R/V Falkor UAV Science



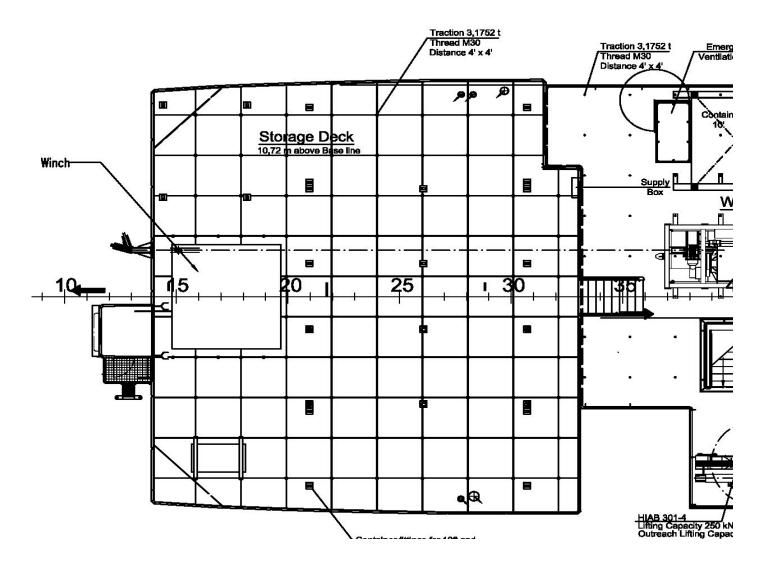
Schmidt Ocean Institute Strategic Areas of Strategic Focus

- 1. Commitment to excellence in oceanographic research operations
- 2. Infrastructure, platform and technology development for marine sciences
- 3. Collaborative scientific research aboard Falkor
- 4. Communications, education and outreach
- 5. Open sharing of information, data and research outcomes
- 6. (Supporting projects deemed high risk by other institutions and funding agencies)



SCHMIDT OCEAN INSTITUTE 2016 UAV USE

Falkor Flight Deck



HQ-60



HQ-60

IN PRODUCTION

Designed for long endurance, 12 to 24 hours, and an 8 to 12 pound payload capacity. This aircraft is intended to demonstrate the excellent endurance achievable with Hybrid Quadrator¹⁹⁶ technology

HQ-60

96 in



HQ-60B PERFORMANCE

PARAMETER	PERFORMANCE
Glide Slope	10:1
VTOL Endurance	5 minutes
Fixed Wing Endurance	15 hours
Loiter Speed	33kts
Cruise Speed	40kts
Dash Speed	60kts
Useful Load	42lbs
Payload	12lbs
Empty Weight	45lbs
Max Gross	95lbs



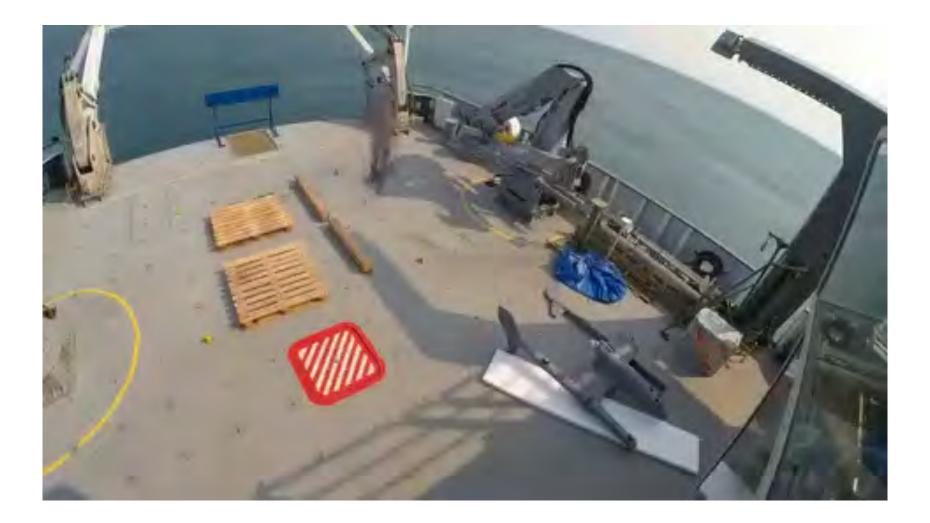


150 in [381 cm]

HQ-60 Payload



HQ-60 Assembly



HQ-60 Landing



SCHMIDT OCEAN INSTITUTE

SCHMIDT OCEAN INSTITUTE UPCOMING UAV USE

2018 UAV Cruises – Tasso

- FK180528
- Ship-bases Integrated Networked Vehicle Systems (SINVS)
 - Sampling physical, chemical and biological features
 - NetOS development and high degree of autonomy and inter-asset communication

Tasso (cont.)

- AUVs, ASVs and UAVs
 - Two types of fixed wing UAVs (six in total, 120" flight)
 - Two types of multi-copter VTOL UAVs (90" flight)
 - Two Wavegliders
 - Seven small (one person portable) AUVs
 - One larger AUV
 - Aerially deployed Drifters

Tasso (cont.) UAVs





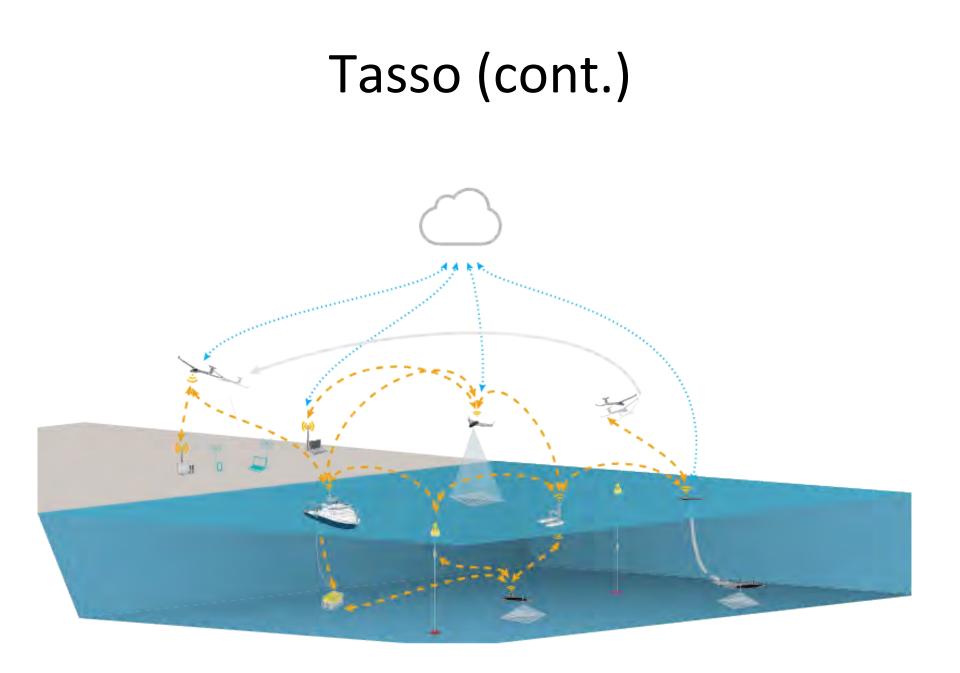
Based on the X8 RC model airframe <u>http://www.lsts.pt/vehicles/x8</u> fully integrated with the LSTS software toolchain http://www.lsts.pt/toolchain

Wingspan	212 cm
Length	60 cm
Weight	Starting at 1.5 up to 3.5 Kg
Endurance	Up to 60 min
Maximum Altitude	600 m
Wind tolerance	Mean 14 Kts Max 18 Kts
Camera	HD 720p on-board recording and streaming / IR
Communication	Wi-Fi 2.4Ghz

Cruiser Mini



- 18 m/s cruise speed
- 9 kg MTOW
- Catapult launch
- Belly or net landing
- Electric, 1-2 hr endurance
- Flexible payload bay
- 1-2 kg payload capacity
- Flexible avionics and payload system integration with ArduPilot open source autopilot and mission planning SW
- Telemetry on 433 MHz or 5.8 GHz radio
- BLOS >20km



2019 UAV Cruise Proposals

- 2019 proposals are still in the evaluation stage
- Two proposals in review requesting UAV use

2019 UAV Proposed Project #1

- Project 1:
 - Instrumentation requirements similar in scope to 2016 UAV cruise
 - Mission scope similar to 2016 project
 - Would strongly consider using Latitude HQ-60B again

2019 UAV Proposed Project #2

- Project 2:
 - Use of two small VTOL UAVs to detect derelict fishing gear

Schmidt Ocean Institute – The Future

- Continuing to expand upon areas of strategic focus (5-10 year time frame)
 - Technology development for researching marine science
 - Interest in exploring the transition from ship based research to information gathering using autonomous vehicles
 - UAVs may play an important role in data movement and atmospheric and sea surface and data collection