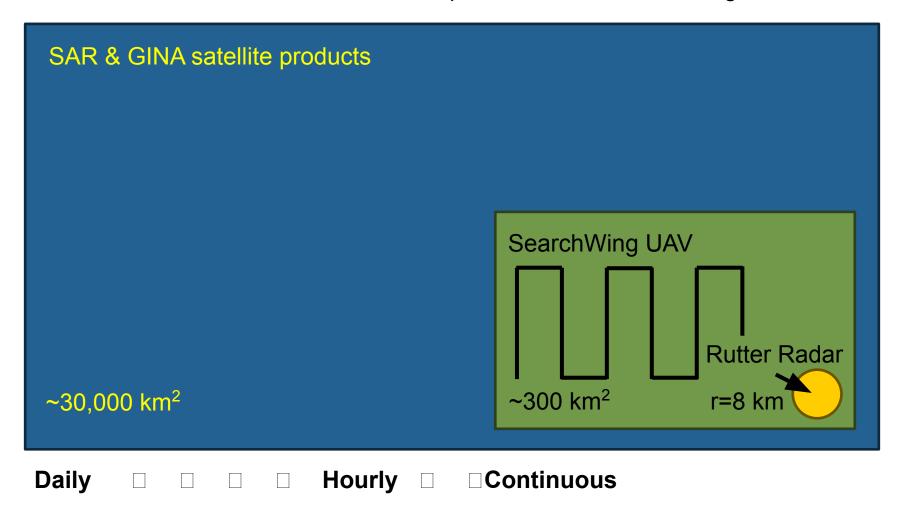
# Viability of using fixed-wing drones for remote sensing during polar operations



### Remote Sensing

Situational Awareness & Operational Decision Making

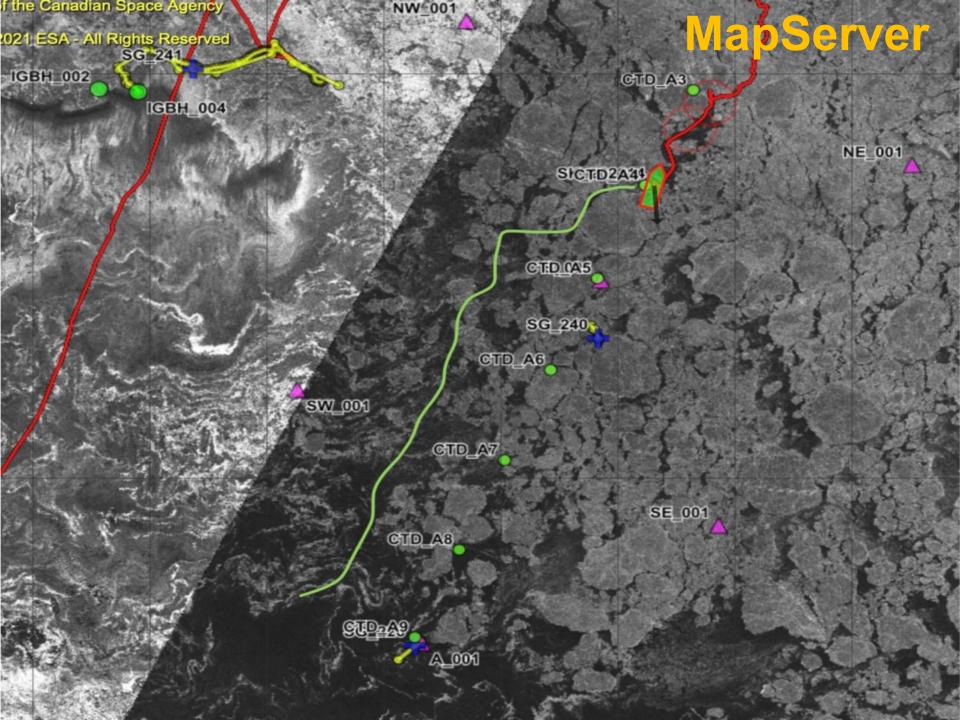








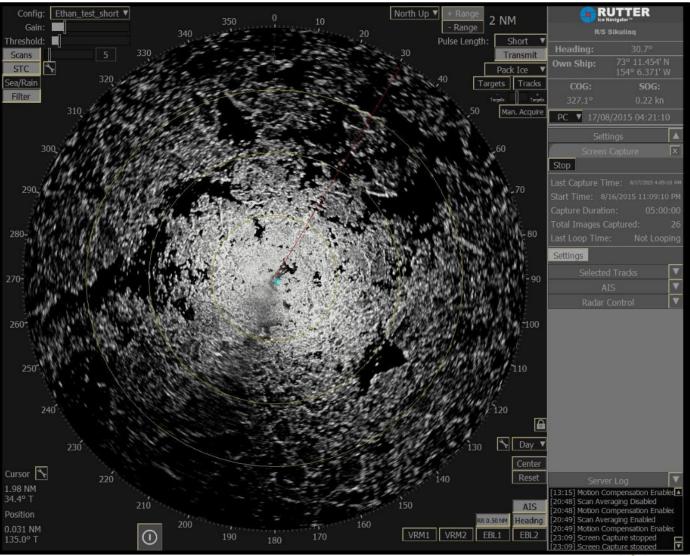




#### Rutter X-band Radar

Ice Navigator and Wave Monitoring System (WaMoS)

- GeoTIFF output
- Wave spectra
- MapServer overlay
- Surface Currents & Sea Ice Drift Maps (U of Miami CSTARS)



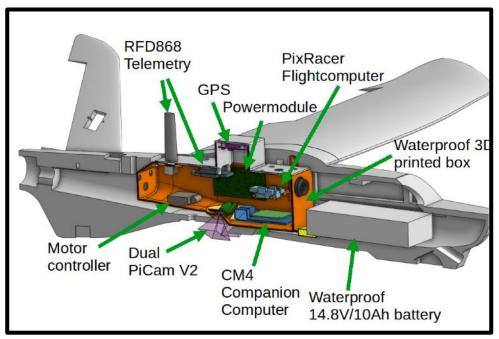








# SearchWing UAV



- Range: 80 120 km
- Flight time: 1 1.5 hours
- Max. area covered: 160 240 km<sup>2</sup>
- Image resolution: ~ 20 cm / pixel at 550 meters altitude

- IP67 (waterproof)
- Telemetry range: 25 km
- Wind resistance: 20-25 knots

#### Sensors:

- Visible light cameras
- GPS
- □ Barometer
- ☐ IMU / Gyrometer
- Internal humidity











## What's needed to operate

- Drone vehicle with sensor payload
- Spare drone + parts & trainer drones
- Remote controllers
- Batteries (lithium) & containment
- Part107-certified pilots
- Training for pilots
- RF antenna & ground station for telemetry
- Tablet for mission planning & programming
- PC for data download & processing
- Ceilometer for determining survey altitude





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Considerations for planning flights based on experiences in Summer 2023

Emily Shimada
OSU Marine Technician



# The Setup

Mounting the antenna and ground station



Network and telemetry checks



Pre-flight checks

Battery life limitations













# The Conditions

Ice station vs. open water

Movine ice floes

Visibility





Temperature and wind chill









# The Operators

Need trained pilots, drone launchers, and observers



Finding flight times

Consider recovery crew operations













# The Data

Post-flight downloads

Image processing and geolocation

Using data for navigation and ops











# Alaska Center for UAS Integration (ACUASI)

3 ingredients for successful ops in the future -

- Dedicated professional drone pilot
- Hybrid fixed-wing/VTOL design
- Synthetic Aperture Radar





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