Tethered Vehicle Activities 2005

Andy Bowen









Tethered Vehicle Upgrades

- Replacement control vans (planning underway for swap 12/05)
- *Medea* upgrades
- **Surface location beacon (GPS/Iridium)**
- Slurp pump test and evaluation
- 3-chip science video camera
- **Homer probes -- in hand and tested**
- 300 kHz Doppler for *DSL120A* and *Jason* (spare to 1200 KHz)
- New bio boxes for use with elevator
- **Summer/Fall maintenance periods**
- Pixelfly mosaicing camera with strobes
- Continued work on *Jason* to *Medea* navigation
- Improved video annotation
- Insite digital still documentation camera added

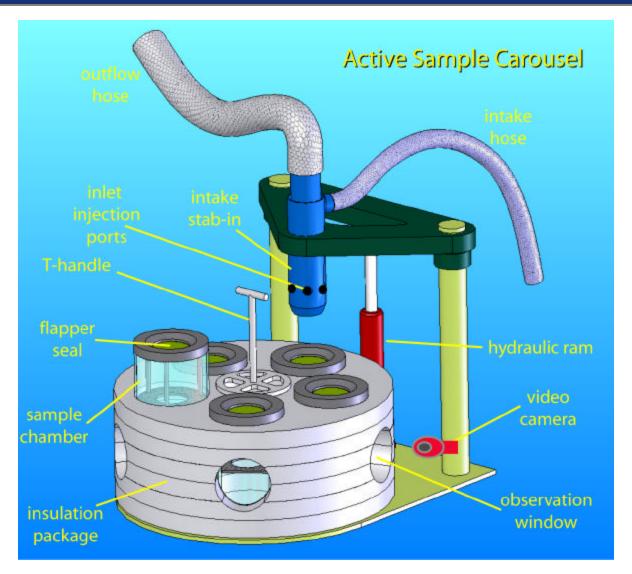








New DSG Multi-Chamber "Slurp"











DSG Slurp Pump Update

- Suction Pump designed and installed on Jason
- Canister valving candidates identified with prototype fabrication/test Summer '05
- **Expect additional tests Fall of '05**









ROV Control Van Upgrades

- New vans received Fall '04
- Conversion planned for late '05
- Improved ergonomics for the data station
- Lower maintenance HVAC (no S.W. required)
- UNOLS/USCG compliant
- Significant upgrade to the monitors and displays









Medea Modifications

- Pixelfly (color/B&W) and Insite digital still cameras with strobes
- Scanning sonar
- Color video camera
- Thrusters for heading control
- Additional science payload interface (power, telem and physical space)
- Stand-alone power and surface control
- Modifications during August maintenance period







