Jason Control Van



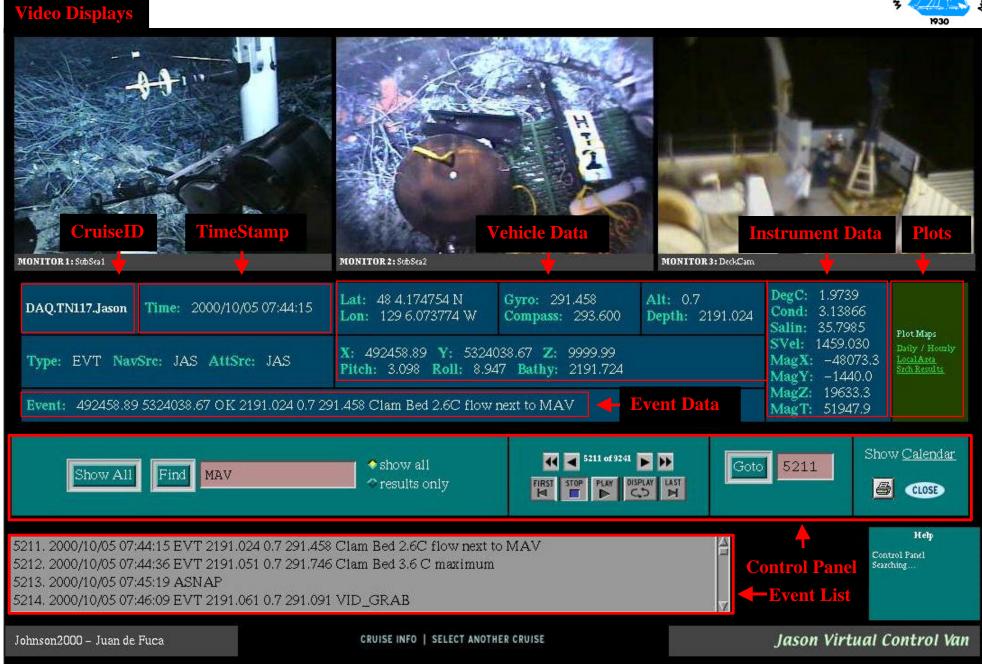
The Control Van is where Pilots, Navigators, and Engineers control remotely operated vehicles (ROV) such as Jason and Argo. Scientists use these vehicles for underwater scientific research.



There is a wealth of information available in the Control Van during ROV operations. This information includes live Video Displays, Navigation Data, Vehicle Data, Scientific Instrument Data, and Events that are entered by Scientists. All of this information is captured and index using a Master Time clock. The Virtual Van is a web-based application that takes snapshots of the information that occurs inside the Control Van during vehicle operations and makes this information available for Scientists and the Public on the web.

Virtual Jason Control Van





Virtual Van Capabilities

- Real-time Monitoring of Control Van for Scientific use and Public Outreach
- Provide On-line Integrated Cruise Synopsis
- Search Capabilities Keyword, Time, Events
- Plot Capabilities Geographic and Time series Plots
- Cruise Synopsis Repository Available On-Ship and On-Shore
- Built-in Automatic Data Acquisition System
- Support Real-Time Playback of Prior Cruise Data

Scientific Applications

- Real-time searchable data access for dive planning
- Integrated events, video snapshots, and vehicle data for rapid searching and data analysis
- Plotting capabilities for quality assurance and anomaly detection
- Easily locate specific data within data archive (eg; video clips)

Future Capabilities and Applications

- Develop Public Outreach User Interface
- Integrate with SeaNet for Live Remote Access
- Enhance Virtual Van Prototype
 - o Support for Video and Audio clips
 - Additional plotting capabilities
 - o Algorithm development, data mining, etc.
- Integrate with other vehicles such as AUVs, Alvin, etc.

