### **RVTEC Meeting 2002**

Towed Undulating Instrument
Systems

### Systems Available in the Fleet

University of Delaware – Scanfish MKII

Oregon State University - Sea Soar

Scripps Institution of Oceanography –
 Sea Soar

## New Fleet Systems

- University of Rhode Island R/V ENDEAVOR Scanfish MKII
- University of Miami, RSMAS HBOI
   W.S. Ocean U-Tow MKII
- Moss Landing Marine Labs R/V POINT SUR TRIAXUS
- University of Minnesota R/V BLUE HERON TRIAXUS
- University of Alaska R/V HELIX TRIAXUS

## Scanfish MKII Specifications



- Length 0.80 m
- Height 0.14 m
- Width 1.60 m
- Weight 50kg
- Depth Range 0 to 400 m
- Towing Speed 2 to 10 kn
- Vertical Speed 0.1 to 1.0 m/s

# Sea Soar Specifications



- Length 1.5 m
- Height 0.98 m
- Width 1.6 m
- Weight 150 kg
- Depth Range 0 to 500 m
- Towing Speed 6.5 to 12 kn
- Vertical Speed 1 to 3 m/s

#### W.S. U-Tow MK II



- Length 1.2 m
- Height 0.23 m
- Width 0.84 m
- Weight 100 kg
- Depth Range 50 to 120m
- Towing Speed 4 to 20 km
- Vertical Speed 1 m/sec

### TRIAXUS Specifications



- Length 1.6 m
- Height 1.2 m
- Width 1.2 m
- Weight 160 kg
- Depth Range 1 to 400m
- Towing Speed 1 to 10 kn
- Vertical Speed ?

### **Breaking News**

- Chelsea will be manufacturing Scanfish MKII. Plans for a larger fish with more sensor payload available are in the idea stage.
- EIVA has bought out GMI and will be looking at writing new windows based software for the Scanfish.
- University of Miami will be testing the U-Tow with a fiber optic cable.
- First delivery of TRIAXUS due in January to Moss Landing Lab – R/V POINT SUR.

## Towed Bodies User E-mail Group

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