

	<u>EVENT</u>	<u>TS SHORT</u>	<u>TS LONG</u>	<u>GLOBAL</u>	<u>EXPEDITIONARY</u>
VEHICLES	<p>Existing 4500m sub</p> <p>AUVs with limited manipulation (maybe simple releasable tools)</p> <p>ROVs: dexterity (fine-scale and delicate samples)</p> <p>“smart” rocks</p>	<p>Existing 4500m sub</p> <p>Deep 6500+ sub</p>	<p>Existing 4500m sub</p> <p>Generic vehicles</p> <p>Observatories Robust ROV (heavy lift, long bottom time)</p> <p>Generic interfaces (so can use various vehicles for same task.)</p> <p>Dedicated AUVs (docked) Flexibility (can download at various data rates)</p> <p>Take up power and interact with control system/vehicles.</p>	<p>Existing 4500m sub</p> <p>Vehicles that match to tasks</p> <p>Both water column and seafloor vehicles</p> <ul style="list-style-type: none"> - benthic crawlers - AUVs in water column - 6000+m capability - 2000m efficiency - wide range time and distance - exploratory (cheap, small, simple) - specialized - 	<p>Existing 4500m sub</p> <p>ROVs with intermediate resolution mapping capability</p> <p>More portable ROVs and tow sleds</p> <p>AUVs:</p> <ul style="list-style-type: none"> - long range (gliders, solar power) - Air dropped (new nav) - Multiple - AUVs with sampling - With fiber or acoustic tether - More intelligent - Expendable <p>Portable observatories</p>
IMAGING	<p>High res</p>	<ul style="list-style-type: none"> - High definition digital video and telemetry - Elect. Digital still cams - red light ops 		<p>High definition video and photog</p>	
MANIPULATORS	<ul style="list-style-type: none"> - Delicate sampling insitu experiments - Programmable 	<ul style="list-style-type: none"> - More precise control for delicate work - Programmable 	<p>Generic manipulators Dexterity</p>	<p>Improved</p>	

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PAYLOAD	Versatility				
SENSORS	<ul style="list-style-type: none"> - Insitu: optical, chem, gradients, hi temp, heat flow, long term non degradable (H2, pH,EH metals, sulfides, DNA) - survey compatibilities - bathy, grav mag, backscatter, subbottom, CTD-optical, photomasaics 	<ul style="list-style-type: none"> - chemical and physical (may need 2+ yr grants) - porewater flow - smooth var spd pan and tilt - computer controlled sed profilers - gas-type manifold for water column sampling 	-minimum suites of sensors (so all are similar?)	<ul style="list-style-type: none"> - presure,temp, grav mag, lights, multi spectral (low freq radiation) - current and flow - chem (both long range and detailed site specific) - acoustic and optical - insitu xray 	<ul style="list-style-type: none"> - molecular and biochem probes and sensors - insitu mass spec
SAMPLERS	<ul style="list-style-type: none"> - Softside and sand/rock coring - sample preservations - fauna/larvae (slurp pump) fluid samplers(small to large volume) 	<ul style="list-style-type: none"> - standardized tools (shareable) - coring improvement (vibracorer?) - drilling capability (subs and rigs) - standardized shareable tools 	generic tools	<ul style="list-style-type: none"> - cores, seds - drills, rocks, etc - water (sml vol/multiple) - geol samples - biology - avoid cross-contain - preserve insitu contam - multiple chamber suction collectors - "enclosure" for delicate 	

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NAVIGATION	Meter or better Simultaneous vehicles Self-contained for AUVs			Short baseline for some may be better option	Improvement
DATA	Storage			Better communication or data transfer	More rigorous data sets
POWER	Advance battery technology				
OTHER			Benchmarks needed	- environ extremes - tech training and infrastructure	