NDSF Operator's Report

DESSC Meeting Dec. 12, 2004









Personnel Changes

- Bob Detrick replaced Dick Pittenger as WHOI's Vice President for Marine Facilities and Operations.
- Liz Caporelli replaced Jon Alberts as Marine Operations Coordinator.
- Dan Fornari stepped down as Chief Scientist of Deep Submergence; now Director of WHOI's Deep Ocean Exploration Institute.









Chief Scientist of Deep Submergence (CSDS) Search

- Search committee formed and position nationally advertised in Spring 2004.
- Candidates interviewed in Summer 2004.
- Maurice Tivey offered and accepted CSDS position through end of 2005; pending his appointment to the WHOI senior scientific staff, Chris German will assume CSDS position in 2006.











2004 NDSF Operations Summary

NDSF Operator's Report



DSV-2

ALVIN

<u>1964-2004</u>



40 years 4,000 dives













2004 ALVIN Operations Summary

NDSF Operator's Report

(as of 12/1/04)

- 213 operating days
- 9 science cruises
- 113 days on station
- 102 dives
- 766 hrs submerged (32 days)
- 7.5 hrs avg/dive
- 474 hrs on bottom (20 days)
- 4.7 hrs avg bottom time/dive
- 2,473 m average depth
- **\$2.4M** budget



Current Ops Group: 3 pilots 6 technicians

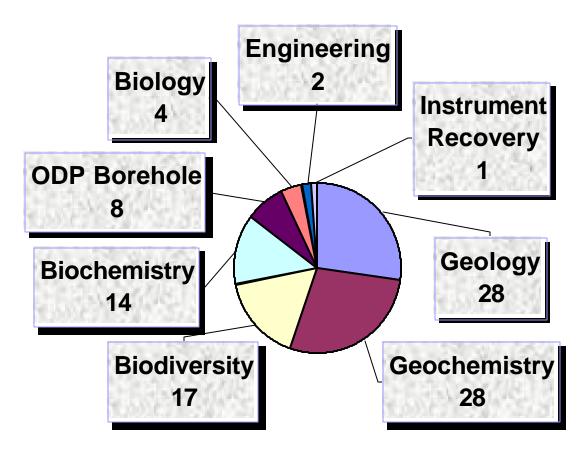








ALVIN Dive Discipline Breakout





All 2004 dives were in the Pacific, including the Gulf of Alaska









NDSF Support Ships in 2004

NDSF Operator's Report

UNOLS vessels used in support of NDSF 2004 operations:

– R/V Atlantis (8 Alvin legs)

- R/V Knorr (2 Jason II legs)

- R/V Revelle (2 Jason II legs)

- R/V Thompson (Jason II DSL-120 leg)

– R/V Kilo Moana (DSL-120 leg)









2004 ROV Operations Summary

- 193 operating days
- 7 science cruises
 - 4 different ships
 - operations from 32S to 53N
- 46 lowerings
 - 39 Jason, 7 DSL-120a
- 1,224 hrs on bottom *(51 days)*
- 328,000 framegrabs from video
- 100th *Jason* dive
- Longest Jason lowering to date (71 hrs on bottom)
- First combined Jason/ABE ops
- \$3.3M budget











Tethered Vehicle Activities '04

- Replacement control vans (planning underway for swap 12/05)
- Designing new shop area (Blake Lab renovations)
- New Medea
- Surface location beacon (GPS/Iridium)
- SM2000/DSL120a test/evaluation
- Science pan & tilt (with camera)
- First use of slack-tensioner
- Homer probes
- New corers
- Fall WHOI dock trial/maintenance period
- Auto altitude (DVL or Simrad altimeter as input)
- Initial evaluation of Jason to Medea navigation
- New DVD duplication station









Support Ship Issues

- Variability in DP operations from vessel to vessel (possible problems with ship propulsion; especially AGOR-23 bow thrusters)
- Lack of consistent crew training/experience in use of DP systems
- Operators moving cruises without discussing ramifications on ROV ops
- Lack of consistency among ship operators with respect to mob/demob and shipboard crew/tech expectations; billing procedures; definition of an in-port day
- Security for vessels in port
- U.S. Customs require original signed 4455 Certification of Registration; (URL for the form on the WHOI web site below) http://www.whoi.edu/marine/ndsf/cruise_planning/forms/intl_ship_summ.pdf











WHOI Access to the Sea Task Force

- Internal Task Force charged with developing a vision for the types of ships, vehicles, and ocean observing systems that will be required over the next 10-15 years to address the highest priority scientific questions in the oceans
- Four working groups on Ships and Ship Operations;
 Vehicles and NDSF; Ocean Observatories and
 Observing Systems; Scientific Data Management
- Report completed in July 2004









Access to the Sea Task Force NDSF-Related Recommendations

- DESSC, UNOLS and the funding agencies need to consider how NDSF will evolve over the next 5-10 years in light of the increasing numbers of tethered and autonomous vehicles in the community and the expected increase in demand for deep submergence assets by ocean observatories.
- Future vehicle needs include new HOV; HROV/AUV; ALVIN rescue vehicle; observatory-capable ROV, AUV.









Access to the Sea Task Force NDSF-Related Recommendations

- NDSF needs to establish data protocols and procedures to insure the quality of data collected by NDSF vehicles, and develop the proper tools to process, archive and serve these data to potential users.
- NDSF needs to more closely integrate the Alvin and ROV operations groups to emphasize the common elements shared by all vehicles.
- NDSF management and DESSC continue to work together to identify ways of obtaining candid feedback from users of NDSF vehicles.











NDSF Operator's Report

- 1. Frame Grabber *Alvin* and *Jason2*, and WHOI Ships Examples and practical approach to providing useful data and metadata on a real-time and archiving basis as well as a template for migration of legacy data.
- 2. Summary of income from NDSF vehicle imagery/data and WHOI outreach

(~ 1/2 FTE at WHOI deals with NDSF imagery issues)



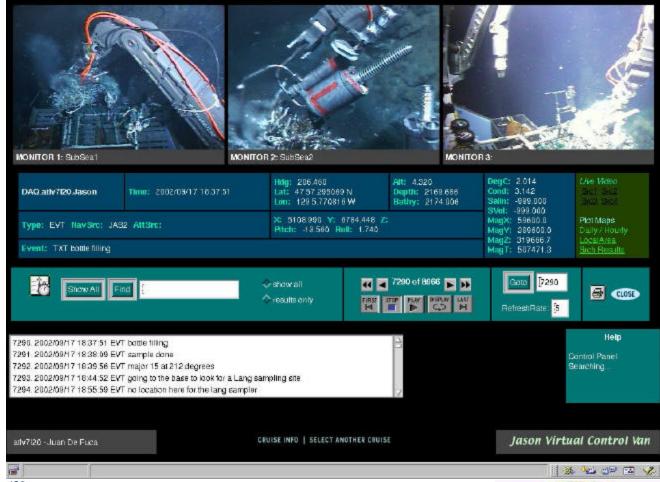






NDSF Operator's Report

1. Frame-grabber - Alvin and Jason2











Virtual Van Image Highlights











NDSF Operator's Report

Frame-grabber - Alvin and Jason2 and WHOI Ships

Main Entry Point URL:

http://www.whoi.edu/home/research/data_center.html

Entry Point URLs for Alvin, Ships and Jason2:

http://4dgeo.whoi.edu/alvin/FG_cruises.html

http://4dgeo.whoi.edu/shipdata/SDG_shipdata.html

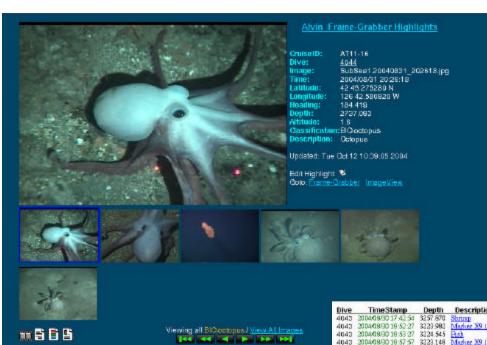
http://www.whoi.edu/marops/vehicles/jason/van_cruises.html







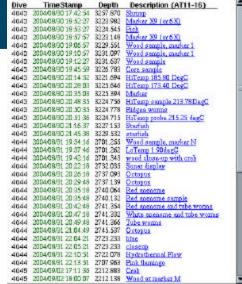
















NDSF Operator's Report

2. Summary of income from NDSF vehicle imagery/data and WHOI outreach

- 350 visual requests to date in 2004. The requestors include such diverse organizations as the National Academies, National Science Foundation, Office of Naval Research and NOAA, John Wiley and Son Publishers, Grolier, McGraw Hill, Dorling Kindersley Publishing in the United Kingdom, Geo Magazine, and Popular Mechanics magazine in South Africa.
- We have also provided materials for many exhibits and special presentations at such locations as the American Museum of Natural History in New York City, Museum of Science in Boston, The Ocean Institute in Dana Point, CA, the Hull Museum in London, and museums in Austria and Germany.
- We also responded to dozens of educators around the country sharing information with their classrooms separate from the many web sites and other educational activities we also support with images and information, such as Dive and Discover, Extreme 2004, NOAA Ocean Explorer, etc.

Total 2004 income received to date is \$27,898.



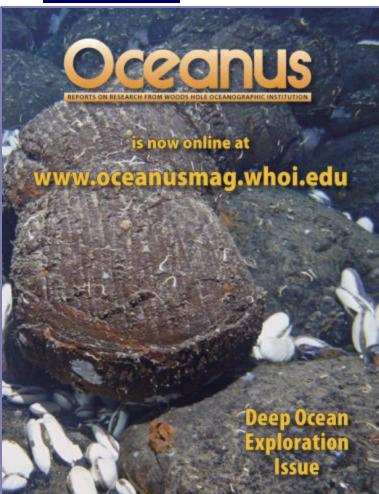






NDSF Operator's Report

Oceanus - Issue on Deep Ocean Exploration



Oceanus Magazine

EXPLORING THE OCEANS IN DEPTH

Follow the latest research, discoveries, and expeditions from Woods Hole Oceanographic Institution at www.oceanusmag.whoi.edu or sign up online to receive printed issues at www.oceanusmag.com. For more information, e-mail jhopewood@whoi.edu or call (508) 289-3516.

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Survey of Future Needs and Upgrades for Deep-Submergence Biological Research

Posted March 12, 2004 37 Respondents

Macro-ecology - 28

Microbiology - 4

Bio-instrumentation/engineers - 2

Geology & Geophysics- 3

http://www.surveymonkey.com/s.asp?u=99909386548









^{*}Results from Biologists only

Survey of Future Needs and Upgrades for Deep-Submergence Biological Research

Survey Design:

Demographics (discipline; usage; future importance)

Tools and Samplers (usage; priority for upgrade/replacement)

Vacuum Samplers

Biobox Collection Boxes

Imaging Systems

Biological Mapping

OPEN FORUM

Demographics - experience

73% used HOVs in the past 2 years (1% never)

63% used ROVs in the past 2 years (7% never)

41% used Towed Vehicles in the past 2 years (38% never)

24% used AUVs in the past 2 years (67% never)









Tools and Samplers (12 options)

Used most often:

74% - Vacuum samplers

63% - Manipulator Claw

59% - Sediment push cores

56% - Nets and Scoops

56% - Bioboxes

40% - Water chem/in situ sensors

37% - Quantitative faunal samplers

Importance for future research:

70% - very important

61% - very important

36% - very important

28% - very important (32% not impt)

54% - very important

57% - very important

30% - very important (35% not impt)









Tools and Samplers – Upgrades

(highest; high; medium; low)

Highest	Priority f	or <i>Alvin</i> :
---------	------------	-------------------

50% - Manipulator Claw

40% - Sediment push cores

11% - Nets and Scoops

29% - Bioboxes (44% impt)

65% - Water chem/in situ sensors

50% - Quantitative faunal samplers

Highest Priority for Jason II:

50% - (44% high)

33% - (53% high)

43% - (14% high)

25% - (25% high)

21% - (50% high)

71% - (18% high)

27% - (27% high)









Vacuum Samplers (Summary)

- 60% of respondents have used one in the past 3 years
- Only 22% satisfied with current samplers available with Alvin
- Optimal size chamber is 2 liters (37%)
- 8 to as many as possible chambers desired (56%)
- Chambers must be free of contamination, thermally insulated,
 removable, adjustable for size (50%)









Biobox Collection Boxes (Summary)

- 63% of respondents have used one in the past 3 years
- 55% are not satisfied with currently available boxes
- Boxes must free of contamination (61%), thermally insulated (58%), compartmentalized (58%), adjustable for size (56%); provided by the NDSF (73%); 55% of biologist use boxes not provided by themselves
- Good sealing mechanisms, Clear lids, Easy to drain









Imaging Systems (Summary)

	Alvin	Jason II
Important to current research	85%	92%
Satisfied with overall quality	49%	35%
Importance to upgrade	78%	78%
How? Camera resolution	71%	67%
How? Camera configuration	57%	60%
How? Lighting intensity	57%	60%
Importance to quantify	72%	87%
increase quantitative usability	75%	87%

Upgrade suggestions:

JII: "computer decoded holography; 3D diffractive elements instead of lenses; high-res digital still on J2, record the zoom and angle of the cameras" Alvin: "record all Alvin channels, access to High Definition, better resolution pan and tilt on Alvin, move the Alvin 3-chip off the arm"









Biological Mapping (Summary)

Alvin Jason II

Prior use of vehicle to map 56% 25%

Importance of image resolution upgrade 95%

Importance to navigation resolution upgrade 91%

Comments: "Doppler navigation has been a great help with Alvin"

Upgrade suggestions: "The most important thing for biologists in mapping...is that the images be geo-referenced...funding should be put into continued navigation improvements" "Make high-accuracy navigation standard rather than a potentially costly option."









Open Forum (Selected Quotes)

"....a whole new breed of imaging systems to obtain 3-dimensional images will revolutionize the field."

"....it would be great if there were a submersible system that could function to assist mid-water research."

"....need a towed system that could be developed that senses a biological specimen and then takes a picture automatically. This could be towed for long periods of time and do a complete survey...independent of *Alvin, Jason*, or *ABE* (a new small vehicle)."

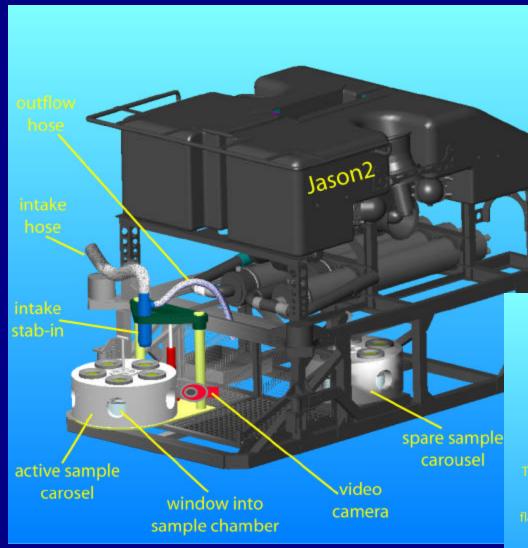
"....Use of elevators should be made more transparent...Has anyone actually compiled the data on using elevators with *Alvin* dives- are dives shorter with elevators than those without?...how often are they lost?"



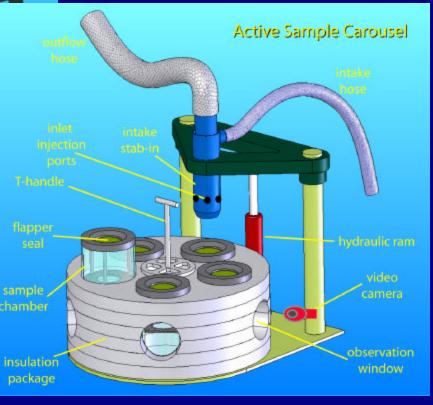






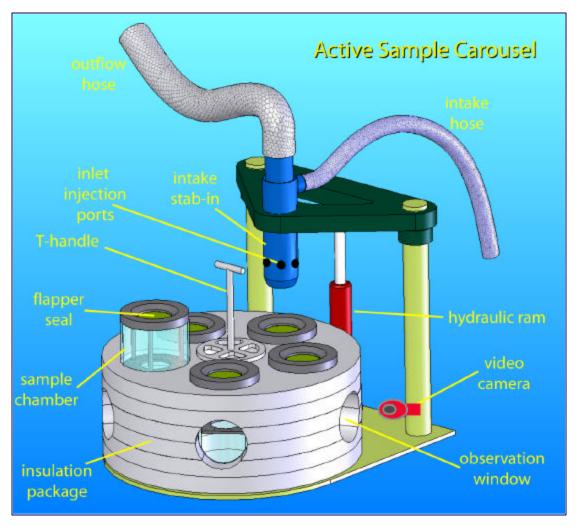


Funded Design for New Jason II Slurp Sampler





NEW DSG Multi-Chamber "Slurp"











DSG Doppler and Fiber Optic Gyro

- New spare 300 kHz DVL for use with DSL120 or Jason
- New spare 1200 kHz DVL for use with Alvin
- New Spare Ixsea Octans FOG for use with DSL120 or Jason
- Funds in hand for purchase of spare Ixsea Octans for Alvin (considering purchase of full INS)









Near-Bottom High Resolution Sonar

- Alvin:
 - Imagenix model 881, 675 kHz for profiling
 - Sunwest SS300 CTFM for OA
- Jason:
 - Imagenix 855 675 kHz for profiling
 - Imagenix 855 675 kHz for OA
- Shared Use (Jason II/DSL120a):
 - Simrad SM2000 multibeam

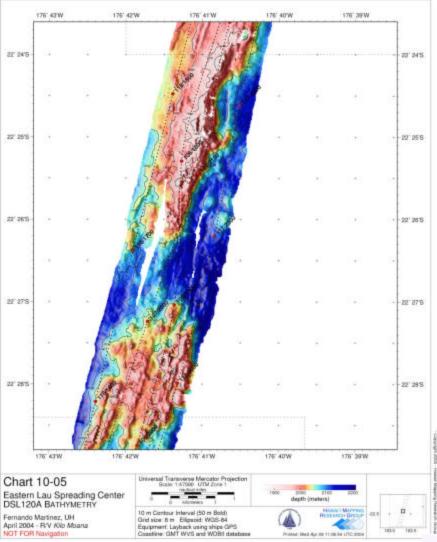








DSL-120a Bathymetry, F. Martinez (U of H) Cruise



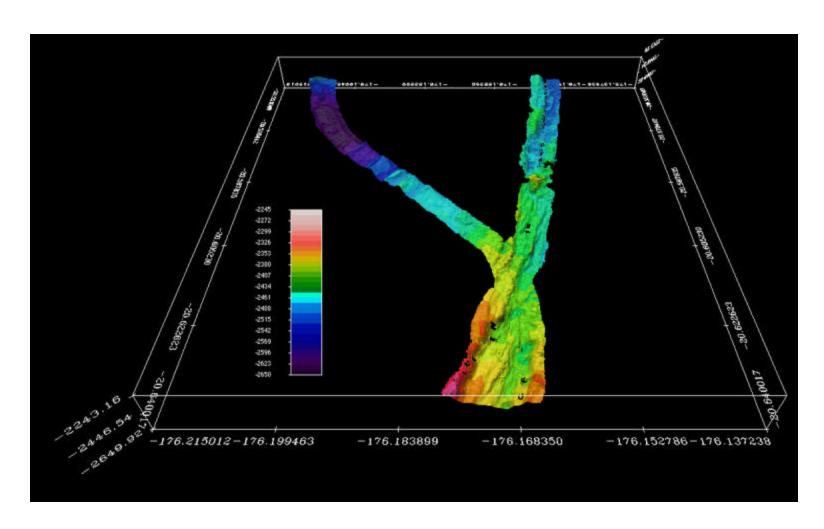








DSL-120a Gridded Bathy Shown in Fledermaus



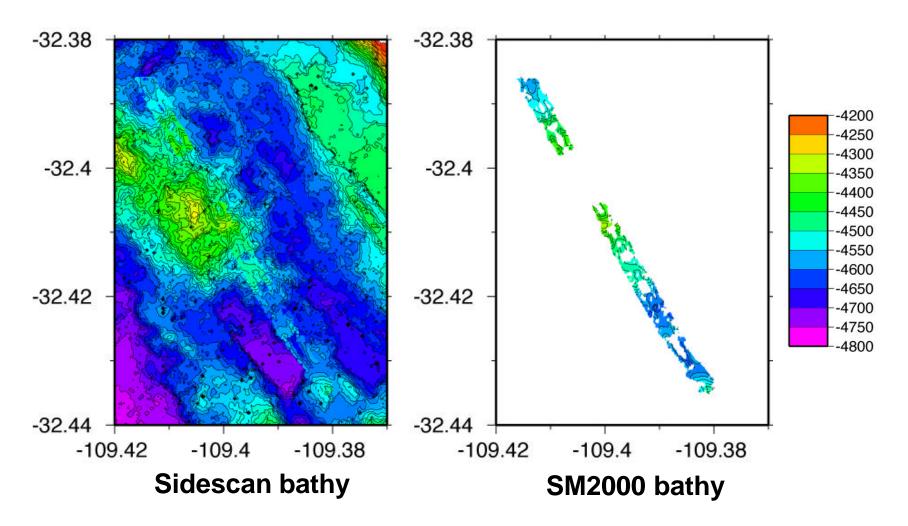








Examples of Data from R. Pockalny (URI) Cruise



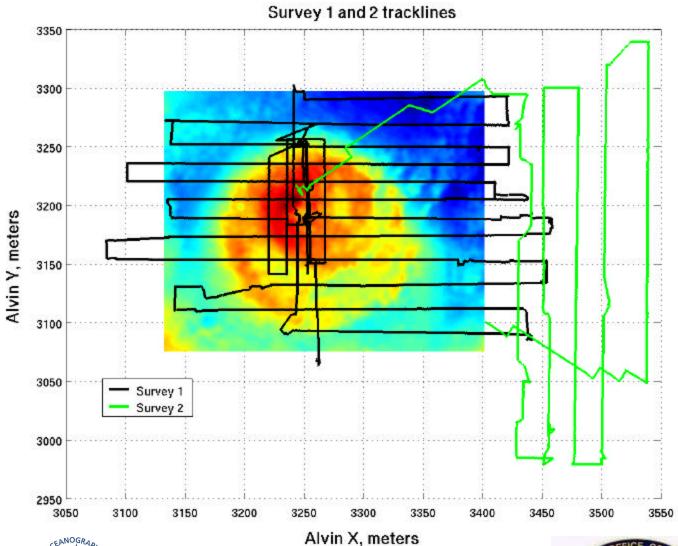








Jason II Track Lines Over TAG



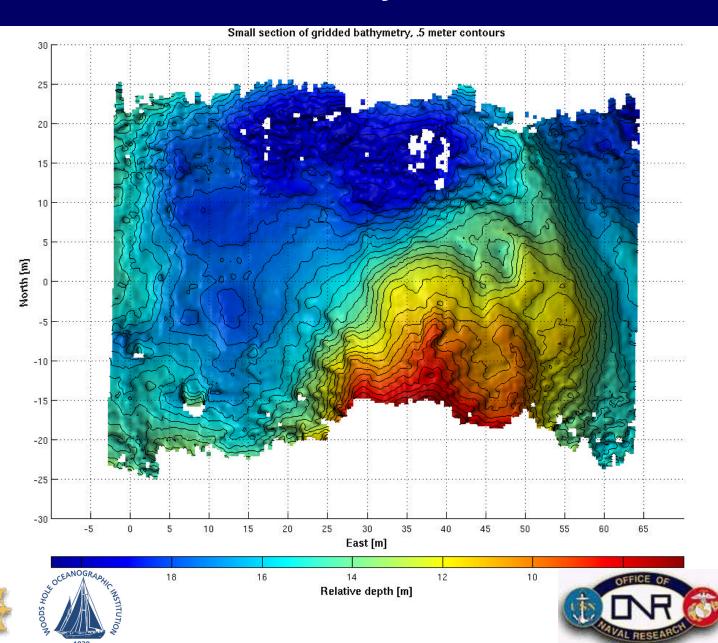








SM2000 Bathy from TAG



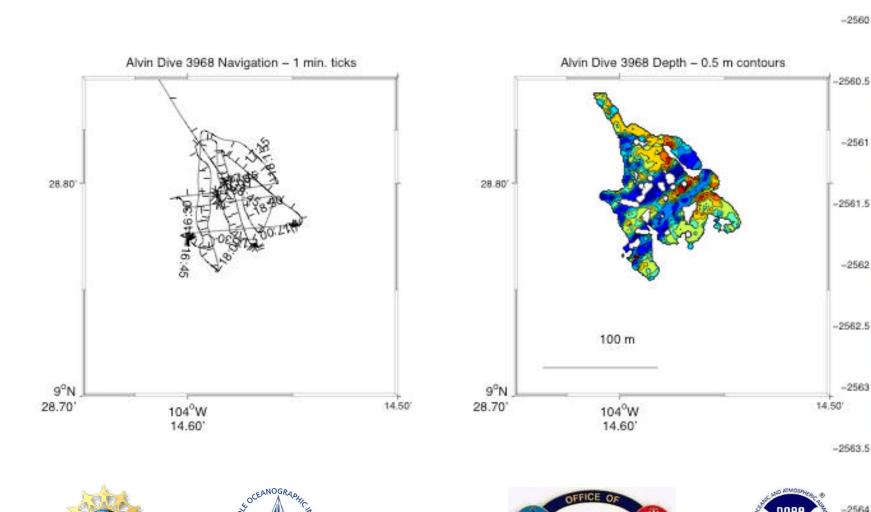
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-2561

-2562

-2563

Alvin Imagnex from H. Schouten on EPR





NDSF Navigation Update

OUTLINE

- 1. Review of Current Capabilities
- 2. What's New in 2004
- 3. What's Next









Navigation Sensors Review of Current Capabilities

Present Navigation Sensors

INSTRUMENT	VARIABLE	INTERNAL	UPDATE RATE	PRECISION	RANGE	DRIFT
Acoustic Altimeter *	Z - Altitude	yes	varies: 0.1-10Hz	0.01-1.0 m	varies	_
Pressure Sensor *	Z - Depth	yes	medium: 1Hz	0.0.01%	full-ocean	
Inclinometer *	Roll, Pitch	yes	fast: 1-10Hz	0.1° - 1°	+/ - 45°	-
Magnetic Compass *	Hdg	yes	medium: 1-2Hz	1 – 10°	360°	_
Gyro: MEMS	Hdg, Pitch, Roll	yes	fast: 10+ Hz	1°	360°	
Gyro: Fiber Optic, North Seeking *	Hdg, Pitch, Roll ω	yes	fast: 1-100Hz	0.1°	360°	_
12 kHz LBL *	XYZ	NO	varies: 0.1-1.0 Hz	0.01-10 m	5-10 Km	_
Bottom-Lock Doppler *	\dot{x}_{body}	yes	fast:1-5Hz	0.01m	varies	1-3%

Planned Future Navigation Sensors

Inertial	$\ddot{x},\omega,\dot{\omega}$	yes	fast: 10-1000Hz	0.01m		1%
300 kHz LBL	XYZ - Position	both	1.0-10.0 Hz	+/-0.01 m	100 m	i i i

* Presently supported on all NDSF vehicles: Alvin, Jason 2/Medea, and DSL120A.









Data Products Review of Current Capabilities

Moving toward a uniform navigation data products for all NDSF vehicles:

- Comma-delimited 1-second spreadsheet file (.CSV Suffix):
 - Logs time-stamped navigation and sensor data at 1 second intervals. 1 MB/hour.
 Compresses 5:1. Loads directly into spreadsheets (Excel, Quattro Pro, etc.)
- Comprehensive DSL Format Data file (.DAT suffix):
 - Logs ALL sensor and processed data as ASCII text, time stamped to 0.001 second. 1-60 MB/Hour. Compresses 10:1. Requires AWK/GREP and MATLAB to process. Supports renavigation capability. Data format are documented.
- Screen Shot JPEG File (.JPEG suffix):
 - Time stamped (to the second) screen shot image of the navigation screen. 500 KB/Image.
 Created when you press the "screenshot" button.
- Navigation Configuration and Initialization Files:
 - Initialization and Configuration files for Long-Baseline Navigation, Doppler Navigation, Transponders, Targets, etc.









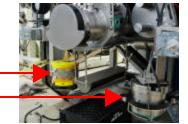
What's New in 2004

 Doppler Post Processing and Renavigation: Post-Processing and renavigation capability implemented for Dvlnav navigation program on Jason 2 /Alvin/DSL120 (Whitcomb, Kinsey).



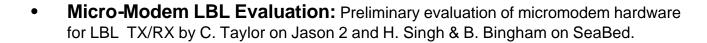
• **High-Altitude Doppler Navigation:** 300KHZ Bottom-Lock Doppler on Jason for high-altitude Doppler navigation and control (Tivey MAR cruise).

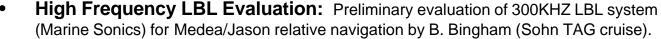
FREQ	MAX RANGE	UPDATE	VELOCITY ACCURACY
300khz	175m	1-4Hz	0.4% +/- 0.2 cm/sec
1200khz	28m	5-10Hz	0.2% +/- 0.2 cm/sec

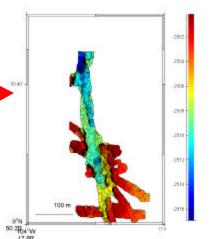


- **ADCP Profiling:** Downward Doppler current profiling on Jason 2 (Sohn TAG cruise).
- Scanning Sonar Bathymetric Processing: Developed Matlab package for postprocessing Alvin Navigation and Imagenex data to produce bathymetric maps (Howland, Yoerger, Kinsey, Whitcomb).

Vicki Ferrini has taken the lead on improving this process (Schouten EPR cruise).







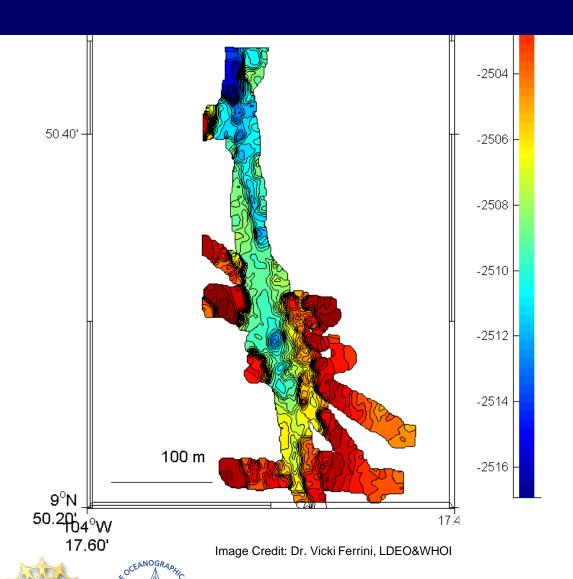








What's New in 2004



Composite Bathymetric Map of the EPR Bio-9 Area (9 50'N, 104 17.5'W).

Created from 7 Alvin dives by Dr. Vicki Ferrini (LDEO & WHOI). This map shows fissures within the axis, and vent structures along the eastern edge of the axis.

Four dives (3961, 3969, 3973, 3976) were conducted during Atlantis Leg AT-11-07, 28 Jan - 24 Feb 2004, Hans Schouten Chief Scientist.

Three dives (4000, 4008, 4011) were conducted during Atlantis Leg AT 11-09, 15 Mar - 1 Apr 2004, Karen Von Damm Chief Scientist.





What's Next

- **Inertial Navigation:** Objective is to provide 100% navigation coverage on-bottom and mid-water.
 - Alvin inertial navigation (INS) purchase is funded. ROVs should follow suit.
 - Presently evaluating IXSEA and Kearfott candidate units.
 - Expand Dvlnav to support inertial navigation.
 - Install and test on NDSF Vehicles on engineering dives.

Long-Baseline Acoustic Navigation (LBL) Improvements:

- Existing NDSF LBL hardware and software dating from 1970's is becoming unsupportable.
- Feasibility of modem-based LBL navigation demonstrated in 2004.
- Next step is to develop standard modem-based hardware and software for use on: Jason 2 / Medea, DSL120A,
 Alvin in-hull and Atlantis top-lab, and for navigated instruments: coring, dredging, tow-cam, etc.
- 300 KHZ LBL for Jason2 / Medea relative navigation for improved LBL coverage and dynamic positioning.

Synchronized LBL Networks to Support Multiple Vehicle:

- NSF supported project (Yoerger, Bradley).
 - Enable multiple vehicle LBL navigation in a single LBL net.
 - Preserve existing update rate and accuracy.
 - Compatible with existing Benthos LBL transponders.

Combined Acoustic Navigation and Communication with Acoustic Modems:

- NSF Supported ITR project (Singh, Yoerger, Whitcomb, Freitag, et. al.) Goal is combined navigation/communication modem network in two years.
- Real-Time 3-D Visualization of Navigation and Scientific Data:
 - Prototype system developed by a collaboration of UNH CCOM/JHC (Ware) and JHU (Whitcomb).











R/V Atlantis Maintenance Plans Improvements

December 2004 – January 2005 in San Diego NDSF Operator's Report

- Installation of High Seas Net antenna and begin test period of system
- Begin first phase of Lab HVAC System upgrade with installation of variable speed fan control in main lab
- Complete repairs to # 1 Generator
- Overhaul # 2 large propulsion diesel engine









Issues to be Addressed on R/V Atlantis 2005 NDSF Operator's Report

- Plan Bow Thruster overhaul for dry-dock period early 2006
- Continue with upgrades to LAB HVAC System
- Continue to modify lab drains
- Continue program to renew weather-tight doors
- Modify the radar platforms to minimize mast interference per Revelle's design







