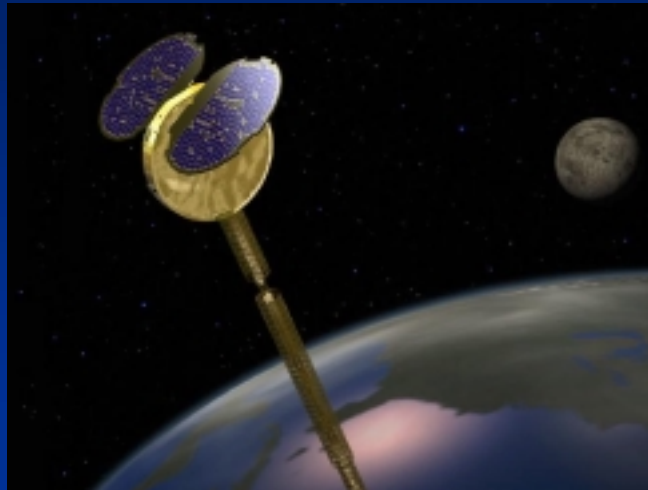
CODAR BUOY



REMUS AUV



ORBCOMM LEO



R/V ENDEAVOR



NASA - AVIRIS



SLOCUM GLIDER



<http://www.dtnrg.org>

Thank You!

<http://tier.cs.berkeley.edu>

Oceanographic Scenario [A. Maffei/WHOI]

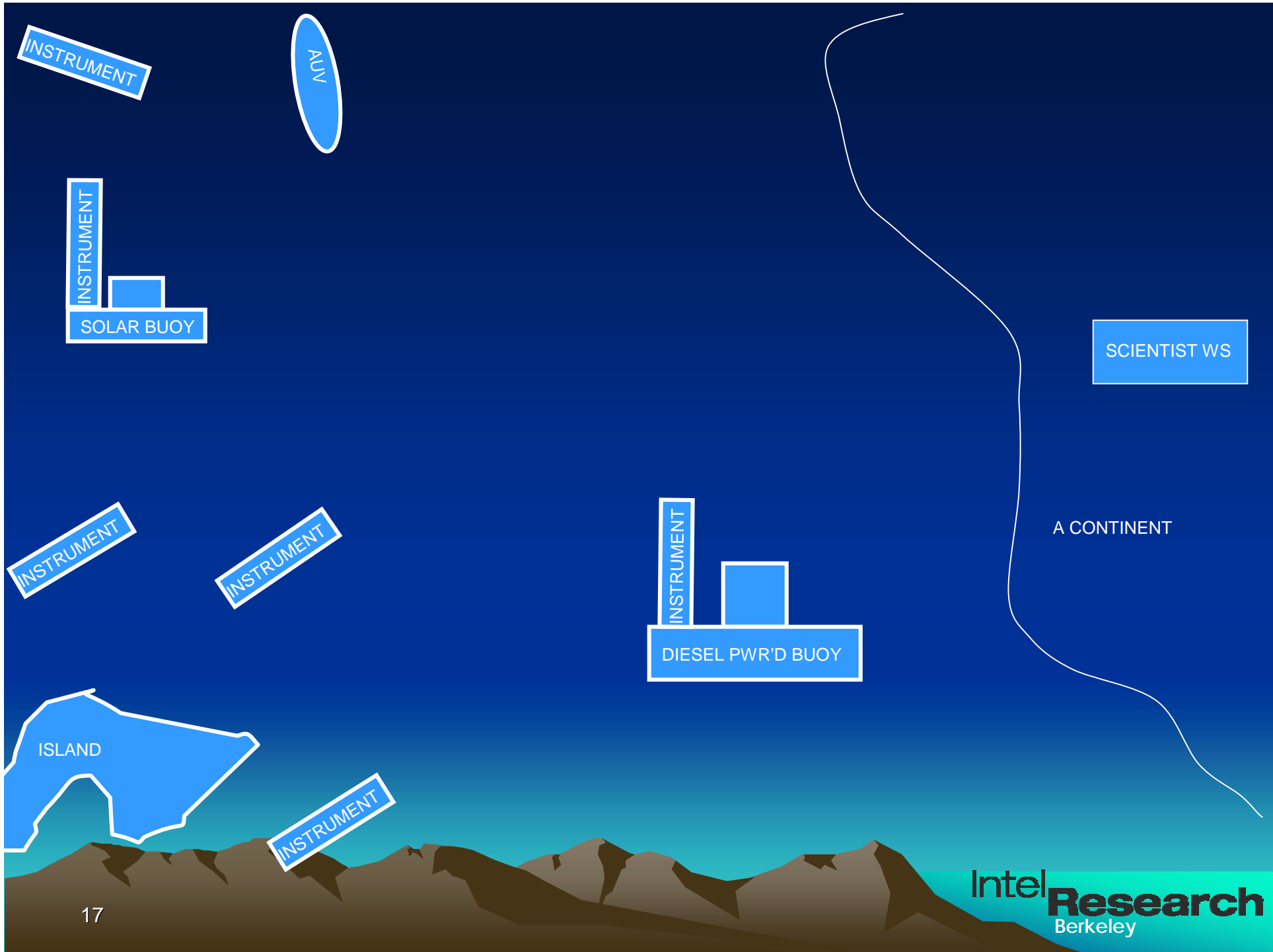
- Imagine you are an oceanographer interested in undersea earthquakes. You have deployed instrument clusters of acoustic, chemical, seismic, etc. sensors with acoustic modems attached to them.
- Autonomous Underwater Vehicles (AUVs) gather data from the instruments on a regular basis. Sometimes you make special requests to gather data from specific instruments, for example after an underwater earthquake occurs.

Scientist Interactions with Instrument Platforms

- As an oceanographer you don't concern yourself about which data communications assets are used to deliver commands to instruments or how data is delivered back to you.
- For example, a *dtm_file_copy* or *dtm_traceroute* command might be issued from your workstation command line indicating a DTN region and an oceanographic instrument name inside that region.
- The command might complete 3 weeks later when email arrives telling you that the data has arrived or displaying a report showing the communications path and sample round-trip latency to the instrument(s) you are interested in.

Potential Oceanographic DTN Regions

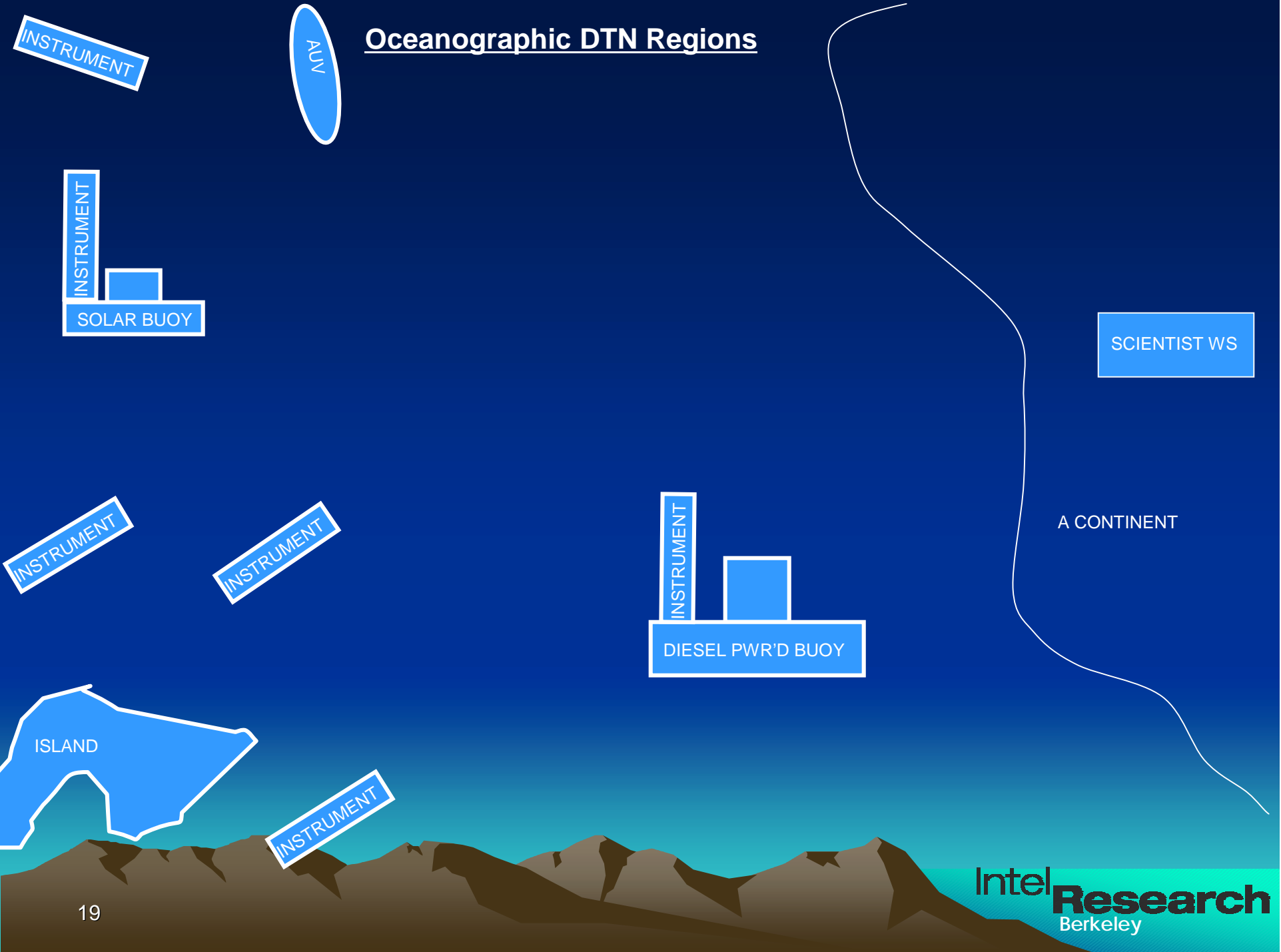
- First, the platforms of interest



Potential Oceanographic DTN Regions

- First, the platforms of interest
- Next, some Oceanographic DTN regions that could be developed (like address families).

Oceanographic DTN Regions

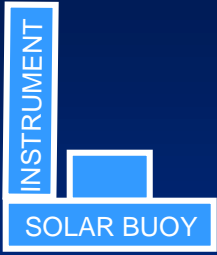


INSTRUMENT

AUV

Oceanographic DTN Regions

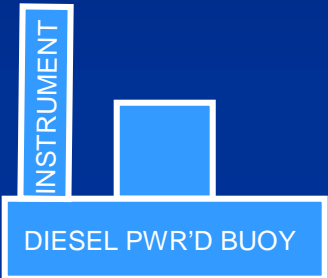
Global Internet Region



SUBMARINE CABLE



A CONTINENT



INSTRUMENT

INSTRUMENT

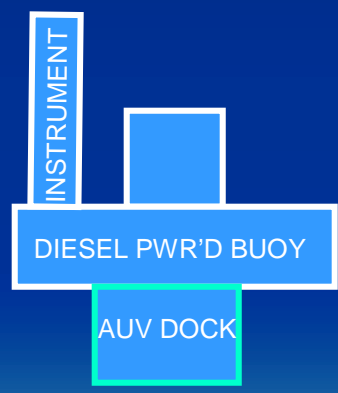
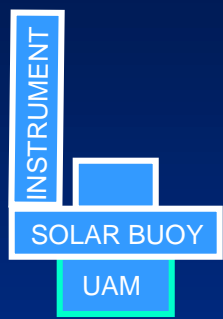


INSTRUMENT



Oceanographic DTN Regions

Global Internet Region
Underwater Acoustic Modem Region



SUBMARINE CABLE

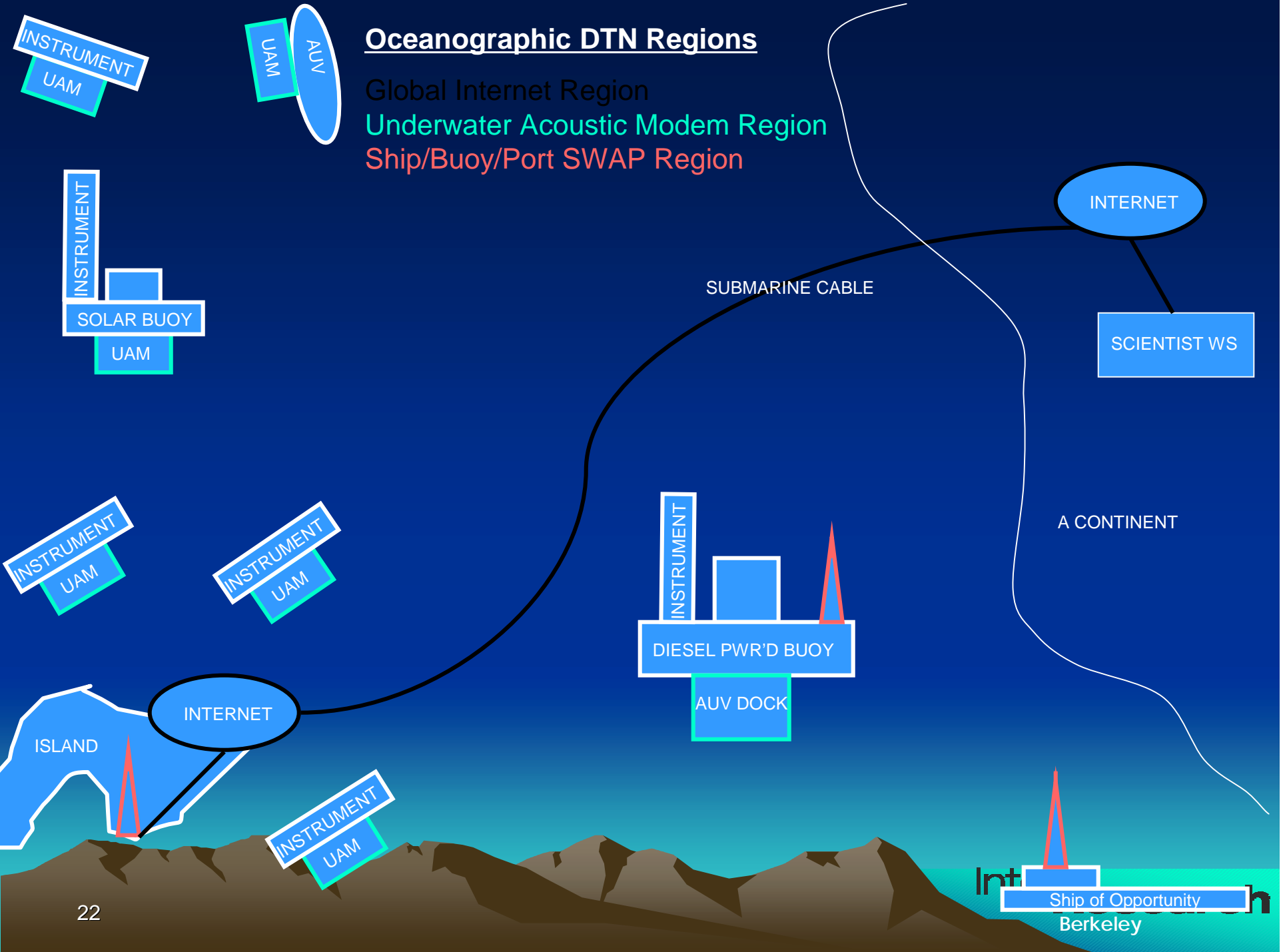


A CONTINENT



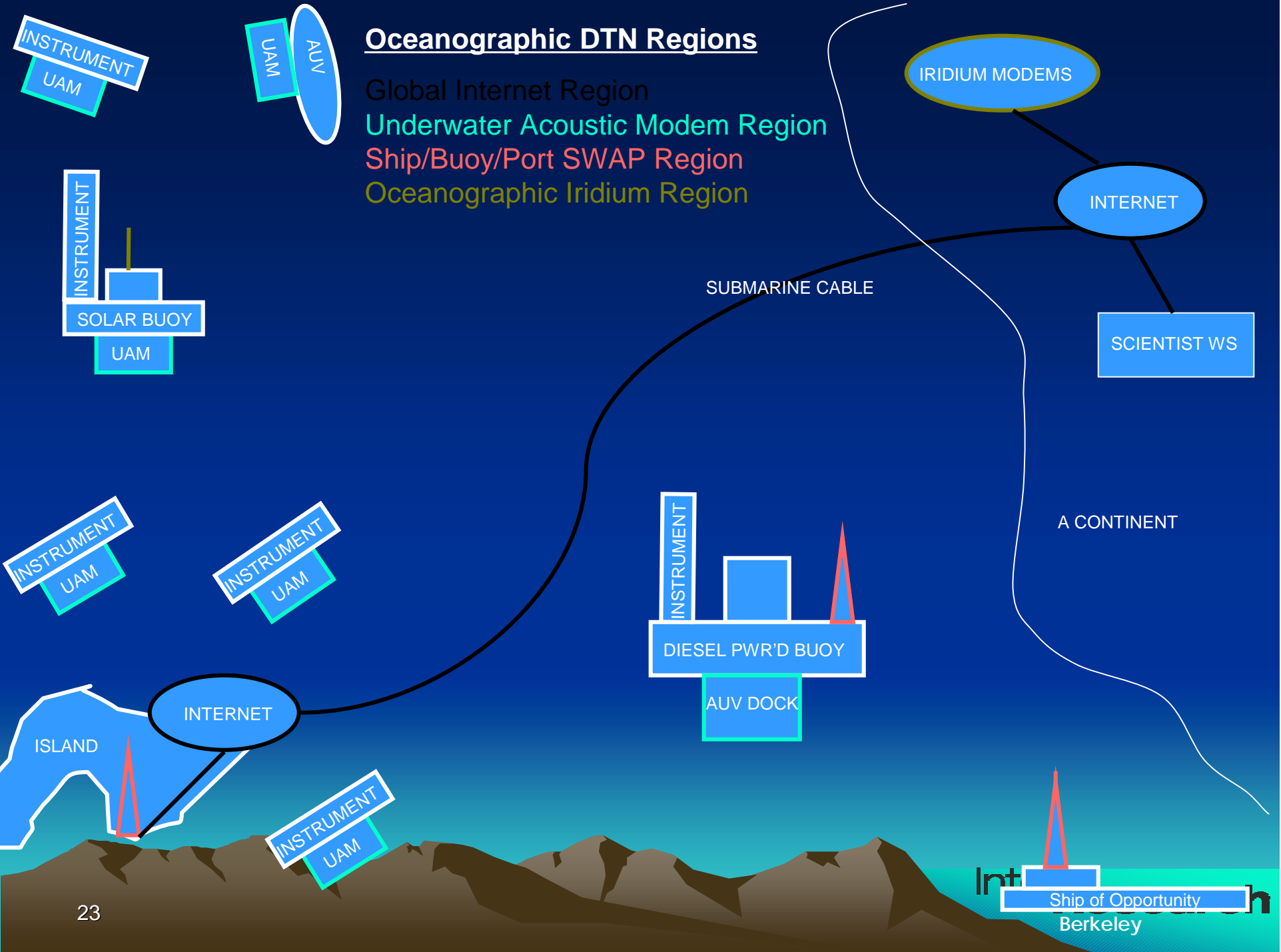
Oceanographic DTN Regions

Global Internet Region
Underwater Acoustic Modem Region
Ship/Buoy/Port SWAP Region



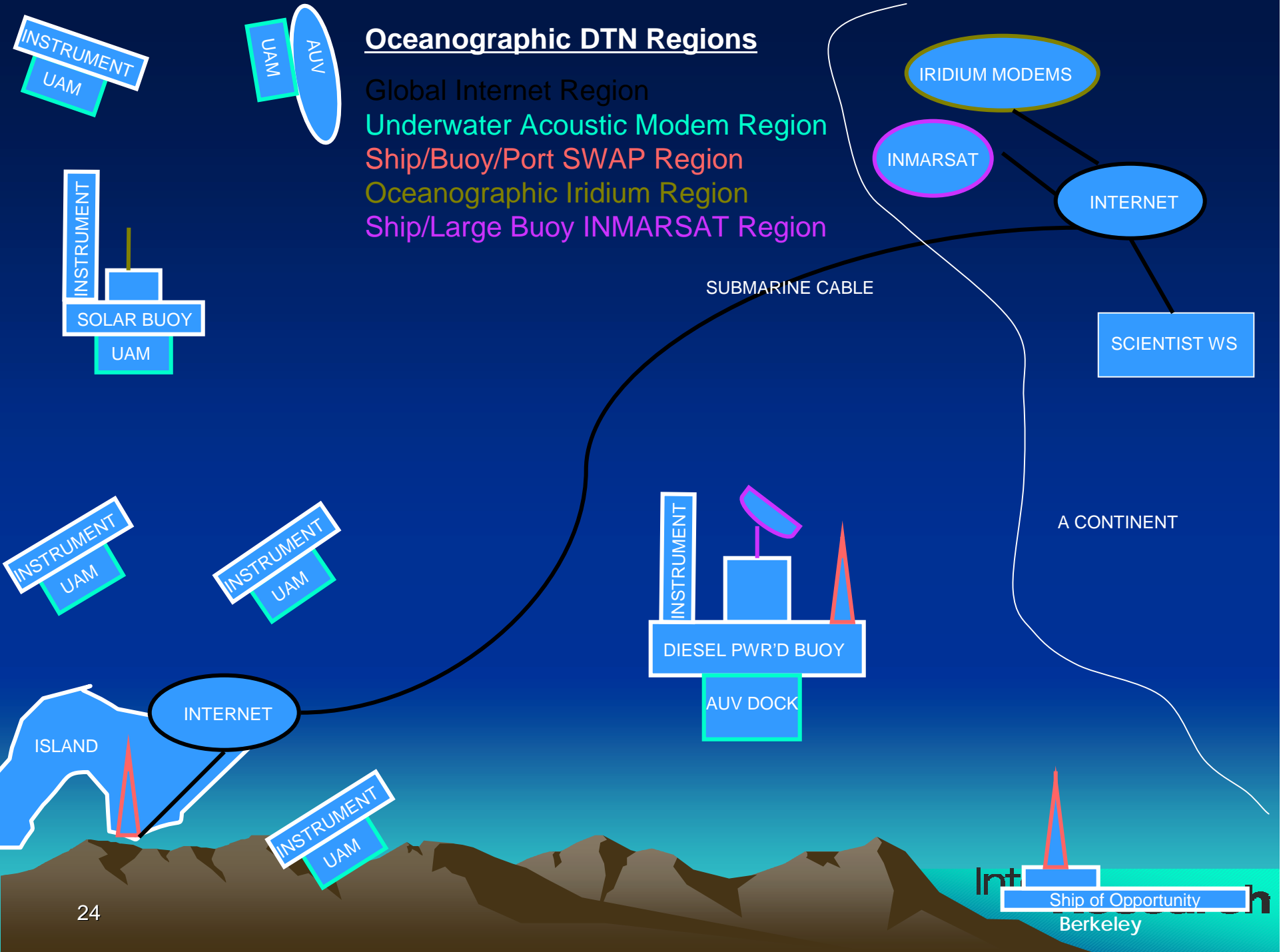
Oceanographic DTN Regions

- Global Internet Region
- Underwater Acoustic Modem Region
- Ship/Buoy/Port SWAP Region
- Oceanographic Iridium Region



Oceanographic DTN Regions

- Global Internet Region
- Underwater Acoustic Modem Region
- Ship/Buoy/Port SWAP Region
- Oceanographic Iridium Region
- Ship/Large Buoy INMARSAT Region

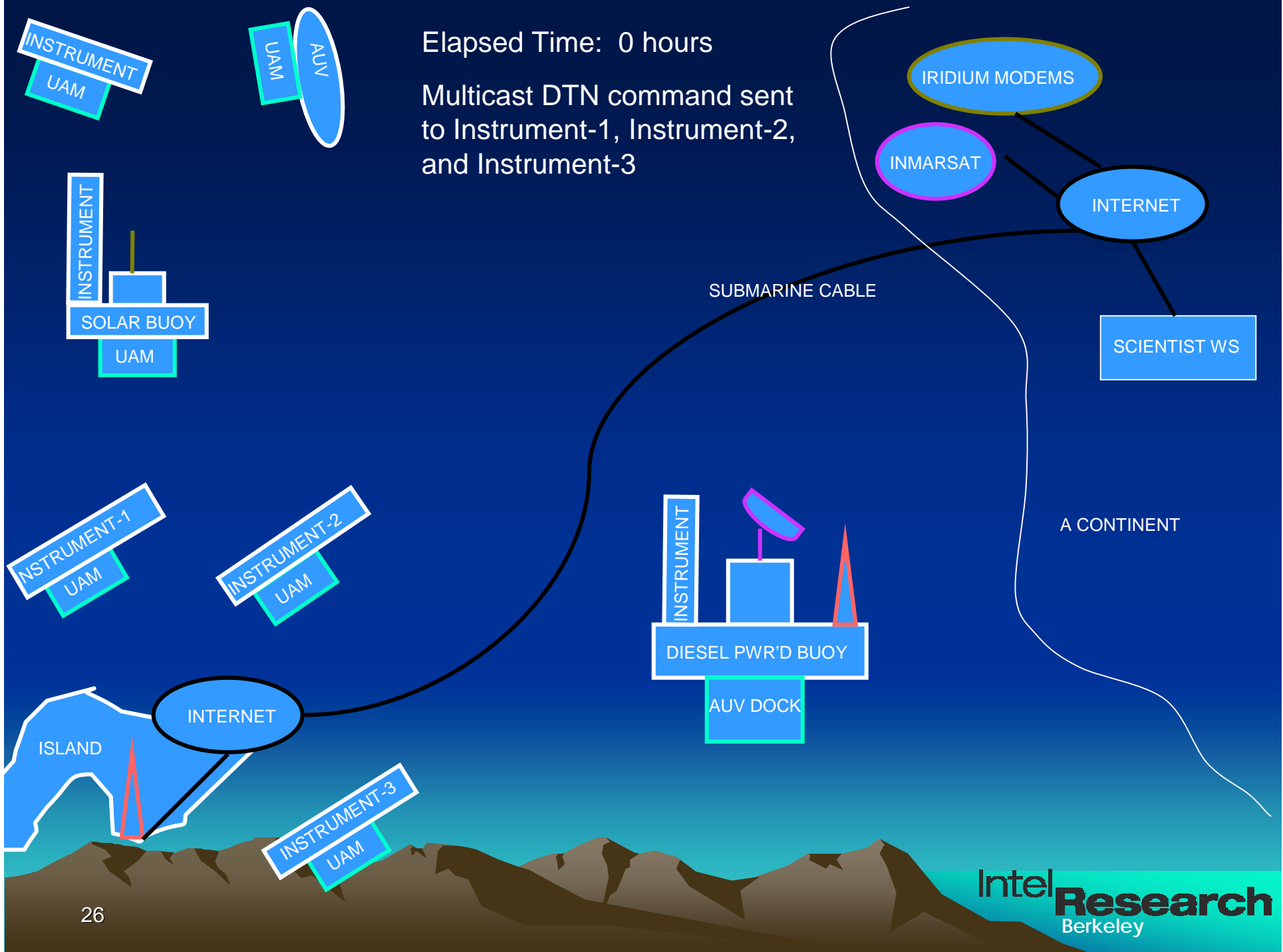


Potential Oceanographic DTN Regions

- First, the platforms of interest
- Next, some Oceanographic DTN regions that could be developed.
- A short animation

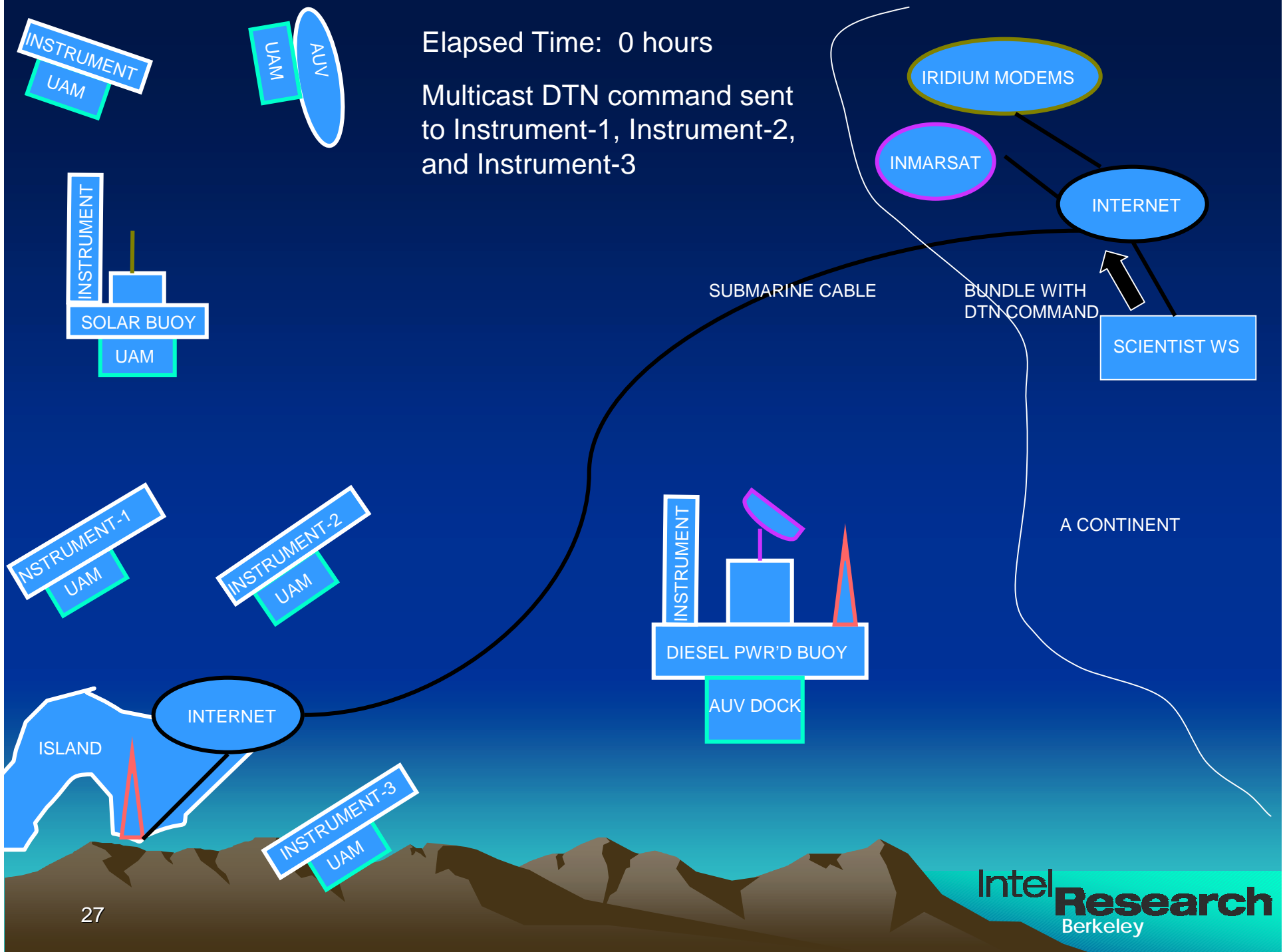
Elapsed Time: 0 hours

Multicast DTN command sent to Instrument-1, Instrument-2, and Instrument-3

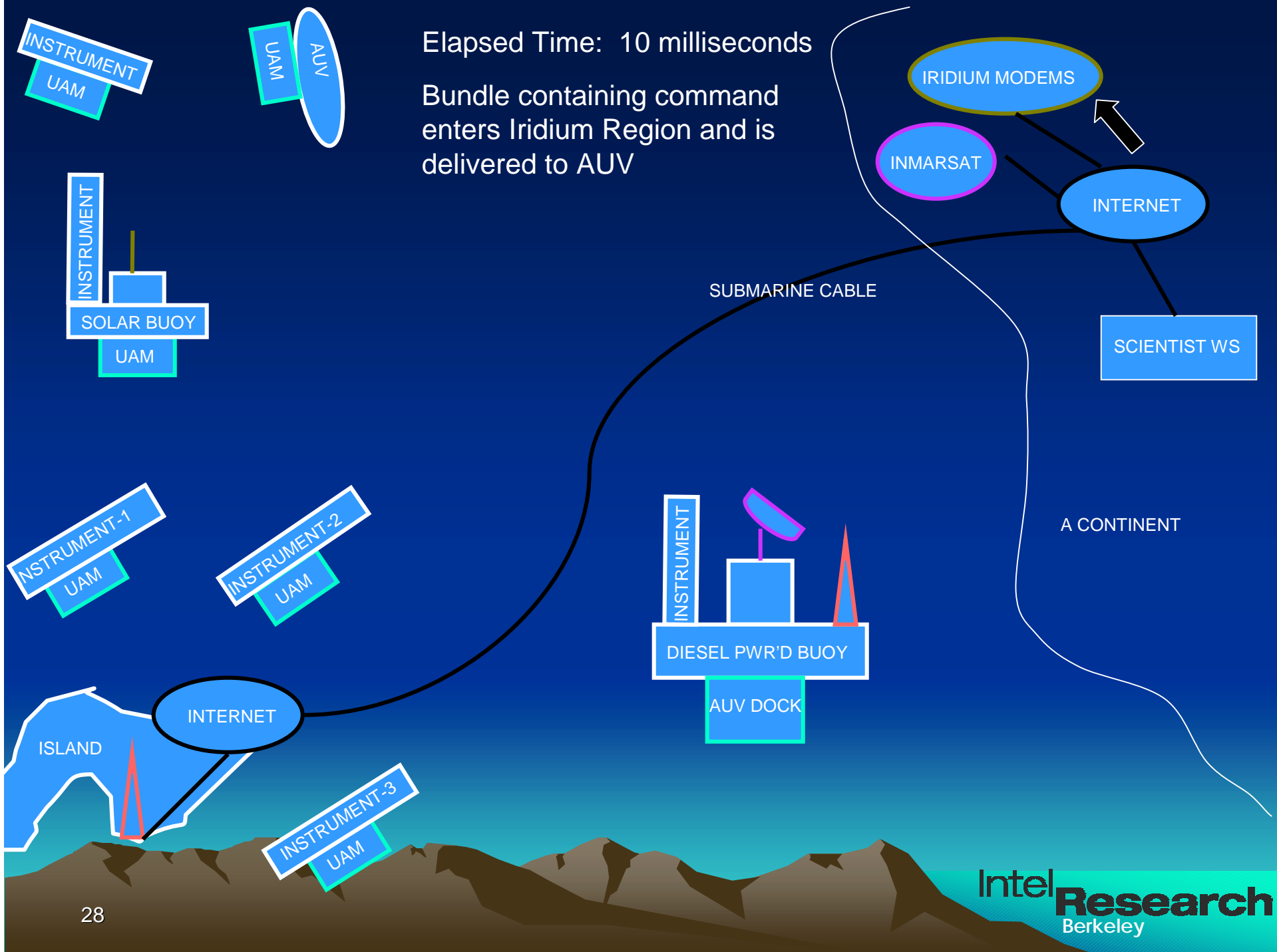


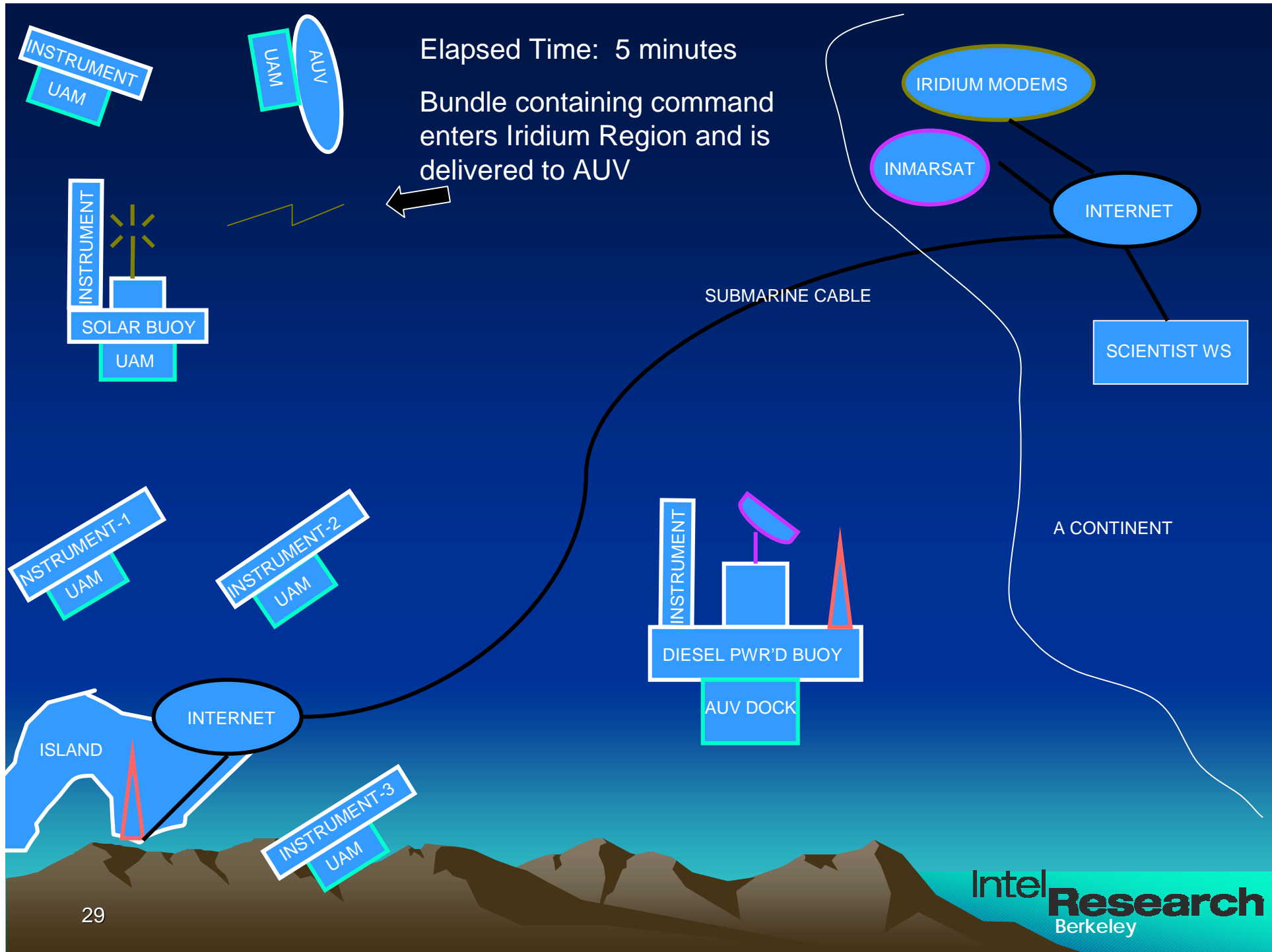
Elapsed Time: 0 hours

Multicast DTN command sent to Instrument-1, Instrument-2, and Instrument-3



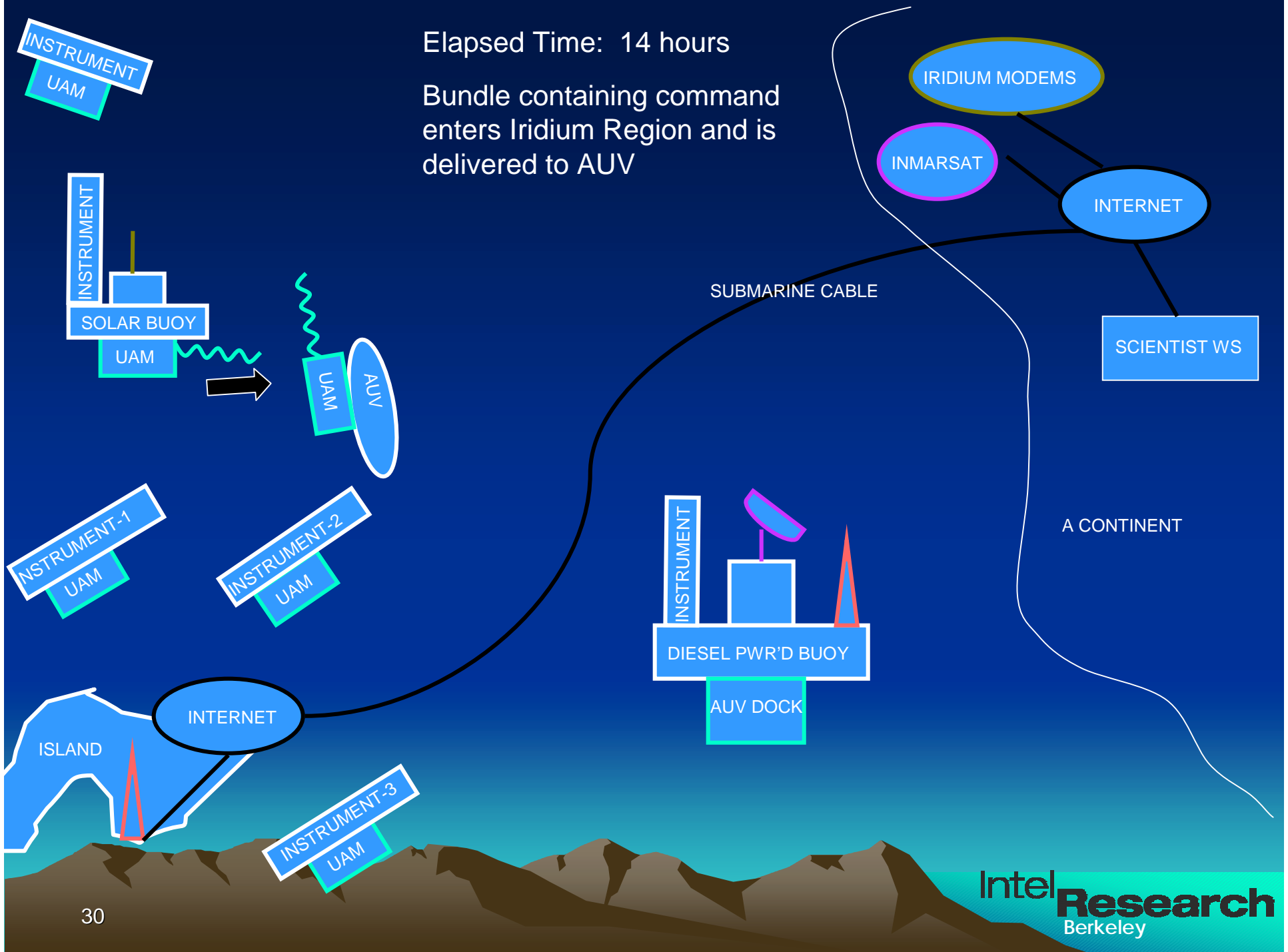
Elapsed Time: 10 milliseconds
Bundle containing command enters Iridium Region and is delivered to AUV





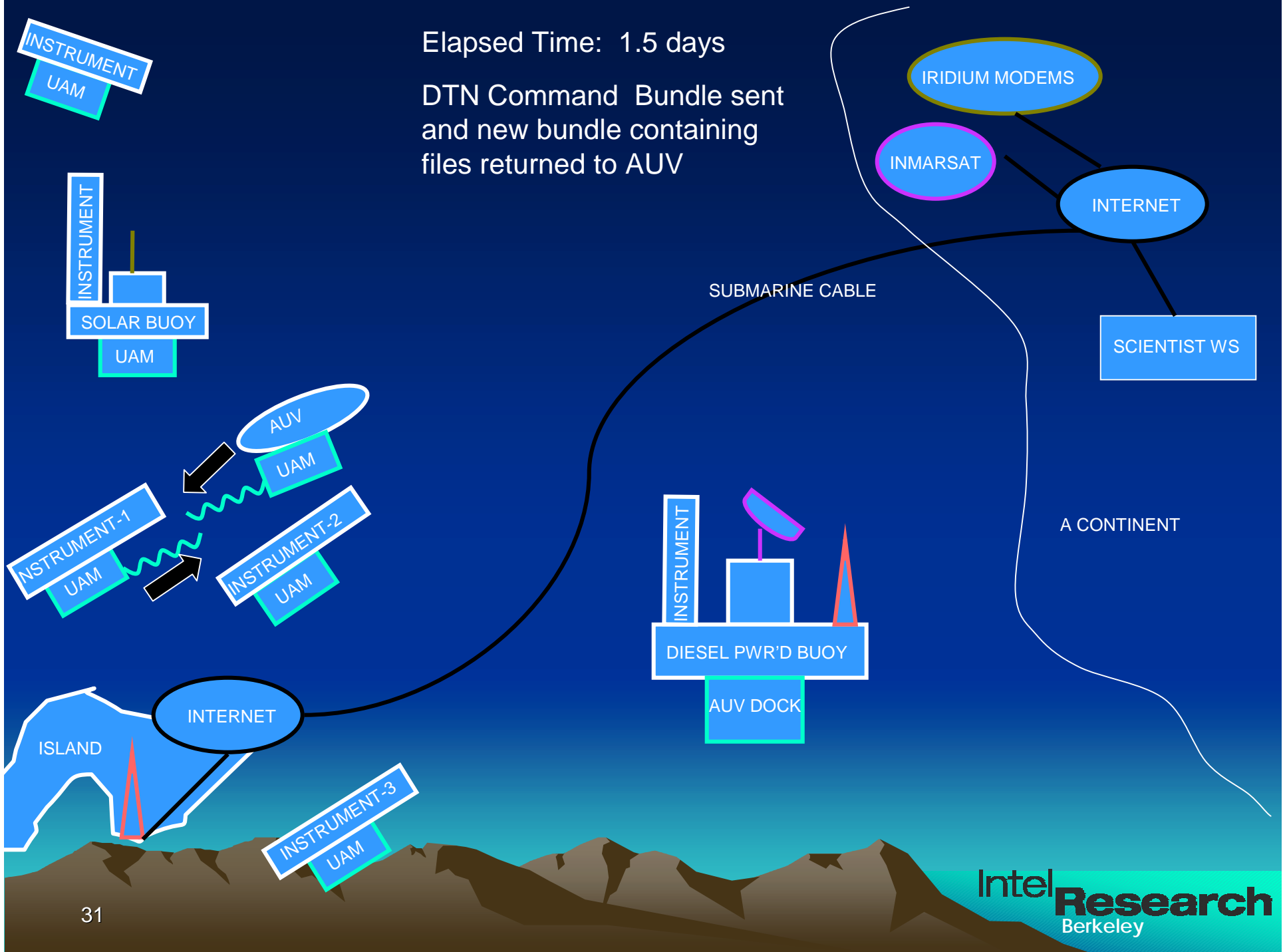
Elapsed Time: 14 hours

Bundle containing command enters Iridium Region and is delivered to AUV



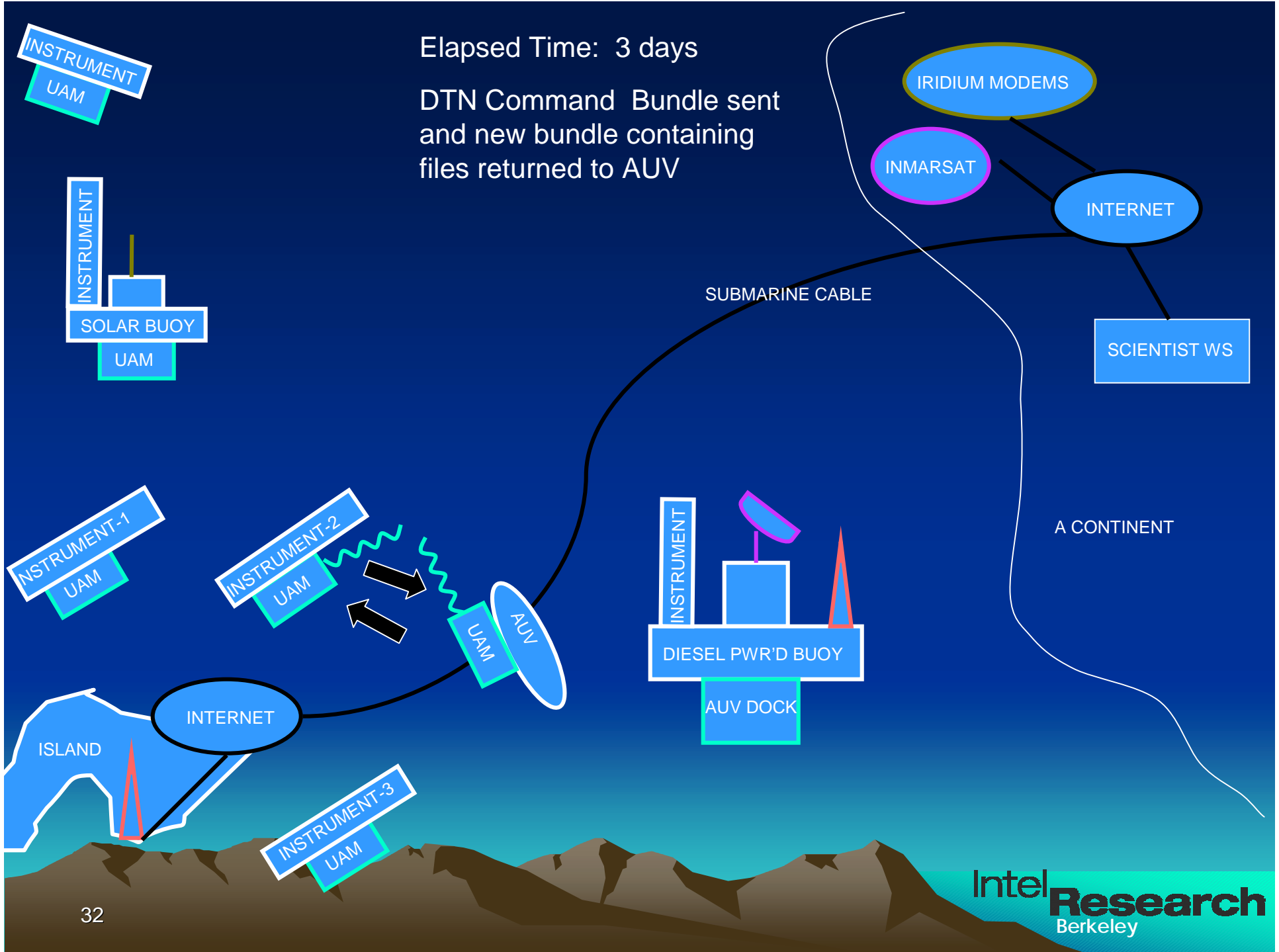
Elapsed Time: 1.5 days

DTN Command Bundle sent
and new bundle containing
files returned to AUV



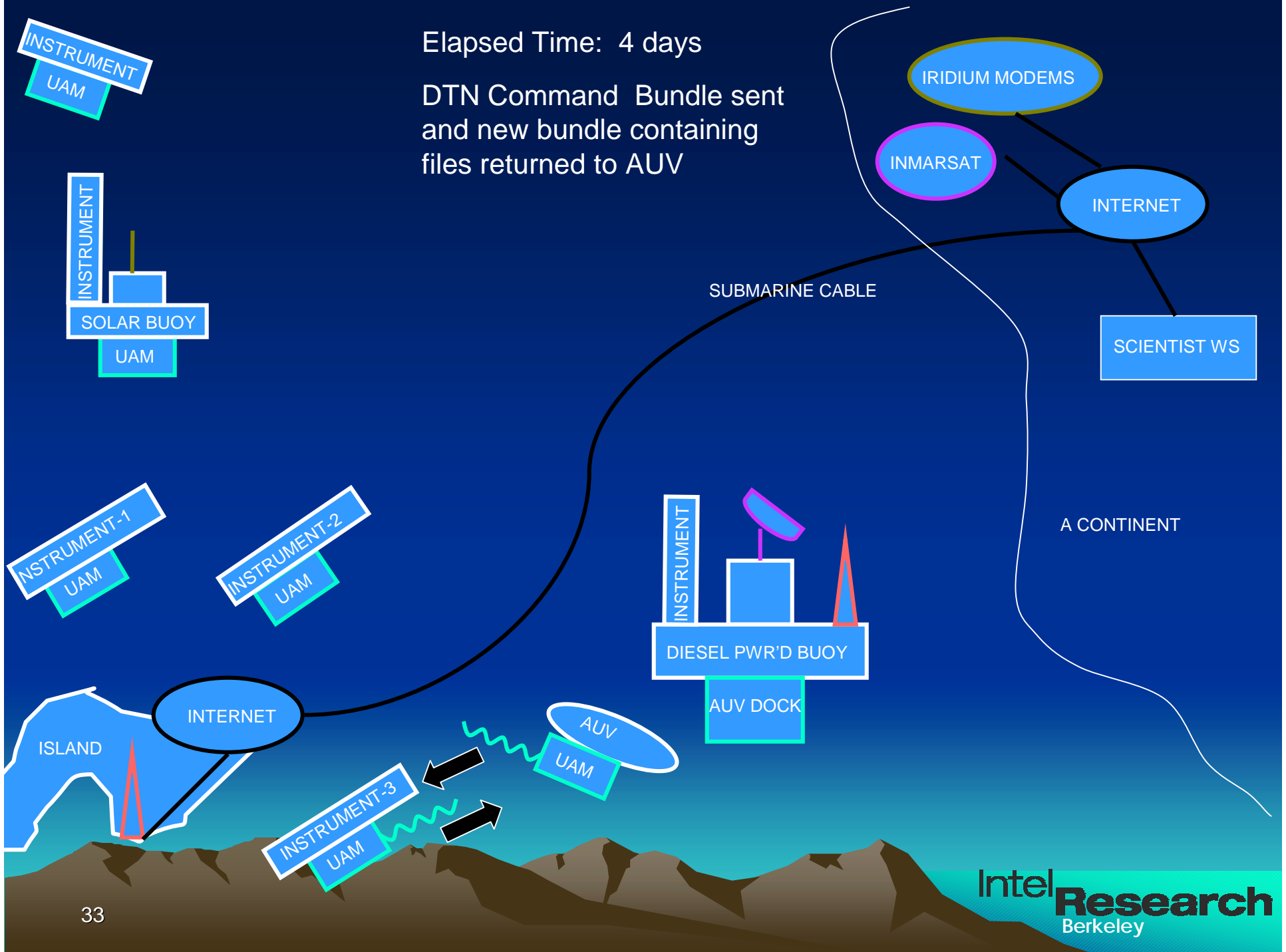
Elapsed Time: 3 days

DTN Command Bundle sent
and new bundle containing
files returned to AUV



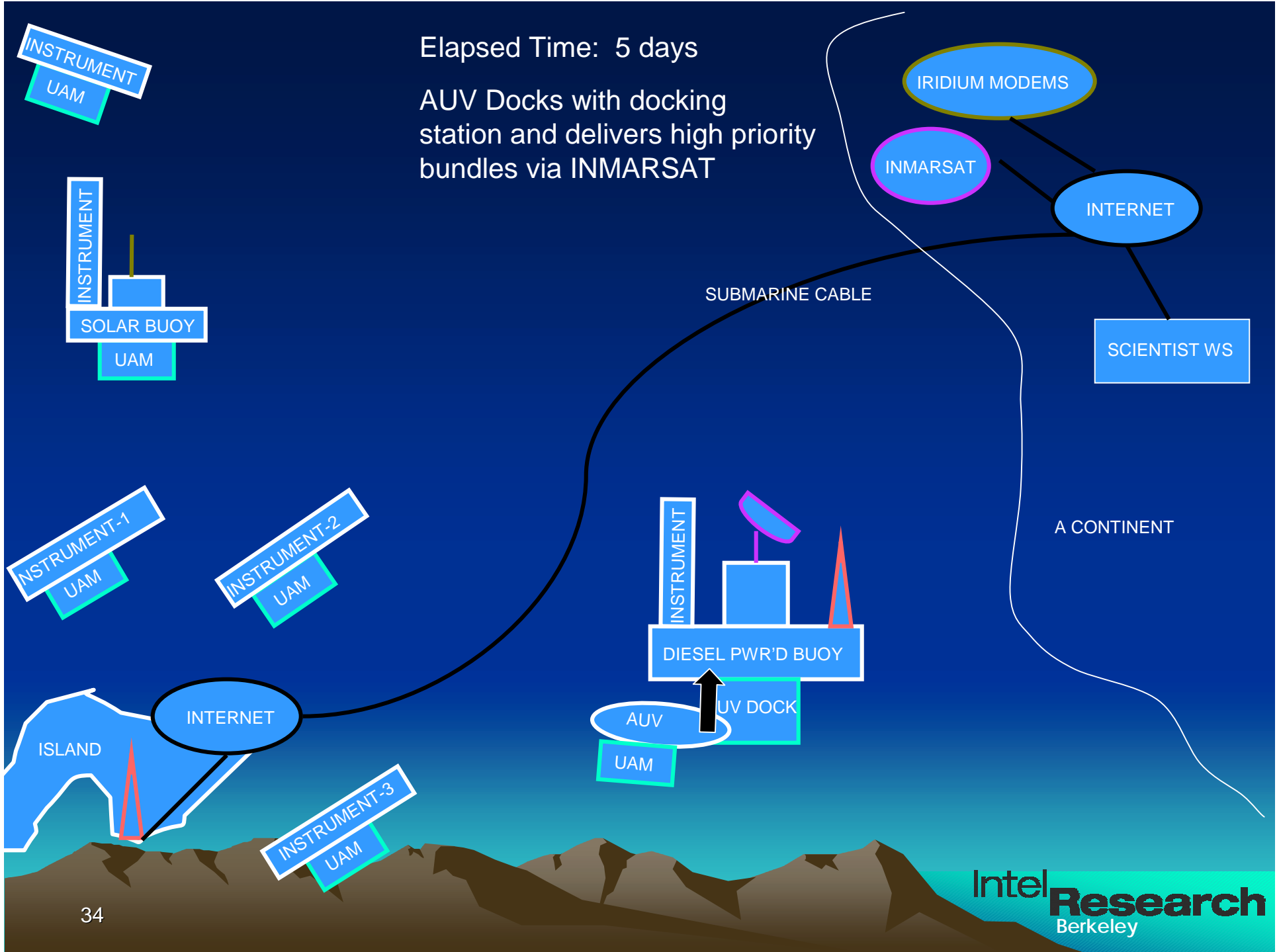
Elapsed Time: 4 days

DTN Command Bundle sent
and new bundle containing
files returned to AUV

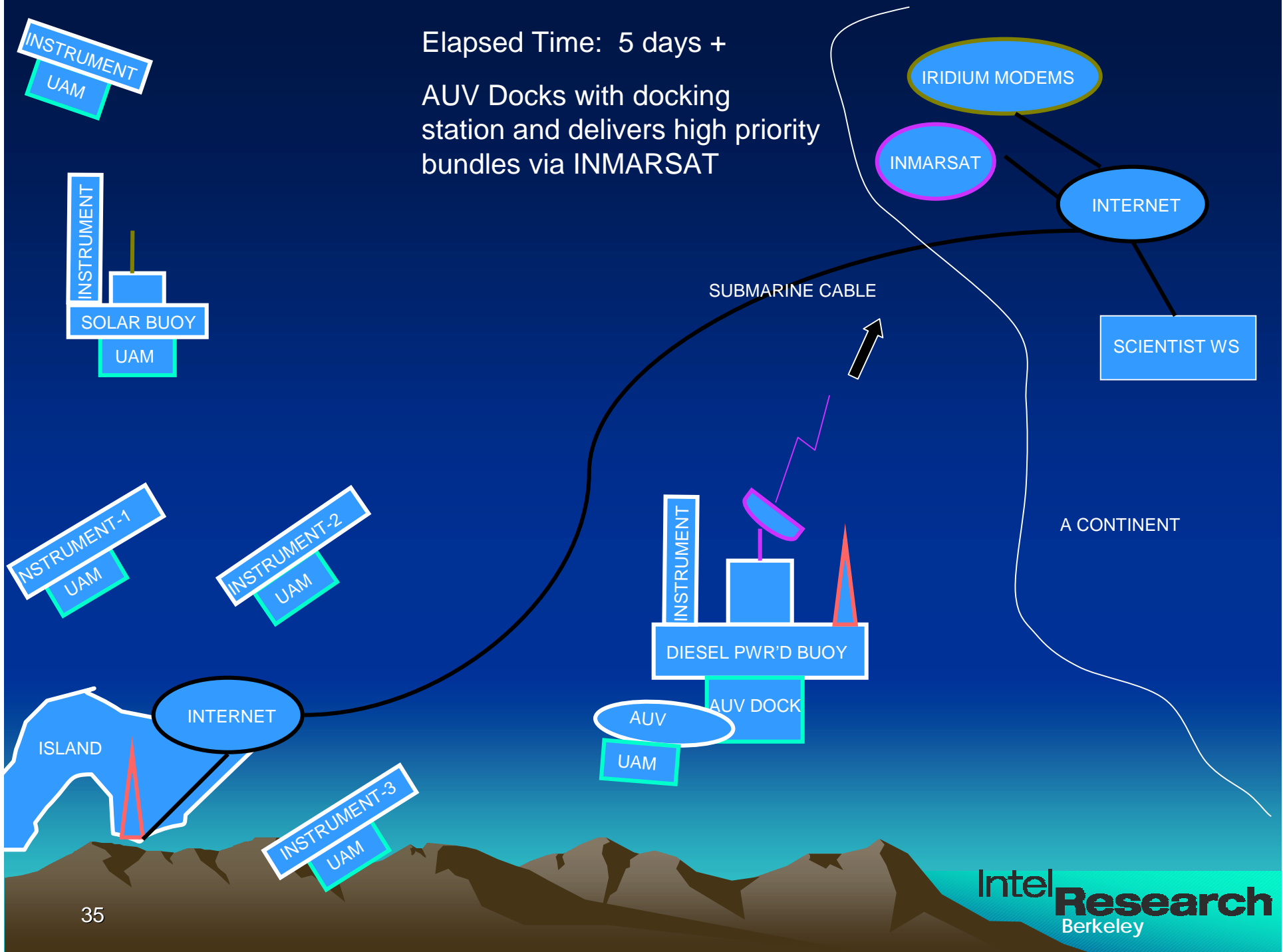


Elapsed Time: 5 days

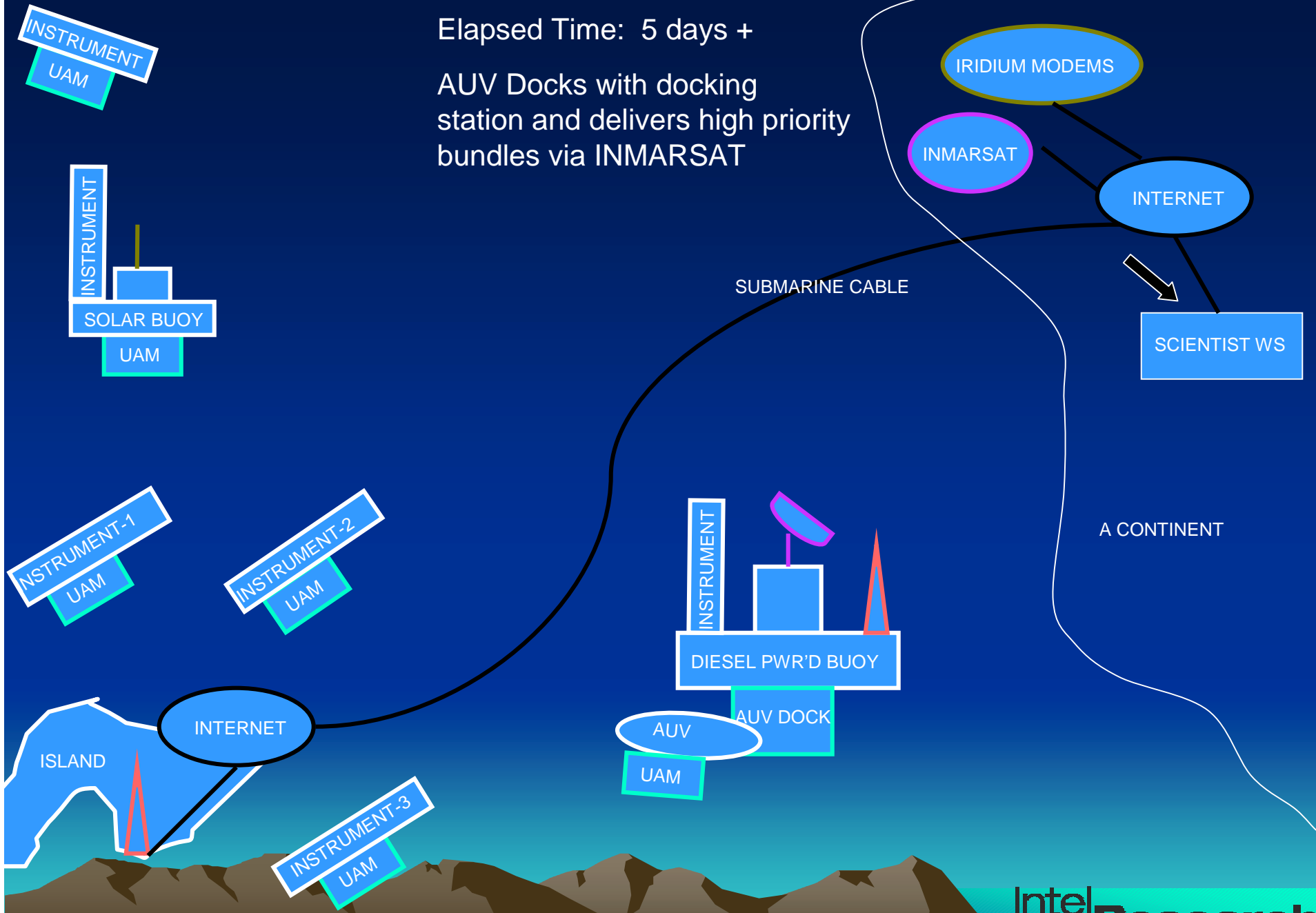
AUV Docks with docking station and delivers high priority bundles via INMARSAT



Elapsed Time: 5 days +
AUV Docks with docking station and delivers high priority bundles via INMARSAT

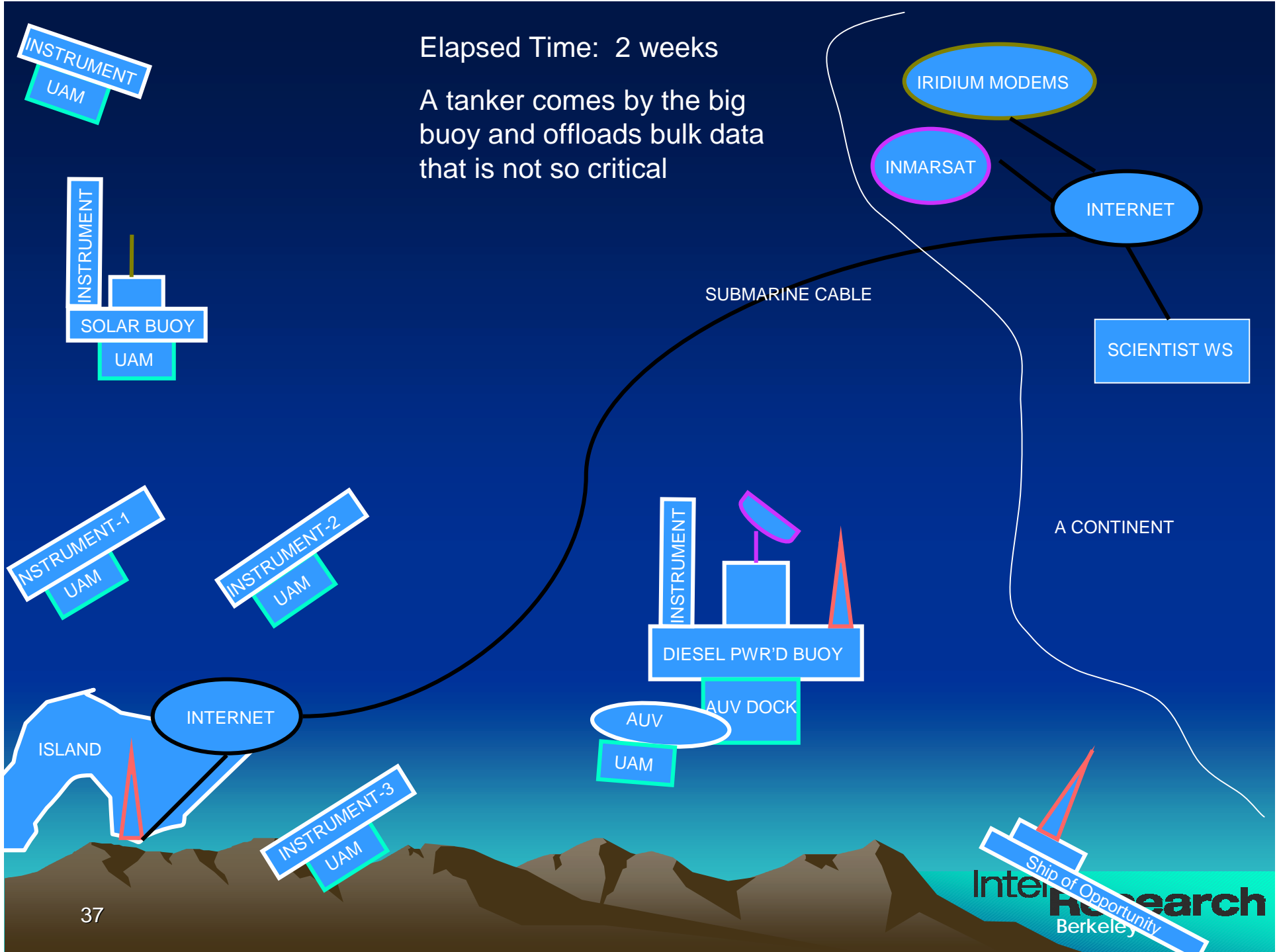


Elapsed Time: 5 days +
AUV Docks with docking
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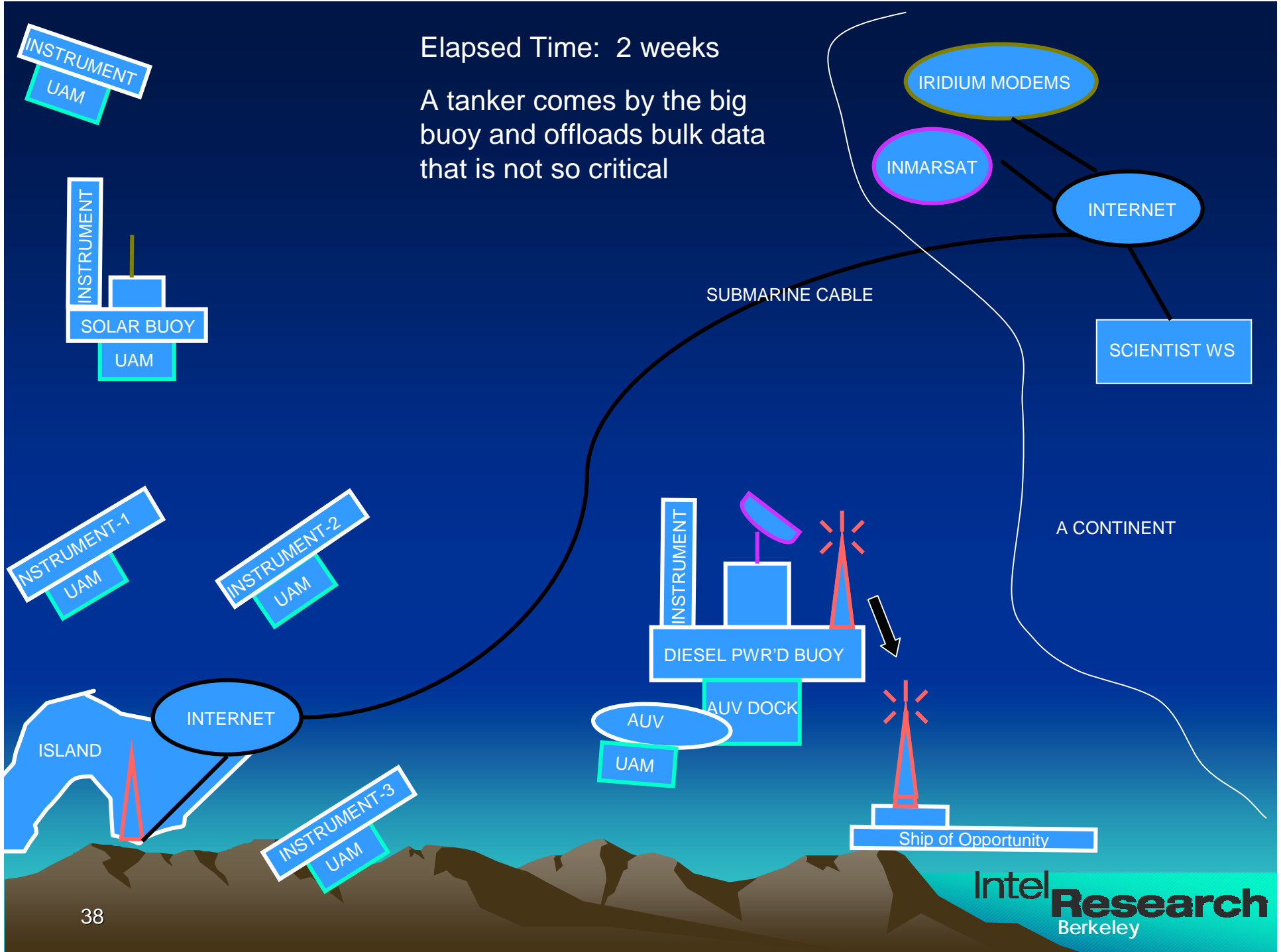
Elapsed Time: 2 weeks

A tanker comes by the big buoy and offloads bulk data that is not so critical

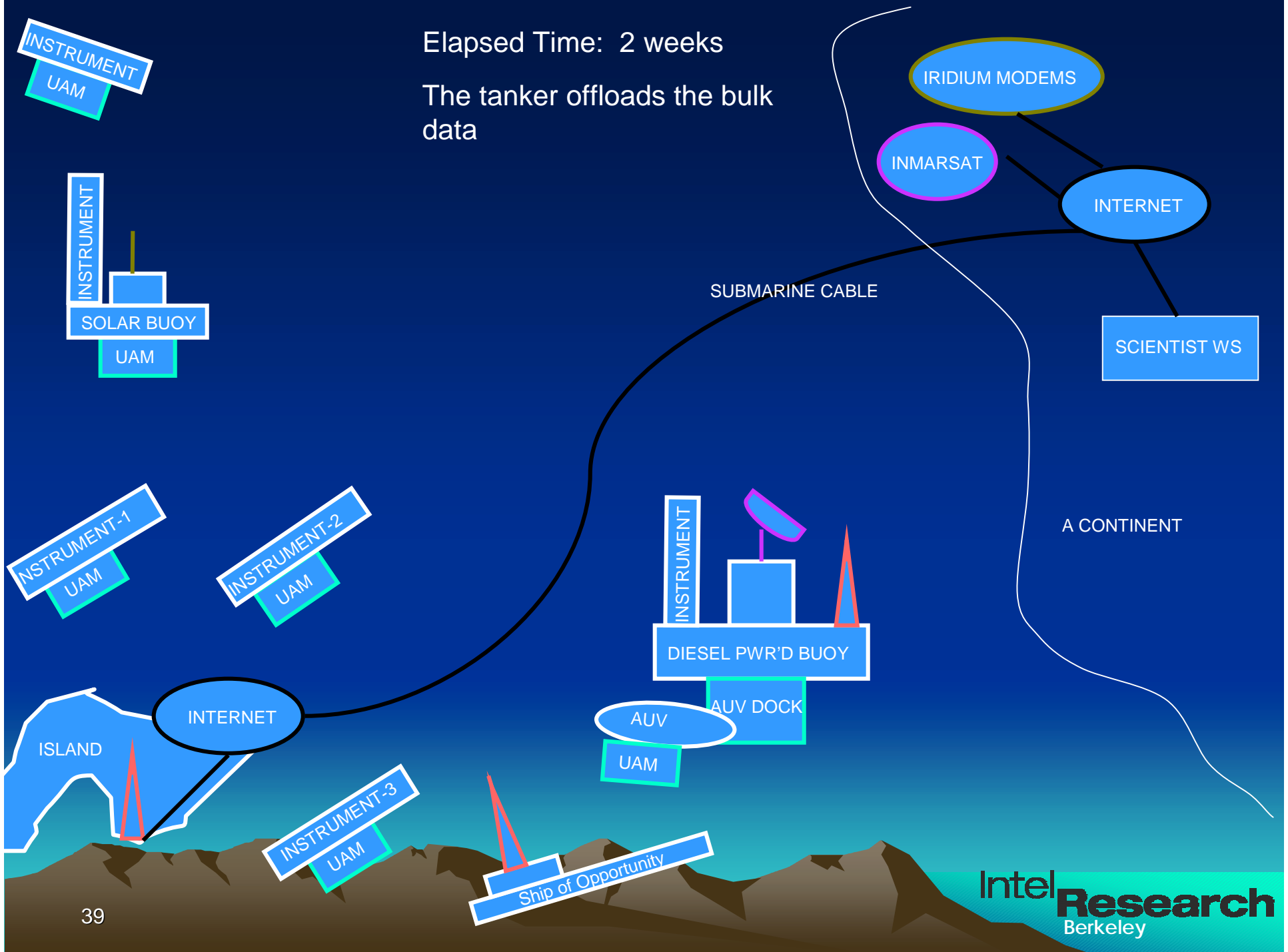


Elapsed Time: 2 weeks

A tanker comes by the big buoy and offloads bulk data that is not so critical

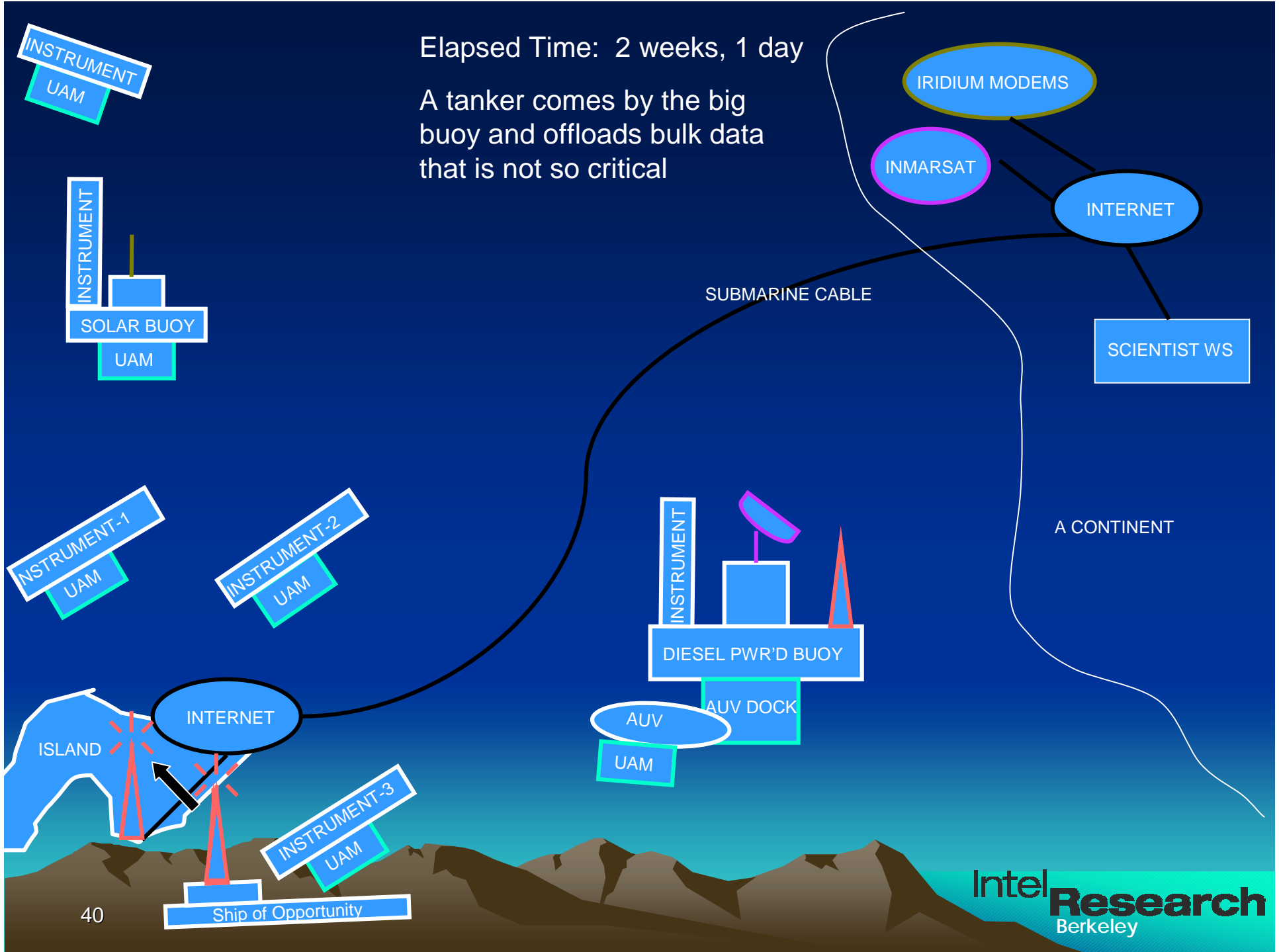


Elapsed Time: 2 weeks
The tanker offloads the bulk data



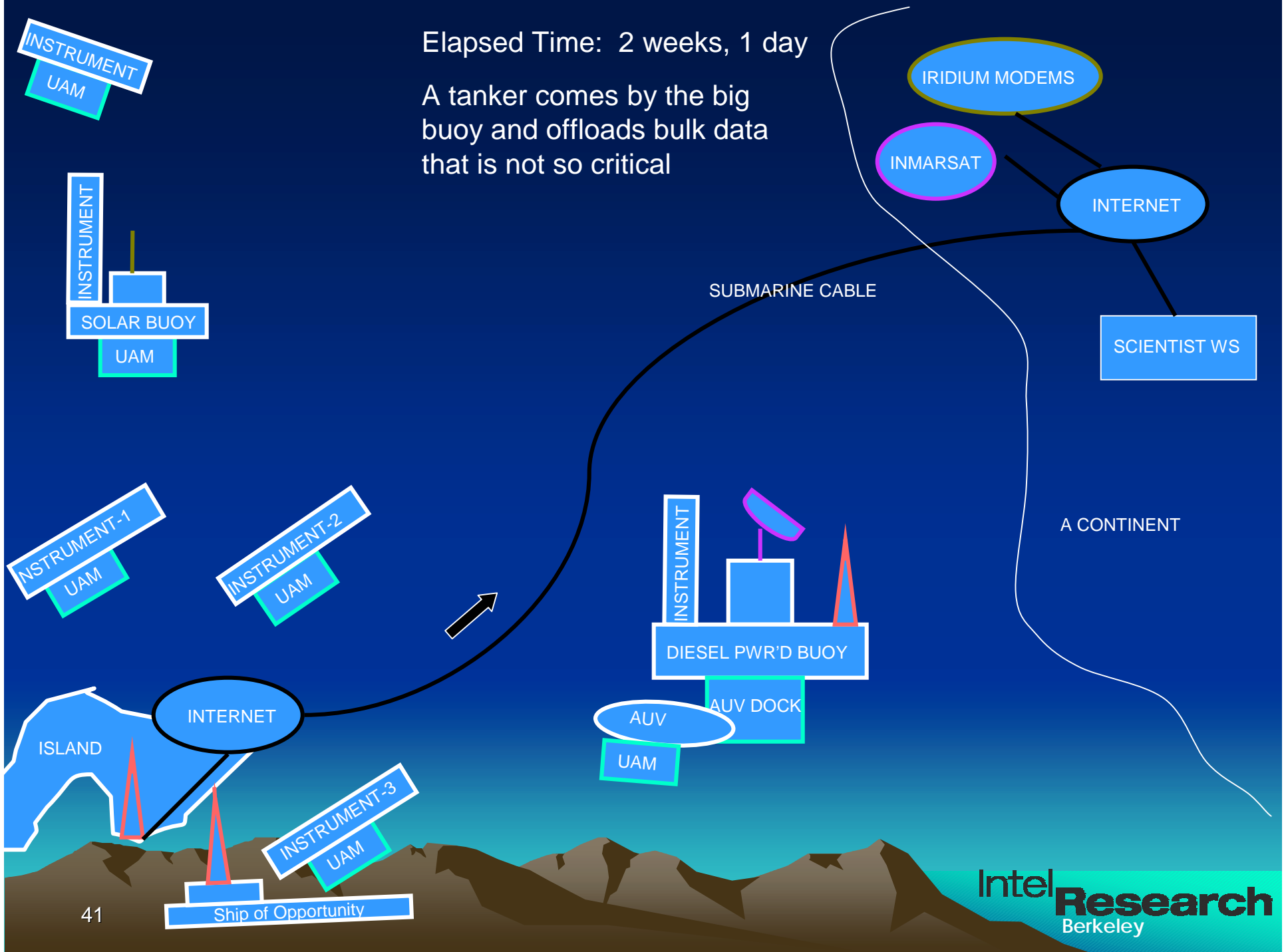
Elapsed Time: 2 weeks, 1 day

A tanker comes by the big buoy and offloads bulk data that is not so critical



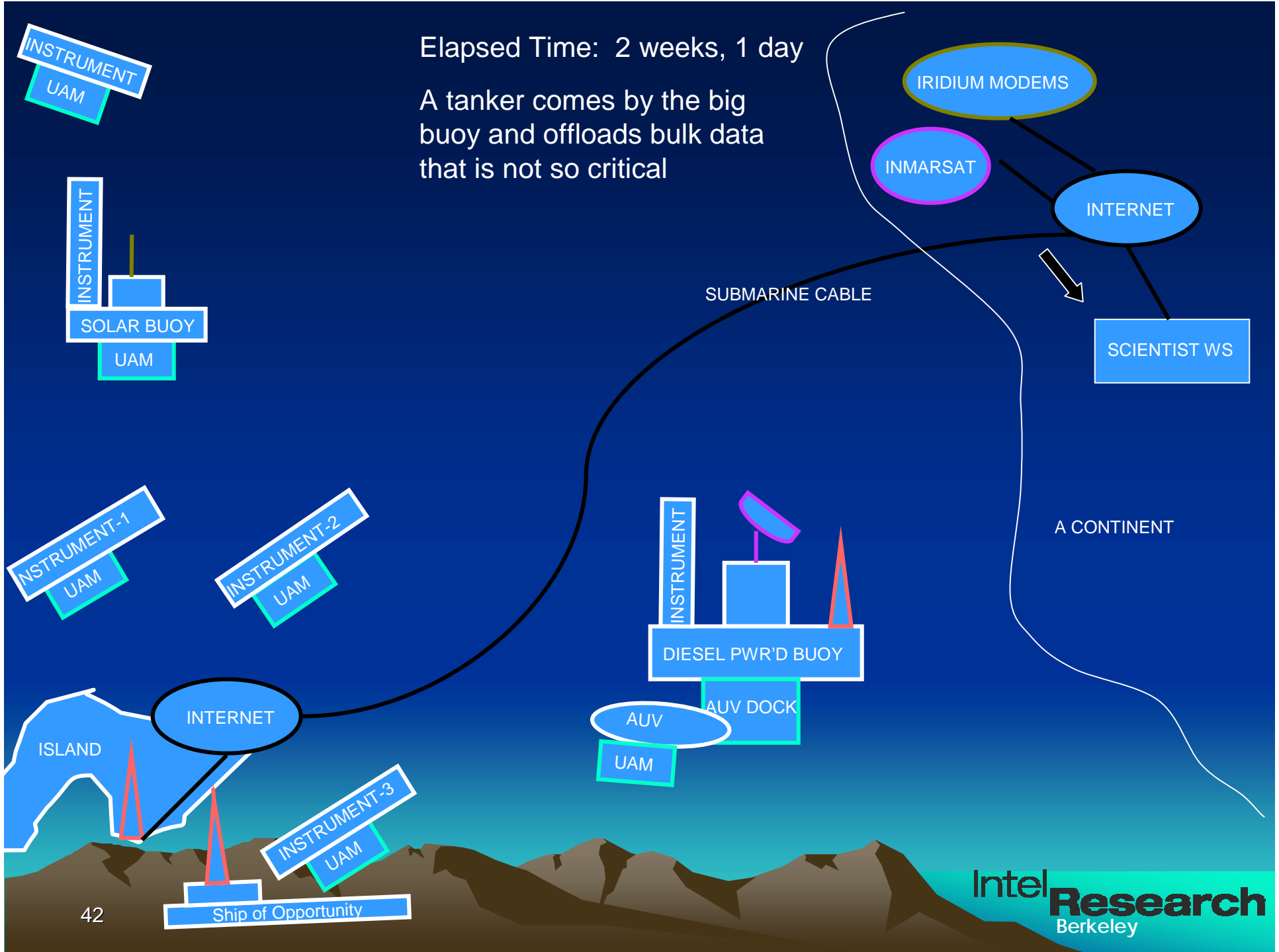
Elapsed Time: 2 weeks, 1 day

A tanker comes by the big buoy and offloads bulk data that is not so critical



Elapsed Time: 2 weeks, 1 day

A tanker comes by the big buoy and offloads bulk data that is not so critical



Reference Implementation Overview

- Written primarily in C++
 - ~22,000 non-comment lines of C++ (~5,000 in C)
 - 10K in generic system support classes (oasys)
 - 189 individual classes
 - Multithreaded using pthreads, mutex, spin lock
 - STL data structures (string, list, hashtable, ...)
- Emphasis on clarity, cleanliness, flexibility
- Ported to Linux, Solaris, Win32 / Cygwin, Linux on PDA (ARM), FreeBSD, Mac OSX

(Source line statistics generated using David A. Wheeler's 'SLOCCount')

Status

- IETF/IRTF DTNRG formed end of 2002
 - See <http://www.dtnrg.org>
- DTN1 Agent Source code released 3/2003
- SIGCOMM Papers: 2003 [arch], 2004 [routing]
- Several other documents (currently ID's):
 - DTNRG Architecture document
 - Bundle specification
 - Application of DTN in the IPN
- Basis for new DARPA DTN program
- Part of NSF 'ICT4B' Project (with UCB)

Naming and Addressing

- Support ‘radical heterogeneity’ using regions:
 - Regions define a namespace (or address space)
 - *May* be defined based upon network topology
- Endpoint Name: ordered name pair $\{R, A\}$
 - **R**: region name [globally valid], used as routing hint
 - **A**: admin ID-- region-specific, opaque outside region **R**
 - **example**: $\{\text{sys1.iridium}, +18455551212\}$
 - represent as an Internet-style URI [see RFC2396]
- **Late binding** of **A** helps isolated nodes:
 - Only resolve **A** to address [if necessary] in transit
 - **A** interpreted only by nodes assigned region **R**
 - semantics implemented only in appropriate region

Acknowledgements

- DTN/ICT4B Contributors:
 - Eric Brewer, Mike Demmer, Rabin Patra (UCB)
 - Bob Durst, Keith Scott (MITRE)
 - Kevin Fall, Melissa Ho (Intel Research Berkeley)
 - Sushant Jain (Univ. of Washington)
 - S. Keshav (U Waterloo)
 - Ting Liu (Princeton)
 - Vint Cerf (MCI)
 - Scott Burleigh, Adrian Hooke (NASA/JPL)
 - Stephen Farrell (Trinity College, Ireland)
 - The *dtn-interest* mailing list and DARPA
- Thanks also to Andy Maffei & Matt Grund (WHOI)

Matt Grund's [whoi] q's

- How do you buffer the data?
 - in files or in database system [abstract api]
- How do you decide when to send the data?
 - Depends on type of link:
 - if 'on demand', then right away
 - if 'scheduled', then not until schedule tells us to [also, some notion of remote side initiating connection– NAT]
- What's the Ack scheme? How success indicated?
 - hop-by-hop acks ~ “custody transfer”
 - end-to-end “return receipt”, if requested
- Could you demo it at WHOI?
 - yes, but not now 😊